



Allen-Bradley

***1336 IMPACT™
Adjustable Frequency
AC Drive
(Series A)***

*A020 – A030
B040 – B050
BX040, BX060
C025 – C060*

Troubleshooting Guide



Important User Information

Because of the variety of uses for the products described in this publication, those responsible for the application and use of this control equipment must satisfy themselves that all necessary steps have been taken to assure that each application and use meets all performance and safety requirements, including any applicable laws, regulations, codes and standards.

The illustrations, charts, sample programs and layout examples shown in this guide are intended solely for purposes of example. Since there are many variables and requirements associated with any particular installation, Rockwell Automation does not assume responsibility or liability (to include intellectual property liability) for actual use based upon the examples shown in this publication.

Rockwell Automation publication SGI-1.1, *Safety Guidelines for the Application, Installation, and Maintenance of Solid-State Control* (available from your local Rockwell Automation office), describes some important differences between solid-state equipment and electromechanical devices that should be taken into consideration when applying products such as those described in this publication.

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ATTENTION: Identifies information about practices or circumstances that can lead to personal injury or death, property damage or economic loss.

Attention statements help you to:

- identify a hazard
- avoid the hazard
- recognize the consequences

Important: Identifies information that is critical for successful application and understanding of the product.



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- SUPERVISE FLOOR OPERATIONS

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Summary of Changes

The information below summarizes the changes to the company-wide templates since the last release.

Updated Information

No changes have been made to this manual.

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Preface

Manual Objective

The information in this manual is designed to help troubleshoot or repair an Allen-Bradley Bulletin 1336 IMPACT Adjustable Frequency AC Drive with ratings A020 – A030, B040, B050, BX040, BX060, and C025 – C060.

Who Should Use This Manual

This manual is intended for qualified service personnel responsible for troubleshooting and repairing the 1336 IMPACT Adjustable Frequency AC Drive. You should:

- Read this entire manual before performing maintenance or repairs to drives.
- Have previous experience with, and basic understanding of, electrical terminology, procedures, required troubleshooting equipment, equipment protection procedures and methods, and safety precautions.

This manual describes equipment, troubleshooting, and disassembly procedures. You begin with general illustrations and end with greater detail concerning replacement parts and part locations on the drives. Later chapters may refer you back to earlier chapters for information on basic equipment and steps necessary to perform detailed diagnostics and part replacement.

Safety Precautions



ATTENTION: Some printed circuit boards and drive components may contain hazardous voltage levels. Remove and lock out power before you disconnect or reconnect wires and before you remove or replace fuses and circuit boards. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Potentially fatal voltages may result from improper usage of oscilloscope and other test equipment. The oscilloscope chassis may be at a potentially fatal voltage if not properly grounded. If an oscilloscope is used to measure high voltage waveforms, use only a dual channel oscilloscope in the differential mode with X 100 probes. It is recommended that the oscilloscope be used in the A minus B Quasi-differential mode with the oscilloscope chassis correctly grounded to an earth ground.



ATTENTION: Only personnel familiar with the 1336 IMPACT Adjustable Frequency AC Drive and associated machinery should plan or implement the installation, start-up and subsequent maintenance of the system. Failure to comply may result in personal injury and/or equipment damage.

Electrostatic Discharge Precautions



ATTENTION: This assembly contains parts and sub-assemblies that are sensitive to electrostatic discharge. Static control precautions are required when servicing this assembly. Component damage may result if you ignore electrostatic discharge control procedures. If you are not familiar with static control procedures, reference Rockwell Automation Publication 8000-4.5.2, Guarding Against Electrostatic Damage, or any other applicable ESD protection handbook.

Electrostatic discharge generated by static electricity can damage the complementary metallic oxide semiconductor devices on various drive boards. It is recommended that you perform these procedures to guard against this type of damage when circuit boards are removed or installed:

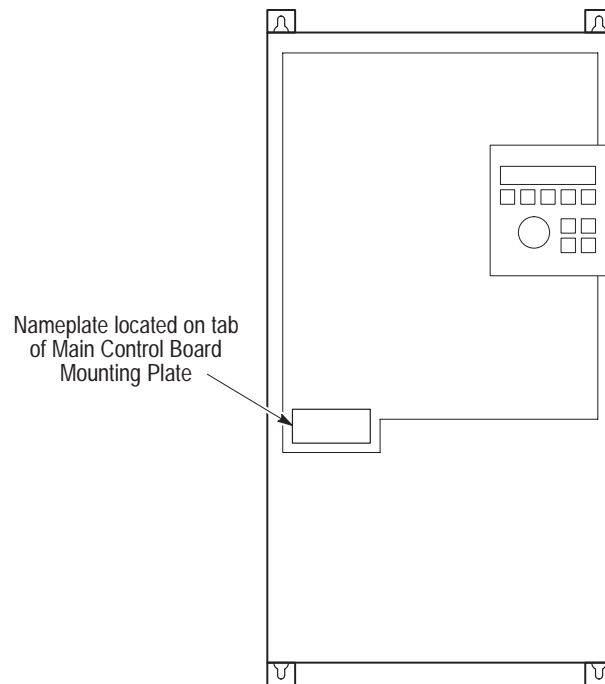
- Wear a wrist-type grounding strap that is grounded to the drive chassis.
- Attach the wrist strap before removing the new circuit board from the conductive packet.
- Remove boards from the drive and immediately insert them into their conductive packets.

1336 IMPACT Product Identification

Drive Nameplate Location

The drive nameplate is located on the face of the Main Control Board Mounting Plate. The drive nameplate contains the drive's catalog number and other important drive information. Reference the catalog number when ordering replacement parts.

Figure P.1
Drive Nameplate Location



AB0334B

Drive and Option Identification

The following is an explanation of the catalog numbering system for 1336 IMPACT Adjustable Frequency AC Drives and options. The catalog number is coded to identify the drive power rating and can be found on the drive shipping carton and nameplate.

1336 IMPACT Drive Catalog Numbers

Table P.A
200 – 240V AC Input

1336E	– A020-AN		– EN	– L6	– HA1	– GM1
Bulletin No.	Rating-Enclosure (Must Be Specified)		Language Module ¹ (Must Be Specified)	L Option ¹ (Optional)	Human Interface ¹ (Optional)	Communication Card ¹ (Optional)
Drive Rating ²			Enclosures			
			Open IP00 No Enclosure	NEMA Type 1 IP20 General Purpose	NEMA Type 4 IP65 Resist Water, Dust	NEMA Type 12 IP54 Industrial Use
Frame Designation	Output Amps	Nominal HP	Code	Code ³	Code	Code
C	64.5	20	A020-AN	A020-AA, -AE	A020-AF	A020-AJ
	78.2	25	A025-AN	A025-AA, -AE	A025-AF	A025-AJ
	80.0	30	A030-AN	A030-AA, -AE	A030-AF	A030-AJ

¹ Refer to the Language Module and Options tables following these Catalog Number tables.

² 200 – 240V AC drive rating is based on nominal voltage of 240V and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. 380 – 480VAC drive rating is based on nominal voltage of 480V and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. 500 – 600V AC drive rating is based on nominal voltage of 600v and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. Refer to Drive Rating Qualifications on page P-9.

³ Refer to Table P.I for explanation of "E" rating.

Table P.B
380 – 480V AC Input

1336E	– B040-AN		– EN	– L6	– HA1	– GM1
Bulletin No.	Rating-Enclosure (Must Be Specified)		Language Module ^[1] (Must Be Specified)	L Option ^[1] (Optional)	Human Interface ^[1] (Optional)	Communication Card ^[1] (Optional)
Drive Rating ^[2]			Enclosures			
			Open IP00 No Enclosure	NEMA Type 1 IP20 General Purpose	NEMA Type 4 IP56 Resist Water, Dust	NEMA Type 12 IP54 Industrial Use
Frame Designation	Output Amps	Nominal HP	Code	Code ^[3]	Code	Code
C	58.7	40	BX040-AN	BX040-AA, -AE	BX040-AF	BX040-AJ
	64.5	40	B040-AN	B040-AA, -AE	B040-AF	B040-AJ
	78.2	50	B050-AN	B050-AA, -AE	B050-AF	B050-AJ
	78.2	60	BX060-AN	BX060-AA, -AE	BX060-AF	BX060-AJ

^[1] Refer to the Language Module and Options tables following these Catalog Number tables.

^[2] 200 – 240V AC drive rating is based on nominal voltage of 240V and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. 380 – 480VAC drive rating is based on nominal voltage of 480V and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. 500 – 600V AC drive rating is based on nominal voltage of 600v and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. Refer to Drive Rating Qualifications on page P-9.

^[3] Refer to Table P.I for explanation of "E" rating.

Table P.C
500 – 600V AC Input

1336E	– C025-AN		– EN	– L6	– HA1	– GM1
Bulletin No.	Rating Enclosure (Must Be Specified)		Language Module ¹ (Must Be Specified)	L Option ¹ (Optional)	Human Interface ¹ (Optional)	Communication Card ¹ (Optional)
Drive Rating ²			Enclosures			
			Open IP00 No Enclosure	NEMA Type 1 IP20 General Purpose	NEMA Type 4 IP56 Resist Water, Dust	NEMA Type 12 IP54 Industrial Use
Frame Designation	Output Amps	Nominal HP	Code	Code	Code	Code
C	30.0	25	C025-AN	C025-AA	C025-AF	C025-AJ
	34.6	30	C030-AN	C030-AA	C030-AF	C030-AJ
	45.1	40	C040-AN	C040-AA	C040-AF	C040-AJ
	57.2	50	C050-AN	C050-AA	C050-AF	C050-AJ
	61.6	60	C060-AN	C060-AA	C060-AF	C060-AJ

¹ Refer to the Language Module and Options tables following these Catalog Number tables.

² 200 – 240V AC drive rating is based on nominal voltage of 240V and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. 380 – 480VAC drive rating is based on nominal voltage of 480V and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. 500 – 600V AC drive rating is based on nominal voltage of 600v and carrier frequency of 4kHz (60HP/45kW and below) or 2kHz (75HP/55kW and above) at altitudes of 1,000 meters or less. Refer to Drive Rating Qualifications on page P-9.

Table P.D
Language Modules

Description	Option Code
English/English	EN
English/French [†]	FR
English/German [†]	DE
English/Italian [†]	IT
English/Japanese [†]	JP
English/Spanish [†]	ES

[†] Not available at time of printing.

Table P.E
Options

Code	Description [†]	Code	Description [†]
Human Interface Modules, NEMA Type 1 (IP20)		Communication Options	
HAB	Blank – No Functionality	GM1	Single Point Remote I/O
HAP	Programmer Only	GM2	RS-232/422/485, DF1, & DH485 Protocol
HA1	Programmer/Controller with Analog Pot	GM5	DeviceNet™
HA2	Programmer/Controller with Digital Pot		
Human Interface Modules, NEMA Type 4/12 (IP65/54)		L Option Boards	
HJP	Programmer Only	L4	Contact Closure
HJ2	Programmer/Controller with Digital Pot	L7E	Contact Closure & Encoder Feedback
		L5	+24V AC/DC
		L8E	+24V AC/DC & Encoder Feedback
		L6	115V AC
		L9E	115V AC & Encoder Feedback

[†] For a more functionally complete description of each option, refer to Publication 1336 IMPACT-1.0.

Table P.F
200 – 240V Drives¹

Catalog Number	Maximum Amp Rating ²	Derate Curve ^{1 3}	Heat Dissipation Drive Watts ^{3 4}	Heat Sink Watts	Total Watts
A020	65	⁵	210	933	1143
A025	78	⁵	215	1110	1325
A030	80	None	220	1110	1330

Table P.G
380 – 480V Drives¹

Catalog Number	Maximum Amp Rating ²	Derate Curve ^{1 3}	Heat Dissipation Drive Watts ^{3 4}	Heat Sink Watts	Total Watts
B040	65	⁵	175	933	1108
B050	78	⁵	193	1110	1303
BX040	59	⁵	175	933	1108
BX060	78	⁵	193	1110	1303

Table P.H
500 – 600V Drives¹

Catalog Number	Maximum Amp Rating ²	Derate Curve ^{1 3}	Heat Dissipation Drive Watts ^{3 4}	Heat Sink Watts	Total Watts
C025	30	None	141	492	633
C030	35	None	141	526	667
C040	45	None	175	678	853
C050	57	None	193	899	1092
C060	62	None	193	981	1174

¹ Amp Rating is at 4kHz. If carrier frequencies above 4kHz are selected, drive Amp Rating must be derated.

² Drive Rating is based on nominal voltage (240, 480, or 600V). If input voltage exceeds Drive Rating, Drive Output must be derated.

³ Drive Ambient Temperature Rating is 40°C. If ambient exceeds 40°C, the drive must be derated.

⁴ Drive Rating is based on altitudes of 1,000m (3,000 ft) or less. If installed at higher altitude, drive must be derated.

⁵ Refer to the 1336 IMPACT User Manual.

Drive Rating Qualifications

Several factors can affect drive rating. If more than one factor exists, derating percentages must be multiplied. For example, if a 14-amp drive is installed at a 2km (6,600 ft.) altitude and has a 2% high-input line voltage, the actual amp rating is: $14 \times 94\%$ altitude derating $\times 96\%$ high-input line derating = 12.6 amps

Enclosure Type

The first character, A, indicates the Enclosure Code.

The second character indicates the type of enclosure shipped from the factory:

Table P.1
Enclosure Type Code Description

Enclosure Type Code	Description
N	Open style (IP00)
A	NEMA Type 1 (IP20)
E	NEMA Type 1 (IP20) "CE" Metal Cover
F	NEMA Type 4 (IP65)
J	NEMA Type 12 (IP54)

Conventions

To help differentiate parameter names and display text from other text in this manual, the following conventions will be used:

- Parameter Names will appear in *italics*.
- Display Text will appear in “quotes”.

The following is a list of conventions used throughout this manual, and definitions of the conventions. For a list of terminology and definitions, refer to the Glossary in the back of this manual.

Auxiliary Interlock

The Auxiliary Interlock is a user supplied circuit consisting of reset, overload, or other interlocking circuitry. The Interlock is wired to the drive Not External Fault Input.

Bit

A bit is a single character or status point used in programmable logic. Eight bits form a BYTE, 16 bits form a word. Drive parameters are actually eight bits or 16 bit words.

Check

To check means to examine either the physical condition of something or the setting of some control, such as a Parameter. Checking a drive board or component may also require measurements and tests.

Connector

A connector connects one drive board to another. Connectors come in two designs, male and female. Male connectors are stationary and contain pins, which are sometimes joined by jumpers. Female connectors are at the ends of wires or ribbon cables and plug into male connectors.

Default

When a drive function defaults, it automatically changes to a pre-programmed setting.

Enable Input

The Enable Input is a terminal connection on the L Option Board. This connection provides an external input to enable or disable the Drive Output section. It must be true to permit the drive to operate.

False

False refers to a logical false state. For instance, an L Option signal on TB3 is false when the input contact is open or the appropriate voltage is not applied to the L Option Board.

Jumper

A jumper completes a circuit between two pins within a male connector on a drive board. In the absence of certain optional equipment using female connectors, jumpers are applied to certain pins within a male connector to complete specific and necessary circuits.

L Option Board

An L Option Board plugs into connectors J7 and J9, located on the lower portion of the Main Control Board. This board is identified as L4, L5, L6, L7E, L8E, and L9E and provides optional control wiring configurations for a drive.

Not External Fault Input

The Not External Fault Input is a terminal connection on the L Option Board. This connection provides an external input for use as an Auxiliary Interlock. Unless this interlock is closed, the drive will be faulted with an External Fault.

Parameter

Parameters are programmable drive functions that define various operating functions or status displays of a drive. Refer to Bulletin 1336 IMPACT Adjustable Frequency AC Drive User Manual for parameter details.

Press

Press a button on the Human Interface Module to change parameter settings and drive functions.

True

True refers to a logical true state. For instance, an L Option signal on TB3 is true when: L4 contact input is closed, L5 input terminal registers 24V, or L6 input terminal registers 115V AC.

Related Publications

The following lists other Allen-Bradley publications that apply to the 1336 IMPACT Adjustable Frequency AC Drives with ratings A020 – A030, B040, B050, BX040, BX060, and C025 – C060:

- Product Pricing Bulletin (1336 IMPACT-3.0)
- User Manual (1336 IMPACT-5.0)
- Renewal Parts List^[1]
- Options Manuals/Instructions
- Product Data DriveTools Software (9303-2.0)
- User Manual Bulletin 1201 Graphic Programming Terminal (1201-5.0)

^[1] Current 1336 IMPACT spare parts information, including recommended parts, catalog numbers, and pricing, can be obtained from the following sources.

- Allen-Bradley home page on the World Wide Web at:

<http://www.ab.com>

Select **Drives**, and the select **Information for Drives, Including Part Lists** . . . Select documents **1060.pdf** (230V drives) and/or **1070.pdf** (460 & 575V drives).

- Standard Drives "AutoFax" service—an automated system that you can call to request a "faxed" copy of the spare parts information (or other technical documentation).

Simply call **444-646-6701** and follow the phone prompts to request document(s) **1060** (230V drives) and/or **1070** (460 & 575V drives).

Control Logic Wiring and Adapters

Chapter Objectives

This chapter introduces you to terminal block locations and wiring and adapter locations and functions.

Chapter Overview

This chapter illustrates and describes:

- L Option boards L4, L5, L6, L7E, L8E, and L9E including terminal block TB3.
- TB3 L Option mode selections and functions
- TB3 terminal designations

Important: All printed circuit boards, except the Main Control Board assembly, are referenced to negative ground (–bus).

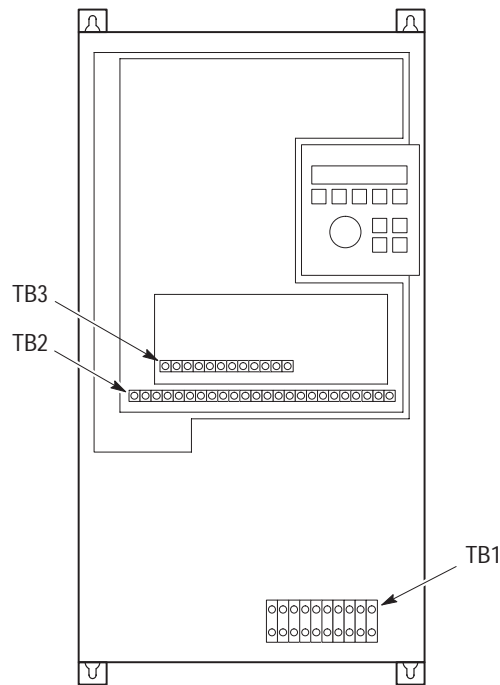


ATTENTION: Some printed circuit boards and drive components may contain hazardous voltage levels. Remove power before you disconnect or reconnect wires and before you remove or replace fuses and circuit boards. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: This assembly contains parts and sub-assemblies that are sensitive to electrostatic discharge. Static control precautions are required when servicing this assembly. Component damage may result if you ignore electrostatic discharge control procedures. If you are not familiar with static control procedures, reference Rockwell Automation Publication 8000-4.5.2, Guarding Against Electrostatic Discharge, or any other applicable ESD protection handbook.

Figure 1.1
Terminal Block Locations



AB0335A



ATTENTION: The National Electrical Code (NEC) and local codes outline provisions for safely installing electrical equipment. Installation must comply with specifications regarding wire types, conductor sizes, branch circuit protection and disconnect devices. Failure to do so may result in personal injury and/or equipment damage.

L Option Board

The L Option Board provides a means of interfacing various signals and commands to the 1336 IMPACT by using contact closures.

Six different versions of the L Option are available:

- L4 Contact Closure Interface¹
- L7E Contact Closure Interface with Encoder Feedback¹
- L5 +24V AC/DC Interface
- L8E +24V AC/DC Interface with Encoder Feedback
- L6 115V AC Interface
- L9E 115V AC Interface with Encoder Feedback

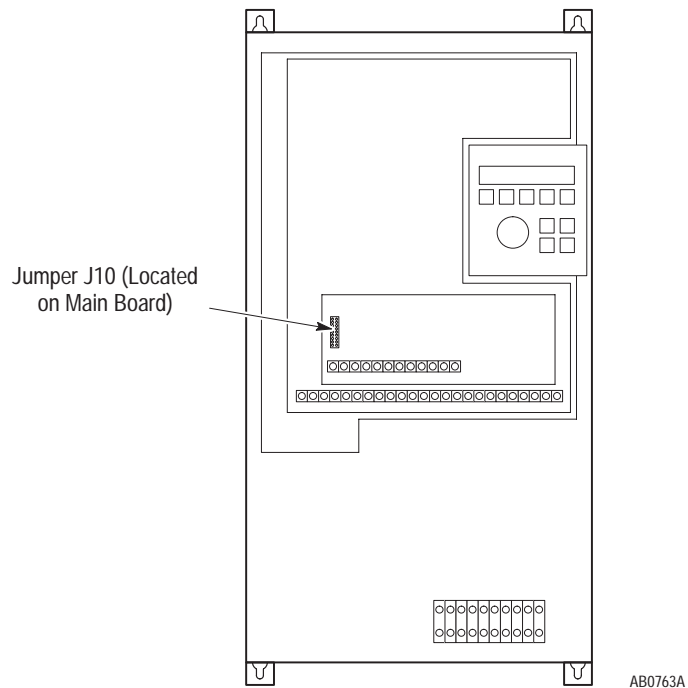
¹ Uses internal +5V DC supply.

The user inputs are connected to the L Option Board through TB3. The L4, L5, and L6 options each have nine inputs: seven user-configurable inputs and two factory-defined control inputs. The function of each L Option must be selected through programming as explained later in this section. The L7E, L8E, and L9E options are similar to L4, L5, and L6 with the addition of encoder feedback L Options.

L Option Board Jumpers

Important: If the L Option Board is being installed, Main Control Board jumpers at pins 3 & 4 and 17 & 18 of J2 (J7 on 7.5 – 30 HP drives) must be removed. If these jumpers are removed, they can be stored on the “spaces” location on the Main Control Board. If this board is removed, these jumpers must be reinstalled and the *L Option Mode* parameter must be programmed to “1”.

Figure 1.2
Jumper Locations



Available Inputs

A variety of combinations made up of the following L Options are available.

Accel/Decel Rate	Process Trim
Digital Potentiometer (MOP)	Ramp
Enable	Reset
Flux Enable	Run Forward
Forward/Reverse	Run Reverse
Jog	Speed Selects
Local Control	Speed Torque Selections
Not Ext Flt	Start
Not Stop, Clear Fault	Stop Mode Selects

The available combinations are shown in Figure 1.4. Programming the *L Option Mode* parameter to one of the L Option Mode numbers listed selects that combination of L Option functions.

Important: The *L Option Mode* parameter can be changed at any time; however, programming changes will not take affect until power has been cycled to the drive. When changing an L Option mode, it is important to note that the corresponding L Options to TB3 may also change.

The programming options of the L Option Board allow the user to select an L Option combination to meet the needs of a specific installation. Appropriate selection of a combination may be done by using Table 1.A. First determine the type of start/stop/direction control desired. Then select the remaining control functions available. After selecting a group of L Option Modes, use Table 1.A for specific mode selection. Record the selected mode number below.

Selected Mode Number: _____

Local Programming

For local programming and control information, refer to the 1336 IMPACT User Manual.

Table 1.A
L Option Mode Selection

Start/Stop Type	Direction Control	Communication Compatibility	Mode(s) to Use
Stop & Enable Only	None	Control must be provided by HIM or Communication Option.	1
Momentary Pushbutton (3 Wire)	Maintained Switch (Open-Forward, Closed-Reverse) Single-Source	Start/Stop – works like HIM and Communication Options. Direction Control will not work in parallel with HIM or Communication Options. User must select direction control from either HIM and Communication Options or TB3 L Option.	2 – 6, 17, 18, and 27 ^[2]
Momentary Pushbutton (3 Wire)	Momentary Pushbuttons (Forward and Reverse) Multi-Source	Start/Stop – works in parallel with HIM and Communication Options. Direction – works in parallel with HIM or Communication Options.	7 – 11, 19 – 22, and 28, 29 ^[2]
Maintained switches for combined run and direction control (2 wire, Run Forward, Run Reverse)		Start – works differently than three-wire control. ^[1] Direction – works differently than three-wire control. ^[1] Stop – always works.	12 – 16, 23 – 26, and 30 ^[2]

^[1] Refer to two-, three-wire notes in the user manual.

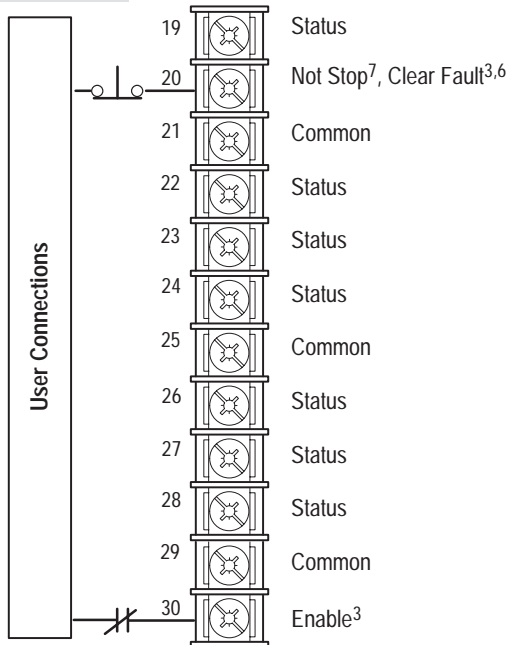
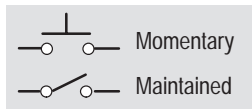
^[2] Diodes 27 – 30 are available with versions 2.02 and later.

Figure 1.3 provides the terminal designations for TB3. The maximum and minimum wire sizes accepted by TB3 is 2.1 and 0.30 mm² (14 and 22 AWG). Maximum torque for all terminals is 1.36 N-m (12 lb-in.). Use copper wire only.

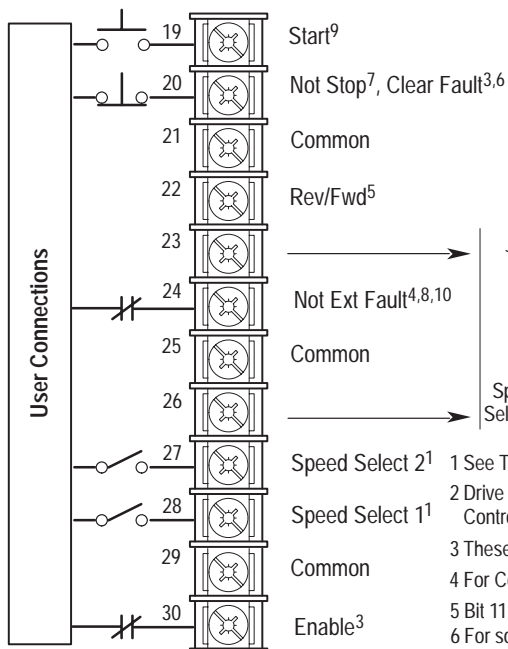
Figure 1.3
TB3 Terminal Designations



Figure 1.4
L Option Mode Selection and Typical TB3 Connections



**L Option Mode (parameter 116) = 1
Factory Default**

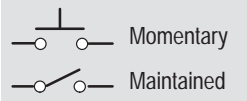


**L Option Mode (parameter 116) = 2 - 6, 17, 18, and 27
Single-Source, Three-Wire Control**

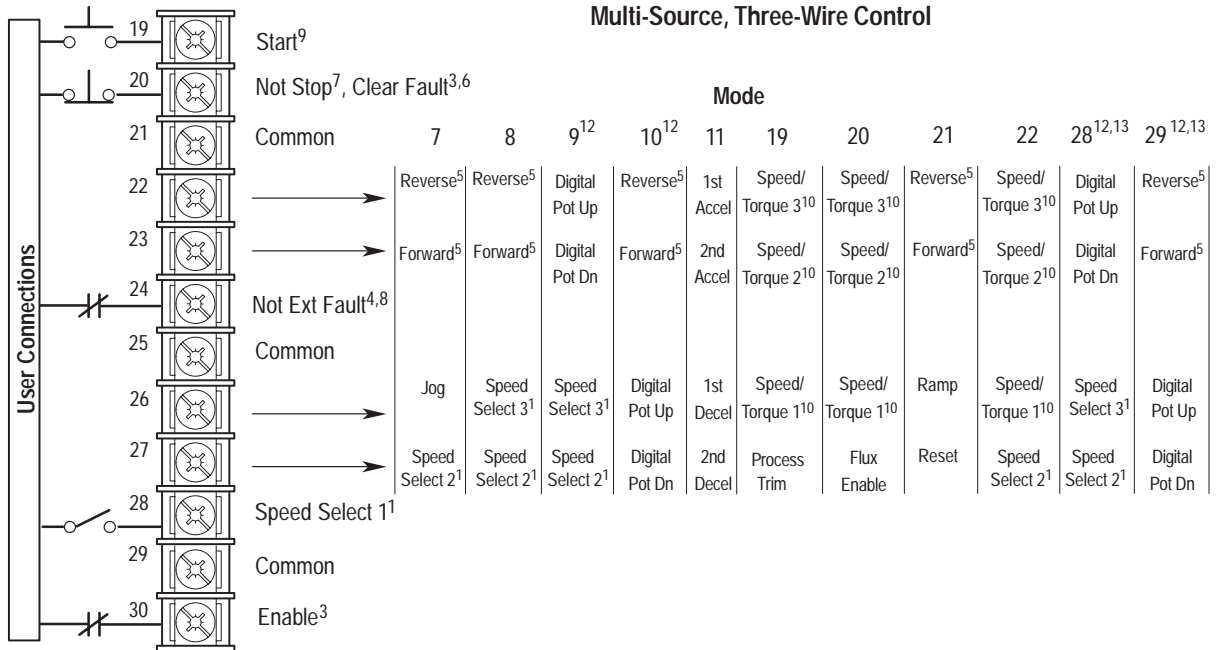
	Mode								
	2	3	4	5 ¹¹	6	17	18	27 ^{11, 12}	
Jog	Jog	Stop Type ⁷	2nd/1st Accel	Digital Pot Up	Jog	Proc Trim	Flux En	Digital Pot Up	
Speed Select 3 ¹	Speed Select 3 ¹	Speed Select 3 ¹	2nd/1st Decel	Digital Pot Dn	Local Control ²	Ramp	Reset	Digital Pot Dn	

- 1 See Table 1.B.
- 2 Drive must be stopped to take Local Control. Control by all other adapters is disabled (except Stop).
- 3 These inputs must be present before drive will start.
- 4 For Common Bus, this becomes Precharge Enable.
- 5 Bit 11 of *Logic Options* (parameter 17) must be 0 for reverse direction control.
- 6 For soft faults only. You need to recycle power to the drive or reset to clear. For hard faults, refer to the troubleshooting chapter.
- 7 To configure the stop type, refer to *Logic Options* (parameter 17).
- 8 This L Option must be present before the fault can be cleared and the drive will start. This can be disabled through *Fault Select 2* (parameter 22) and *Warning Select 2* (parameter 23).
- 9 Latched starts require a stop to stop the drive.
- 10 This input must be present or masked out before drive will start.
- 11 In mode 5, the MOP value is not reset to 0 when you stop. In mode 27, the MOP value is reset when you stop.
- 12 Available in versions 2.02 and later.

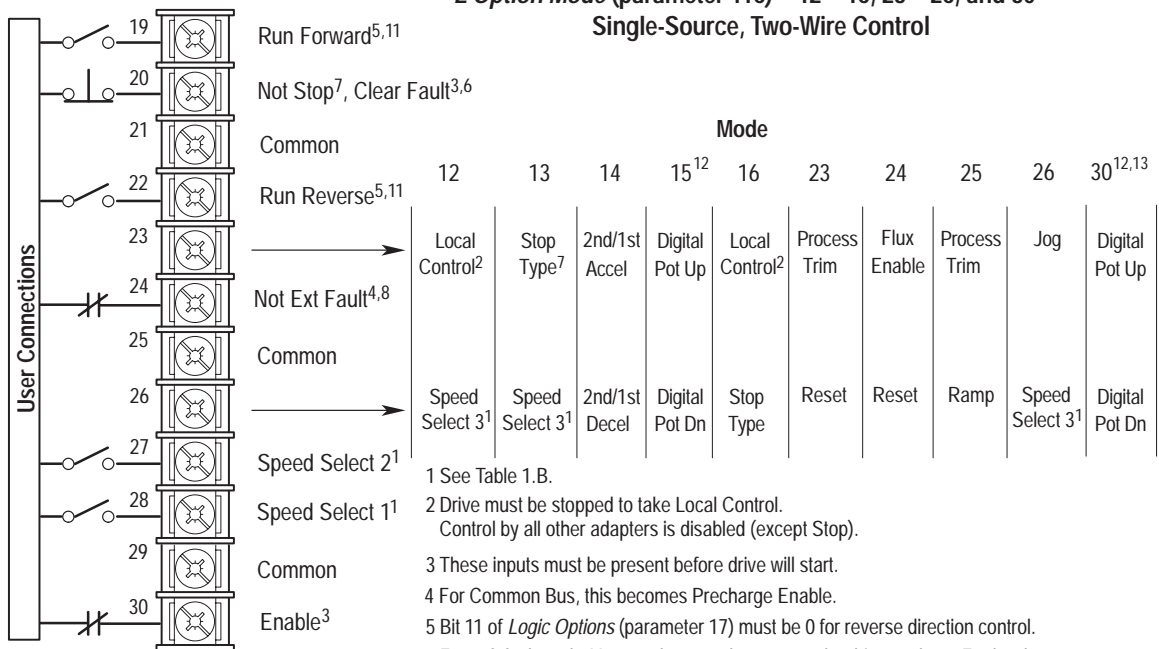
AB02908



L Option Mode (parameter 116) = 7 – 11, 19 – 22, 28, and 29
Multi-Source, Three-Wire Control



L Option Mode (parameter 116) = 12 – 16, 23 – 26, and 30
Single-Source, Two-Wire Control



- 1 See Table 1.B.
- 2 Drive must be stopped to take Local Control. Control by all other adapters is disabled (except Stop).
- 3 These inputs must be present before drive will start.
- 4 For Common Bus, this becomes Precharge Enable.
- 5 Bit 11 of *Logic Options* (parameter 17) must be 0 for reverse direction control.
- 6 For soft faults only. You need to recycle power to the drive to clear. For hard faults, refer to the troubleshooting chapter.
- 7 To configure the stop type, refer to *Logic Options* (parameter 17).
- 8 This L Option must be present before the fault can be cleared and the drive will start. This can be disabled through *Fault Select 2* (parameter 22) and *Warning Select 2* (parameter 23).
- 9 Latched starts require a stop to stop the drive.
- 10 See Speed/Torque Select table.
- 11 Unlatched start.
- 12 In modes 9, 10, and 15, the MOP value is not reset to 0 when you stop. In modes 28, 29, and 30, the MOP value is reset when you stop.
- 13 Available in versions 2.02 and later.

AB0291B

Table 1.B defines the input state of the Speed Select inputs for a desired frequency source.

Table 1.B
Speed Select/Speed Reference

Speed Select 3	Speed Select 2	Speed Select 1	Frequency Source
O	O	O	Speed Ref 1
O	O	X	Speed Ref 2
O	X	O	Speed Ref 3
O	X	X	Speed Ref 4
X	O	O	Speed Ref 5
X	O	X	Speed Ref 6
X	X	O	Speed Ref 7
X	X	X	Last State

O = Open = Removed = 0

X = Closed = Applied = 1

Table 1.C defines the input state of the Speed/Torque Mode Select inputs for a desired speed/torque mode.

Table 1.D
Speed/Torque Select

Speed/ Torque Mode Select 3	Speed/ Torque Mode Select 2	Speed/ Torque Mode Select 2	Speed/Torque Mode
O	O	O	Zero torque
O	O	X	Speed regulate
O	X	O	Torque regulate
O	X	X	Minimum torque/speed
X	O	O	Maximum torque/speed
X	O	X	Sum of the torque and speed
X	X	O	Zero torque
X	X	X	Zero torque

O = Open = Removed = 0

X = Closed = Applied = 1

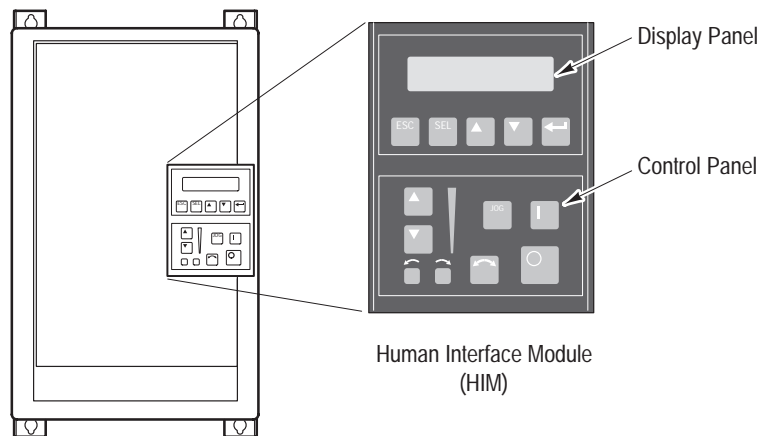
Human Interface Module (HIM)

Description

When the drive-mounted HIM is supplied, it will be connected as SCANport Adapter 1 (refer to Figure 1.6) and visible from the front of the drive. The HIM can be divided into two sections: Display Panel and Control Panel. The Display Panel provides a means of programming the drive and viewing the various operating parameters. The Control Panel allows different drive functions to be controlled. Refer to the 1336 IMPACT User Manual for HIM operation.

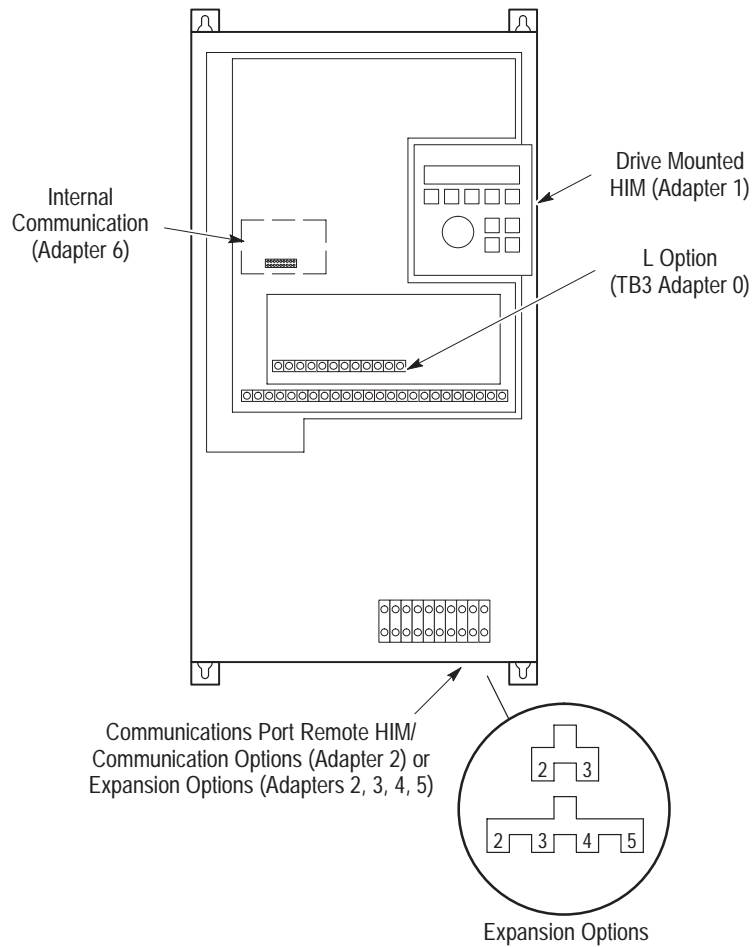
Important: The operation of HIM functions depends upon drive parameter settings. Default parameter values allow full HIM functionality.

Figure 1.5
Human Interface Module



AB0268B

Figure 1.6
Adapter Locations



AB0337B

Removing the HIM

For handheld operation, you can remove the module and place it up to 10 meters (33 feet) from the 1336 IMPACT drive. (You do need a cable to do this.)



ATTENTION: Some voltages present behind the drive front cover are at incoming line potential. To avoid an electrical shock hazard, use extreme caution when removing/replacing the HIM.

Important: Removing a HIM (or other SCANport device) from a drive while power is applied causes a Serial Fault, unless *SP Enable Mask* (parameter 124) or *Fault Select 1* (parameter 20) have been set to disable this fault or *Control Logic* (from the *Control Status* menu) has been disabled (only available on a Series A, version 3.0 or Series B HIM). Setting bit 1 of *SP Enable Mask* to 0 disables Serial Fault from a HIM on port 1. It also disables all HIM control functions except Stop. Setting bit 9 of *Fault Select 1* to 0 disables the serial fault from the HIM on port 1 but still allows HIM control.



ATTENTION: Hazard of personal injury or equipment damage exist. If you initiate a command to start motor rotation (command a start or jog) and then disconnect the programming device, the drive will not fault if you have the SCANport communications fault set to be ignored for that port.

To remove the HIM, you need to:

1. Either remove the power or clear the port bit, which corresponds to the port the HIM is attached to, in *SP Enable Mask* (parameter 124) or *Fault Select 1* (parameter 20) to prevent the drive from faulting.
2. Remove the front cover of the drive.
3. Push the release at the bottom of the HIM cradle and slide the module down out of its cradle.

To use the module from anywhere up to 10 meters (33 feet) from your drive, you need to:

1. Connect the appropriate cable between the HIM and the communications port (adapter 2, 3, 4, or 5) or adapter 1 (the HIM cradle).
2. Set *SP Enable Mask* (parameter 124) and/or *Fault Select 1* (parameter 20) to enable the port into which you plugged the HIM.

To replace the module, follow these steps:

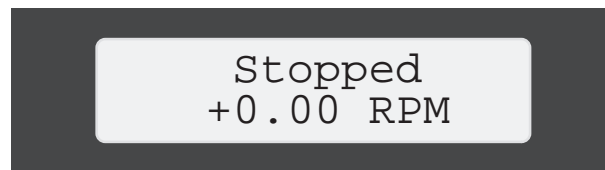
1. Slide the module up into its cradle.
2. Replace the front cover of the drive.
3. Apply power, set *SP Enable Mask* or set *Fault Select 1*.

HIM Operation

When power is first applied to the drive, the HIM will cycle through a series of displays. These displays will show drive ID and communication status. Upon completion, the Status Display (see Figure 1.7) will be shown. This display shows the current status of the drive (i.e. Stopped, Running, etc.) or any faults that may be present (Not Enabled, etc.).

Refer to the 1336 IMPACT User Manual for HIM operation.

Figure 1.7
Status Display



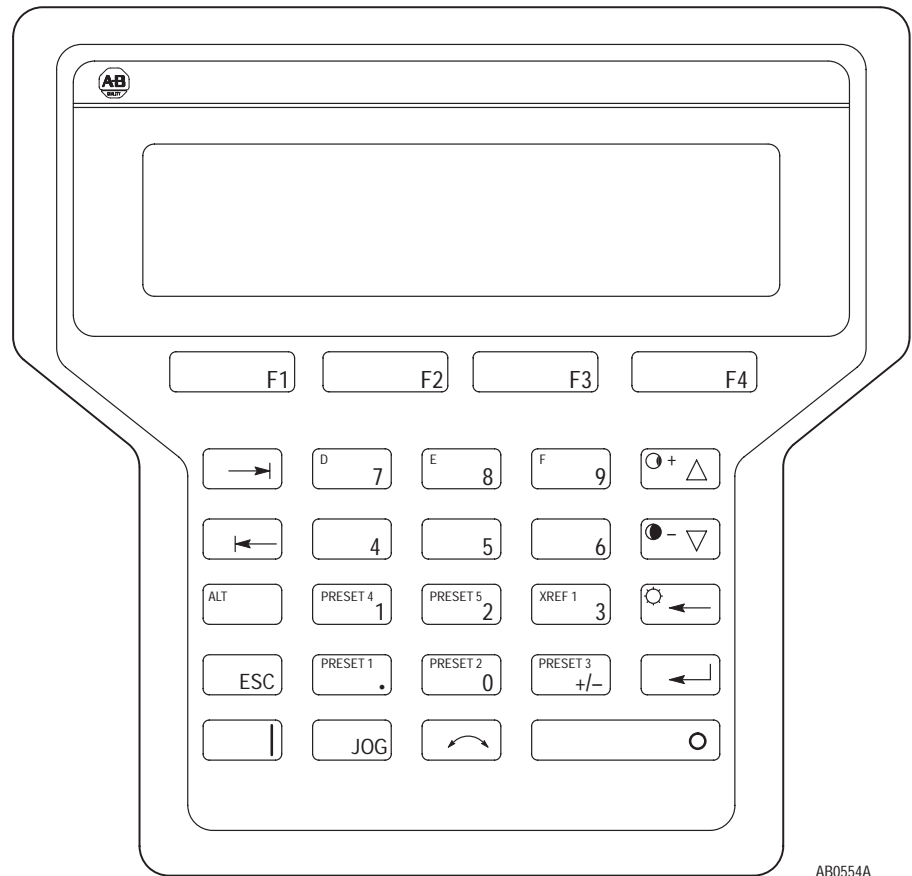
Graphic Programming Terminal

GPT Description

The optional GPT (Figure 1.8) is a remote device with a 1.8 meter (6 foot) long cable. The GPT offers a 40-by-8 character display that can also be used as a graphics display. For GPT operation, refer to the 1201 GPT User Manual.

Important: Main Menu screens are dynamic and will change based on functionality provided by adapter and drive status.

Figure 1.8
Graphic Programming Terminal



DriveTools

DriveTools software is a Windows 3.1 compatible family of application programs allowing the user to perform programming, monitoring, and diagnostic operations on Rockwell Automation AC and DC digital drive products. The software consists of five Windows applications. For operation, refer to the Product Data DriveTools Software manual.

Control Firmware Function

All control functions in the 1336 IMPACT drive are performed through the use of parameters that can be changed with a programming terminal or DriveTools. Refer to an overview Block Diagram of the Control Firmware Function in the 1336 IMPACT User Manual.

Feedback information is derived from hardware devices as part of the process equipment used. Analog signals are converted to digital signals for use by the drive. Control signals may be provided to the drive by the Main Control Board.

All setup and operation information used by the drive is stored in a system parameter table. Every parameter, including Setup and Configuration parameters (Sources and Destinations), has an entry in the parameter table. For example, parameter 29 is named the *Speed Ref 1* parameter and contains a number value representing the speed reference. The speed reference can originate from an external control device such as a potentiometer connected to the analog input of the Main Control Board. Refer to the 1336 IMPACT User Manual, Publication 1336 IMPACT-5.0.

Troubleshooting and Error Codes

Chapter Objectives

This chapter provides information to help troubleshoot your 1336 IMPACT drive.



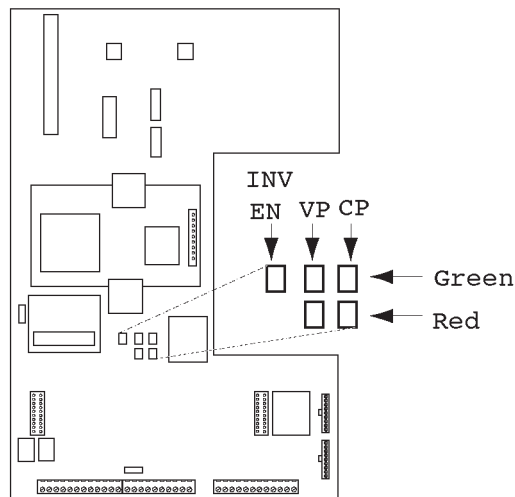
ATTENTION: Do not troubleshoot or maintain the 1336 IMPACT drive unless you are familiar with your drive system and the associated machinery. You may be injured and/or the equipment may be damaged if you do not comply.

During the start-up procedure, you should have recorded board jumper settings for each board, board software version numbers, and the drive and motor nameplate data in Table 6.A of the *1336 IMPACT™ Adjustable Frequency AC Drive User Manual*. If this information was not recorded, record it before beginning any troubleshooting sequences.

Fault/Warning Handling

When a problem occurs with your drive, check the VP and CP lights on your drive on the main control board. Figure 2.1 shows the location of the VP and CP lights.

Figure 2.1
VP and CP LED Locations



Frames B – H

The lights on the motor control board indicate the status of the velocity processor (VP) and current processor (CP):

Table 2.A

If the VP or CP LED is:	Then, for that processor:
Solid green	No fault occurred.
Flashing green	A drive warning occurred.
Flashing red	A drive soft fault occurred.
Solid red	A drive hard fault occurred.

Faults fall into three basic categories:

Table 2.B

This type of fault:	Has the following definition:	To remove this fault, you need to:
Hard	Trips the drive causing it to stop. You cannot regain control until you reset the drive.	Perform a <i>Drive Reset</i> command or cycle drive power.
Soft	Trips the drive causing it to stop.	1 Address the condition that caused the fault. 2 Perform a <i>Clear Faults</i> command.
Warning	Indicates an undesirable condition. The drive will not stop, but the condition may lead to a fault that will stop the drive.	Address the condition that caused the warning.

Faults are annunciated on the Human Interface Module (HIM) at the time they occur. Warnings are not annunciated on the HIM.

To help troubleshoot your 1336 IMPACT drive, the drive logs any faults or warnings in either the fault or warning queue. The faults and warnings that are contained in the queues are either configurable or non-configurable.

Table 2.C

This fault type:	Refers to faults that you:
Configurable	Can set up to either trip the drive or provide only a visual warning while the drive continues to operate.
Non-configurable	Cannot disable. These faults are the result of a condition that could damage the drive if allowed to persist.



You can reset the soft faults by pressing the stop button on the HIM.

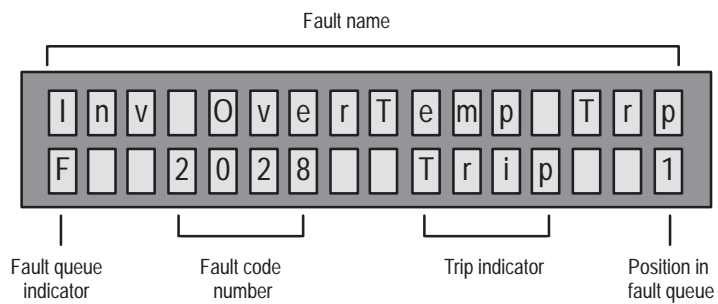
Viewing the Fault and Warning Queues on the HIM

You can use the HIM to view the fault and warning queues. To view the fault queue, you need to:

1. Press the *Escape* key until you reach the *Choose Mode* level.
2. Use the *Increment* or *Decrement* key to scroll through the *Choose Mode* options until *Control Status* is displayed.
3. Press the *Enter* key.
4. Use the *Increment* or *Decrement* key to scroll through the *Control Status* options until *Fault Queue* is displayed.
5. Press the *Enter* key.
6. Press the *Enter* key when *View Queue* is displayed.

The fault queue can contain up to 32 faults. The 1336 IMPACT drive reports the faults using the following format:

Figure 2.2

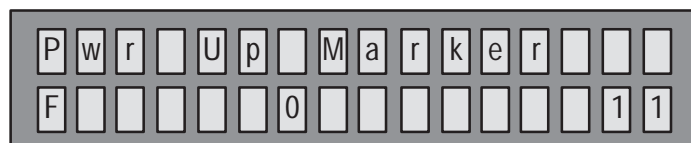


The trip indicator is only present if this fault caused the drive to trip.

The last number (1) indicates the position of this fault within the fault queue.

A marker is placed in the queue when the first fault occurs after a power up sequence. This power up marker is as shown.

Figure 2.3



The 1336 IMPACT drive tracks the time that has elapsed since power up. The drive uses this information as a time stamp so that you can tell when a fault occurred in relation to when the drive was powered up.

To clear the fault queue, select *Clear Queue* from the *Fault Queue* options.

To view the warning queue, select *Warning Queue* from the *Control Status* options. The remaining steps are the same as for the fault queue.

What Are the Fault Descriptions

When a fault occurs, the fault is displayed until you initiate a *Drive Reset* or a *Clear Faults* command. A *Drive Reset* clears all faults, while a *Clear Faults* command only clears soft and warning faults. You can perform a *Drive Reset* and *Clear Faults* either through bits in *Logic Input Sts* (parameter 14) or with a terminal.

The fault codes are defined as shown in Table 2.D.

Table 2.D
Fault Descriptions

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
01027 <i>Autotune Diag</i>	VP, Flashing red	Soft	The drive encountered a problem while running the autotune tests. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Check <i>Autotune Errors</i> (parameter 176). For additional information about <i>Autotune Errors</i> , refer to Chapter 13, <i>Understanding the Autotuning Procedure</i> , in the user manual.
01051 <i>MtrOvrlD Pnd</i>	VP, Flashing red	Soft	A motor overload is pending. The drive has reached 95% of the level required for a motor overload trip (see fault 01052).	Check for possible motor overheating. <ul style="list-style-type: none"> • If the motor temperature is excessive, reduce the accel/decel times (parameters 42 – 45) or reduce the load. • If the motor temperature is acceptable, increase the value of <i>Motor Overload %</i> (parameter 26). If you do not want this condition to be reported as a fault, change bit 3 in <i>Fault Select 2</i> (parameter 22) to 0.
01052 <i>MtrOvrlD Trp</i>	VP, Flashing red	Soft	Motor overload tripped. The drive has reached the level of accumulated motor current over time as set by <i>Motor Overload %</i> (parameter 26).	Check for possible motor overheating. <ul style="list-style-type: none"> • If the motor temperature is excessive, reduce the accel/decel times (parameters 42 – 45) or reduce the load. • If the motor temperature is acceptable, increase the value of <i>Motor Overload %</i> (parameter 26). If you do not want this condition to be reported as a fault, change bit 4 in <i>Fault Select 2</i> (parameter 22) to 0.
01053 <i>Mtr Stall</i>	VP, Flashing red	Soft	The drive is in a limit condition for a period of time in excess of the value specified in <i>Motor Stall Time</i> (parameter 25) with the motor at zero speed.	Check <i>Torque Limit Sts</i> (parameter 87) to see which limit has occurred. Increase the appropriate limit parameter or reduce the load. If you do not want this condition to be reported as a fault, change bit 5 in <i>Fault Select 2</i> (parameter 22) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
01083 <i>MtrOvrlD Pend</i>	VP, Flashing green	Warning	Motor overload pending. The drive has reached 95% of the level required for a motor overload trip (see fault 01084).	Check for possible motor overheating. <ul style="list-style-type: none"> • If the motor temperature is excessive, reduce the accel/decel times (parameters 42 – 45) or reduce the load. • If the motor temperature is acceptable, increase the value of <i>Motor Overload %</i> (parameter 26). If you do not want this condition to be reported as a warning, change bit 3 in <i>Warning Select 2</i> (parameter 23) to 0.
01084 <i>MtrOvrlD Trp</i>	VP, Flashing green	Warning	Motor overload tripped. The drive has reached the level of accumulated motor current over time as set by <i>Motor Overload %</i> (parameter 26).	Check for possible motor overheating. <ul style="list-style-type: none"> • If the motor temperature is excessive, reduce the accel/decel times (parameters 42 – 45) or reduce the load. • If the motor temperature is acceptable, increase the value of <i>Motor Overload %</i> (parameter 26). If you do not want this condition to be reported as a warning, change bit 4 in <i>Warning Select 2</i> (parameter 23) to 0.
01085 <i>Mtr Stall</i>	VP, Flashing green	Warning	The drive is in a limit condition for a period of time in excess of the value specified in <i>Motor Stall Time</i> (parameter 25) with the motor at zero speed.	Check <i>Torque Limit Sts</i> (parameter 87) to see which limit has occurred. Increase the appropriate limit parameter or reduce the load. If you do not want this condition to be reported as a warning, change bit 5 in <i>Warning Select 2</i> (parameter 23) to 0.
02028 <i>Inv Overtemp Trp</i>	VP, Flashing red	Soft	Inverter overtemperature trip. There is excessive temperature at the heatsink. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Check the cabinet filters, drive fans, and heatsinks. Check the thermal sensor and sensor wiring (connector). Reduce the load or duty cycle if possible. Lower the value of <i>PWM Frequency</i> (parameter 10).
02049 <i>Inv Overtemp Pnd</i>	VP, Flashing red	Soft	An inverter overtemperature is pending. The inverter heatsink temperature is approaching the trip level.	Check the cabinet filters, drive fans, and heatsinks. Check the thermal sensor and sensor wiring (connector). Reduce the load or duty cycle if possible. Lower the value of <i>PWM Frequency</i> (parameter 10). If you do not want this condition to be reported as a fault, change bit 1 in <i>Fault Select 2</i> (parameter 22) to 0.
02061 <i>InvOvld Pend</i>	VP, Flashing red	Soft	An inverter (IT) overload is pending. The inverter current has been in excess of 105% of <i>Inverter Amps</i> (parameter 11) too long. Continued operation at this load level will cause an overload.	Reduce the load or duty cycle if possible. If you do not want this condition to be reported as a fault, change bit 13 in <i>Fault Select 2</i> (parameter 22) to 0.
02063 <i>Inv Overload</i>	VP, Flashing red	Soft	Inverter (IT) overload. The inverter current has been in excess of 105% of <i>Inverter Amps</i> (parameter 11) too long.	Reduce the load or duty cycle if possible. If you do not want this condition to be reported as a fault, change bit 15 in <i>Fault Select 2</i> (parameter 22) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
02081 <i>Inv Overtemp Pnd</i>	VP, Flashing green	Warning	An inverter overtemperature is pending. The inverter heatsink temperature is approaching the trip level.	Check the cabinet filters, drive fans, and heatsinks. Check the thermal sensor and sensor wiring (connector). Reduce the load or duty cycle if possible. Lower the value of <i>PWM Frequency</i> (parameter 10). If you do not want this condition to be reported as a warning, change bit 1 in <i>Warning Select 2</i> (parameter 23) to 0.
02093 <i>InvOvld Pend</i>	VP, Flashing green	Warning	An inverter (IT) overload is pending. The inverter current has been in excess of 105% of <i>Inverter Amps</i> (parameter 11) too long. Continued operation at this load level will cause an overload.	Reduce the load or duty cycle if possible. If you do not want this condition to be reported as a warning, change bit 13 in <i>Warning Select 2</i> (parameter 23) to 0.
02095 <i>Inv Overload</i>	VP, Flashing green	Warning	Inverter (IT) overload. The inverter current has been in excess of 105% of <i>Inverter Amps</i> (parameter 11) too long.	Reduce the load or duty cycle if possible. If you do not want this condition to be reported as a warning, change bit 15 in <i>Warning Select 2</i> (parameter 23) to 0.
03008 <i>HW Malfunction</i>	VP, Red 1 blink	Hard	A hardware malfunction was detected on power up or reset. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03009 <i>HW Malfunction</i>	VP, Red 2 blink	Hard	A hardware malfunction was detected on power up or reset. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03010 <i>HW Malfunction</i>	VP, Red 3 blink	Hard	A hardware malfunction was detected on power up or reset. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03011 <i>HW Malfunction</i>	VP, Red 4 blink	Hard	A hardware malfunction was detected on power up or reset. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03012 <i>HW Malfunction</i>	VP, Red 5 blink	Hard	A hardware malfunction was detected on power up or reset. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03014 <i>EE Checksum</i>	VP, Flashing red	Soft	The parameter database is corrupt.	Initialize parameters or: <ul style="list-style-type: none"> • Perform a Recall Values operation. • Perform a Save Values operation. • Verify the parameters. • Reset the drive. If the fault still occurs, replace the main control board.
03015 <i>HW Malfunction</i>	VP, Flashing red	Soft	A hardware malfunction has occurred.	Recycle the power. If the fault does not clear, replace the main control board.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
03022 <i>Diff Drv Type</i>	VP, Flashing red	Soft	The main control board has been initialized on a different size drive.	Issue a <i>Reset Defaults</i> command to set the drive parameters back to the default values.
03023 <i>SW Malfunction</i>	VP, Solid red	Hard	A software malfunction has occurred.	Recycle the power. If the fault does not clear, replace the main control board. If the fault still occurs, replace the gate driver board.
03024 <i>SW Malfunction</i>	VP, Solid red	Hard	A software malfunction has occurred. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03025 <i>Absolute Overspd</i>	VP, Flashing red	Soft	The motor speed has exceeded the speed limit plus <i>Absolute Overspd</i> (parameter 24) settings. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	If operating in torque mode, check if the load is allowing excessive motor speed. Check if the setting of <i>Absolute Overspd</i> (parameter 24) or the speed limits (parameters 40 and 41) are too low.
03026 <i>Analog Spply Tol</i>	VP, Flashing red	Soft	The analog supply tolerance voltage is outside of the 13V to 18V range. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Possible faulty analog 15V power supply. The gate driver board or the main control board may require replacement.
03029 <i>SW Malfunction</i>	VP, Solid red	Hard	A software malfunction has occurred.	Recycle the power. If the fault does not clear, replace the main control board.
03030 <i>SW Malfunction</i>	VP, Solid red	Hard	A software malfunction has occurred. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Recycle the power. If the fault does not clear, replace the main control board.
03031 <i>SW Malfunction</i>	VP, Solid red	Hard	A software malfunction has occurred.	Recycle the power. If the fault does not clear, replace the main control board.
03040 <i>mA Input</i>	VP, Flashing red	Soft	A loss of 4 – 20mA input has occurred.	Check your wiring and connections. If the fault does not clear, replace the main control board. If you do not want this condition to be reported as a fault, change bit 8 in <i>Fault Select 1</i> (parameter 20) to 0.
03057 <i>Param Limit</i>	VP, Flashing red	Soft	A parameter limit has occurred.	Examine the parameter limit testpoints to determine the exact cause. Refer to the <i>Understanding Parameter Limit Faults</i> section in the troubleshooting chapter of the user manual. If you do not want this condition to be reported as a fault, change bit 9 in <i>Fault Select 2</i> (parameter 22) to 0.
03058 <i>Math Limit</i>	VP, Flashing red	Soft	A math limit has occurred.	Examine the math limit testpoints to determine the exact cause. Refer to the <i>Understanding Math Limit Faults</i> section in the troubleshooting chapter of the user manual. If you do not want this condition to be reported as a fault, change bit 10 in <i>Fault Select 2</i> (parameter 22) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
03072 <i>mA Input</i>	VP, Flashing green	Warning	A loss of 4 – 20mA input has occurred.	Check your wiring and connections. If you do not want this condition to be reported as a warning, change bit 8 in <i>Warning Select 1</i> (parameter 21) to 0.
03089 <i>Param Limit</i>	VP, Flashing green	Warning	A parameter limit has occurred.	Examine the parameter limit testpoints to determine the exact cause. Refer to the <i>Understanding Parameter Limit Faults</i> section in the troubleshooting chapter of the user manual. If you do not want this condition to be reported as a warning, change bit 9 in <i>Warning Select 2</i> (parameter 23) to 0.
03090 <i>Math Limit</i>	VP, Flashing green	Warning	A math limit has occurred.	Examine the math limit testpoints to determine the exact cause. Refer to the <i>Understanding Math Limit Faults</i> section in the troubleshooting chapter of the user manual. If you do not want this condition to be reported as a warning, change bit 10 in <i>Warning Select 2</i> (parameter 23) to 0.
05048 <i>Spd Fdbk Loss</i>	VP, Flashing red	Soft	A loss of feedback occurred.	Check the encoder wiring. Verify that the encoder signals are free of noise. If you do not want this condition to be reported as a fault, change bit 0 in <i>Fault Select 2</i> (parameter 22) to 0.
05054 <i>External Flt In</i>	VP, Flashing red	Soft	The external fault input from the L Option board is open.	Check the external circuit for cause of an open input signal. If you do not want this condition to be reported as a fault, change bit 6 in <i>Fault Select 2</i> (parameter 22) to 0.
05080 <i>Spd Fdbk Loss</i>	VP, Flashing green	Warning	A loss of feedback occurred.	Check the encoder wiring. Verify that the encoder signals are free of noise. If you do not want this condition to be reported as a warning, change bit 0 in <i>Warning Select 2</i> (parameter 23) to 0.
05086 <i>External Flt In</i>	VP, Flashing green	Warning	The external fault input from the L Option board is open.	Check the external circuit for cause of an open input signal. If you do not want this condition to be reported as a warning, change bit 6 in <i>Warning Select 2</i> (parameter 23) to 0.
06041 <i>SP 1 Timeout</i>	VP, Flashing red	Soft	The SCANport adapter at port 1 has been disconnected and the logic mask bit for port 1 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a fault, change bit 9 in <i>Fault Select 1</i> (parameter 20) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
06042 <i>SP 2 Timeout</i>	VP, Flashing red	Soft	The SCANport adapter at port 2 has been disconnected and the logic mask bit for port 2 is set (1).	<p>If the adapter was not intentionally disconnected:</p> <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. <p>If you do not want this condition to be reported as a fault, change bit 10 in <i>Fault Select 1</i> (parameter 20) to 0.</p>
06043 <i>SP 3 Timeout</i>	VP, Flashing red	Soft	The SCANport adapter at port 3 has been disconnected and the logic mask bit for port 3 is set (1).	<p>If the adapter was not intentionally disconnected:</p> <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. <p>If you do not want this condition to be reported as a fault, change bit 11 in <i>Fault Select 1</i> (parameter 20) to 0.</p>
06044 <i>SP 4 Timeout</i>	VP, Flashing red	Soft	The SCANport adapter at port 4 has been disconnected and the logic mask bit for port 4 is set (1).	<p>If the adapter was not intentionally disconnected:</p> <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. <p>If you do not want this condition to be reported as a fault, change bit 12 in <i>Fault Select 1</i> (parameter 20) to 0.</p>
06045 <i>SP 5 Timeout</i>	VP, Flashing red	Soft	The SCANport adapter at port 5 has been disconnected and the logic mask bit for port 5 is set (1).	<p>If the adapter was not intentionally disconnected:</p> <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. <p>If you do not want this condition to be reported as a fault, change bit 13 in <i>Fault Select 1</i> (parameter 20) to 0.</p>
06046 <i>SP 6 Timeout</i>	VP, Flashing red	Soft	The SCANport adapter at port 6 has been disconnected and the logic mask bit for port 6 is set (1).	<p>If the adapter was not intentionally disconnected:</p> <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. <p>If you do not want this condition to be reported as a fault, change bit 14 in <i>Fault Select 1</i> (parameter 20) to 0.</p>
06047 <i>SP Error</i>	VP, Flashing red	Soft	SCANport communications have been interrupted.	<p>If the adapter was not intentionally disconnected:</p> <ul style="list-style-type: none"> • Check the amount of noise on the system. • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. <p>If you do not want this condition to be reported as a fault, change bit 15 in <i>Fault Select 1</i> (parameter 20) to 0.</p>

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
06073 <i>SP 1 Timeout</i>	VP, Flashing green	Warning	The SCANport adapter at port 1 has been disconnected and the logic mask bit for port 1 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 9 in <i>Warning Select 1</i> (parameter 21) to 0.
06074 <i>SP 2 Timeout</i>	VP, Flashing green	Warning	The SCANport adapter at port 2 has been disconnected and the logic mask bit for port 2 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 10 in <i>Warning Select 1</i> (parameter 21) to 0.
06075 <i>SP 3 Timeout</i>	VP, Flashing green	Warning	The SCANport adapter at port 3 has been disconnected and the logic mask bit for port 3 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 11 in <i>Warning Select 1</i> (parameter 21) to 0.
06076 <i>SP 4 Timeout</i>	VP, Flashing green	Warning	The SCANport adapter at port 4 has been disconnected and the logic mask bit for port 4 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 12 in <i>Warning Select 1</i> (parameter 21) to 0.
06077 <i>SP 5 Timeout</i>	VP, Flashing green	Warning	The SCANport adapter at port 5 has been disconnected and the logic mask bit for port 5 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 13 in <i>Warning Select 1</i> (parameter 21) to 0.
06078 <i>SP 6 Timeout</i>	VP, Flashing green	Warning	The SCANport adapter at port 6 has been disconnected and the logic mask bit for port 6 is set (1).	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 14 in <i>Warning Select 1</i> (parameter 21) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
06079 <i>SP Error</i>	VP, Flashing green	Warning	SCANport communications have been interrupted.	If the adapter was not intentionally disconnected: <ul style="list-style-type: none"> • Check the amount of noise on the system. • Check the wiring to the SCANport adapters. • Replace wiring, SCANport expander, SCANport adapters, and main control board. • Replace drive, if required. If you do not want this condition to be reported as a warning, change bit 15 in <i>Warning Select 1</i> (parameter 21) to 0.
12016 <i>Overvoltage</i>	CP, Solid red	Soft	The DC bus voltage has exceeded the maximum value. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Monitor the AC line for high line voltage or transient conditions. Increase the deceleration time or install the dynamic brake option because motor regeneration can also cause bus overvoltages. Refer to the user manual for a description of <i>Bus Options</i> (parameter 13) for additional information about bus overvoltages. If you are using flux braking, refer to Chapter 9, <i>Applications</i> , in the user manual for information about flux braking.
12017 <i>Desaturation</i>	CP, Solid red	Soft	There was too much current in the system. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Run the power structure diagnostics. Check for a shorted motor or motor wiring. Replace the drive.
12018 <i>Ground Fault</i>	CP, Solid red	Soft	A current path to earth ground in excess of drive rated current has been detected at one or more of the drive output terminals. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Run the power structure diagnostics. Check the motor and external wiring to the drive output terminals for a grounded condition. Replace the drive.
12019 <i>Overcurrent</i>	CP, Solid red	Soft	There was too much current in the system. When this condition occurs, the drive coasts to a stop regardless of the selected stop type.	Run the power structure diagnostics. Check for shorted motor or motor wiring. Replace drive.
12032 <i>RidethruTime</i>	CP, Flashing red	Soft	There was a bus voltage drop of 150V and power did not return within 2 seconds.	Check the incoming power and fuses. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a fault, change bit 0 in <i>Fault Select 1</i> (parameter 20) to 0.
12033 <i>Prechg Time</i>	CP, Flashing red	Soft	The precharge function could not complete within 30 seconds.	Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a fault, change bit 1 in <i>Fault Select 1</i> (parameter 20) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
12034 <i>Bus Drop</i>	CP, Flashing red	Soft	The bus voltage dropped 150V below the bus tracker voltage.	Monitor the incoming AC line for low voltage or line power interruption. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a fault, change bit 2 in <i>Fault Select 1</i> (parameter 20) to 0.
12035 <i>Bus Undervlt</i>	CP, Flashing red	Soft	The DC bus voltage fell below the trip value (388V DC at 460V AC input).	Monitor the incoming AC line for low voltage or line power interruption. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a fault, change bit 3 in <i>Fault Select 1</i> (parameter 20) to 0 or decrease the bus undervoltage setpoint.
12036 <i>Bus Cycle>5</i>	CP, Flashing red	Soft	At least 5 ridethrough cycles have occurred within a 20 second period. This indicates a converter problem or a problem with the incoming power.	Monitor the incoming AC line for low voltage or line power interruption. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a fault, change bit 4 in <i>Fault Select 1</i> (parameter 20) to 0.
12037 <i>Open Circuit</i>	CP, Flashing red	Soft	The fast flux up current is less than 50% of commanded.	Make sure the motor is properly connected. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a fault, change bit 5 in <i>Fault Select 1</i> (parameter 20) to 0.
12064 <i>RidethruTime</i>	CP, Solid green	Warning	There was a drop of 150V and power did not return within 2 seconds.	Check the incoming power and fuses. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a warning, change bit 0 in <i>Warning Select 1</i> (parameter 21) to 0.
12065 <i>Prechrg Time</i>	CP, Solid green	Warning	The precharge function could not complete within 30 seconds.	Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a warning, change bit 1 in <i>Warning Select 1</i> (parameter 21) to 0.

Fault Code and Text	LED Information	Fault Type	Description	Suggested Action
12066 <i>Bus Drop</i>	CP, Solid green	Warning	The bus voltage dropped 150V below the bus tracker voltage.	Monitor the incoming AC line for low voltage or line power interruption. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a warning, change bit 2 in <i>Warning Select 1</i> (parameter 21) to 0.
12067 <i>Bus Undervlt</i>	CP, Solid green	Warning	The DC bus voltage fell below the minimum value (388V DC at 460V AC input).	Monitor the incoming AC line for low voltage or line power interruption. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a warning, change bit 3 in <i>Warning Select 1</i> (parameter 21) to 0.
12068 <i>Bus Cycle>5</i>	CP, Solid green	Warning	At least 5 ridethrough cycles have occurred within a 20 second period. This indicates a converter problem or a problem with the incoming power.	Monitor the incoming AC line for low voltage or line power interruption. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a warning, change bit 4 in <i>Warning Select 1</i> (parameter 21) to 0.
12069 <i>Open Circuit</i>	CP, Solid green	Warning	The fast flux up current is less than 50% of commanded.	Make sure the motor is properly connected. Refer to the <i>Understanding Precharge and Ridethrough Faults</i> section in the troubleshooting chapter of the user manual for more information. If you do not want this condition to be reported as a warning, change bit 5 in <i>Warning Select 1</i> (parameter 21) to 0.
13000 <i>HW Malfunction</i>	CP, Solid red	Hard	A hardware malfunction occurred.	Recycle the power. If the fault does not clear, replace the main control board.
13001 <i>HW Malfunction</i>	CP, Solid red	Hard	A hardware malfunction occurred.	Recycle the power. If the fault does not clear, replace the main control board.
13002 <i>HW Malfunction</i>	CP, Solid red	Hard	A hardware malfunction occurred.	Recycle the power. If the fault does not clear, replace the main control board.
13003 <i>HW Malfunction</i>	CP, Solid red	Hard	A hardware malfunction occurred.	Recycle the power. If the fault does not clear, replace the main control board.
13004 <i>HW Malfunction</i>	CP, Solid red	Hard	A hardware malfunction occurred.	Recycle the power. If the fault does not clear, replace the main control board.

Diagnostic Procedures by Symptom

The following charts list drive symptoms, symptom descriptions, and recommended actions.

Figure 2.4
Drive Will Not Start or Jog

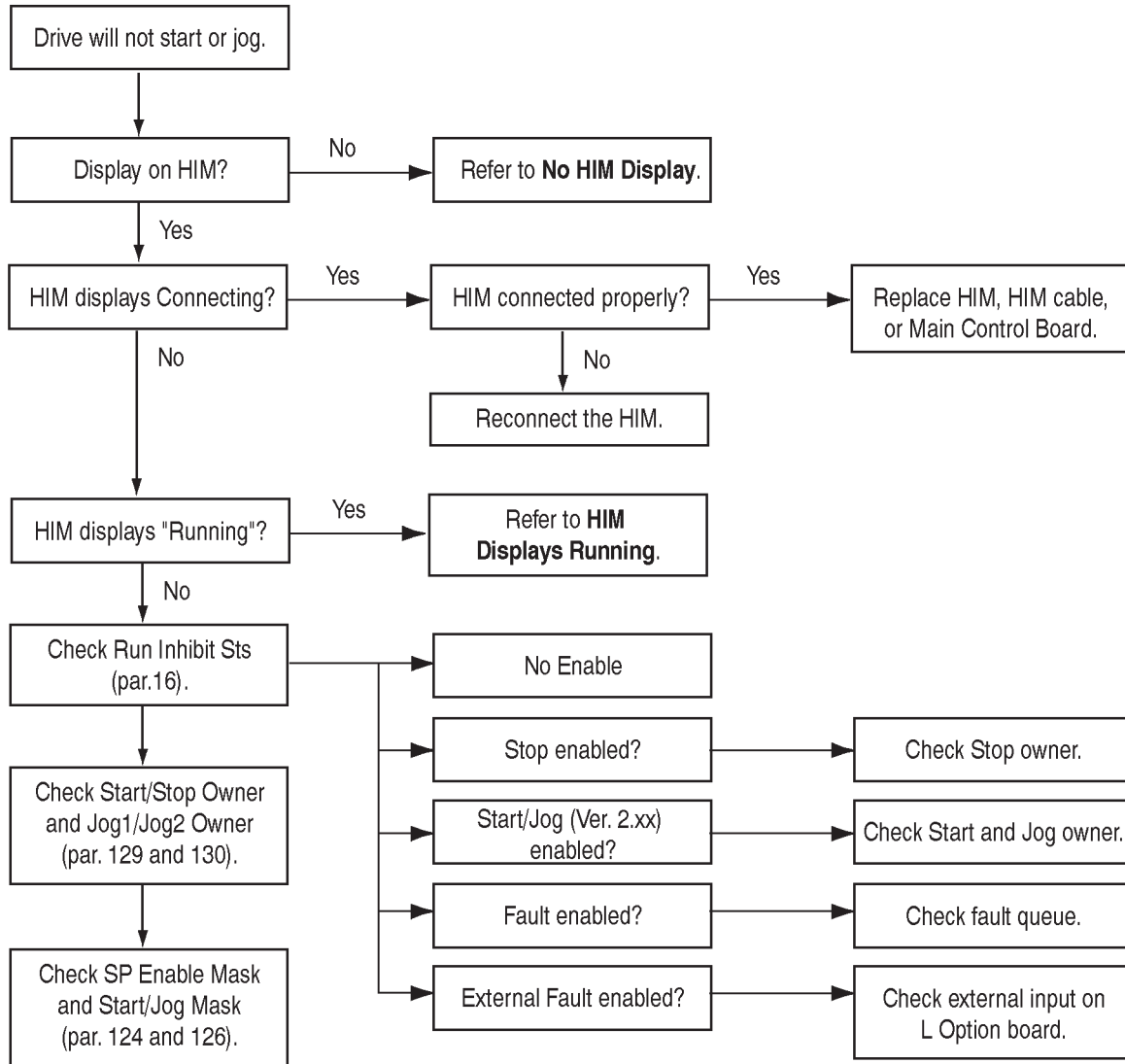


Figure 2.5
No HIM Display

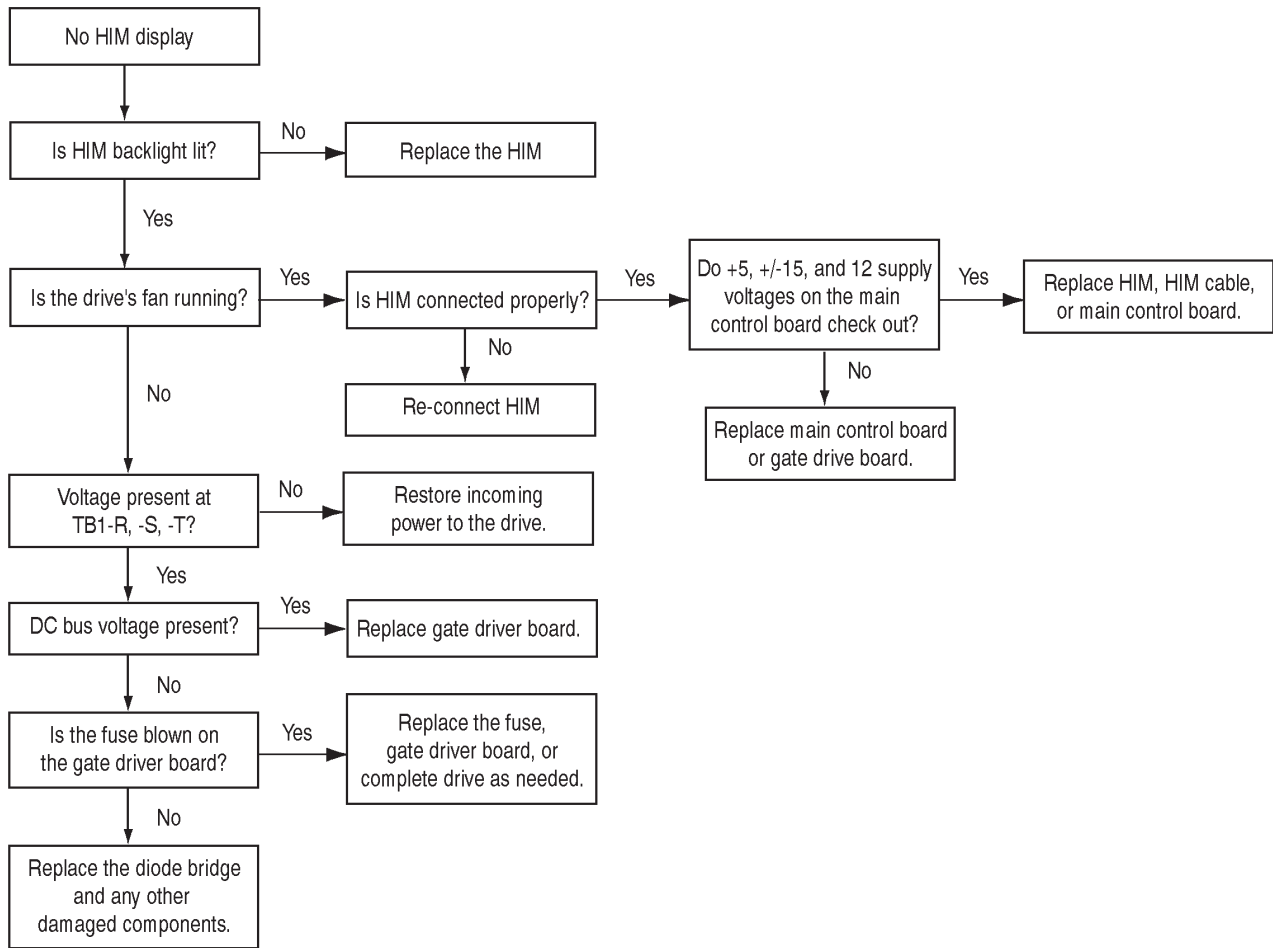


Figure 2.6
HIM Displays "Running"

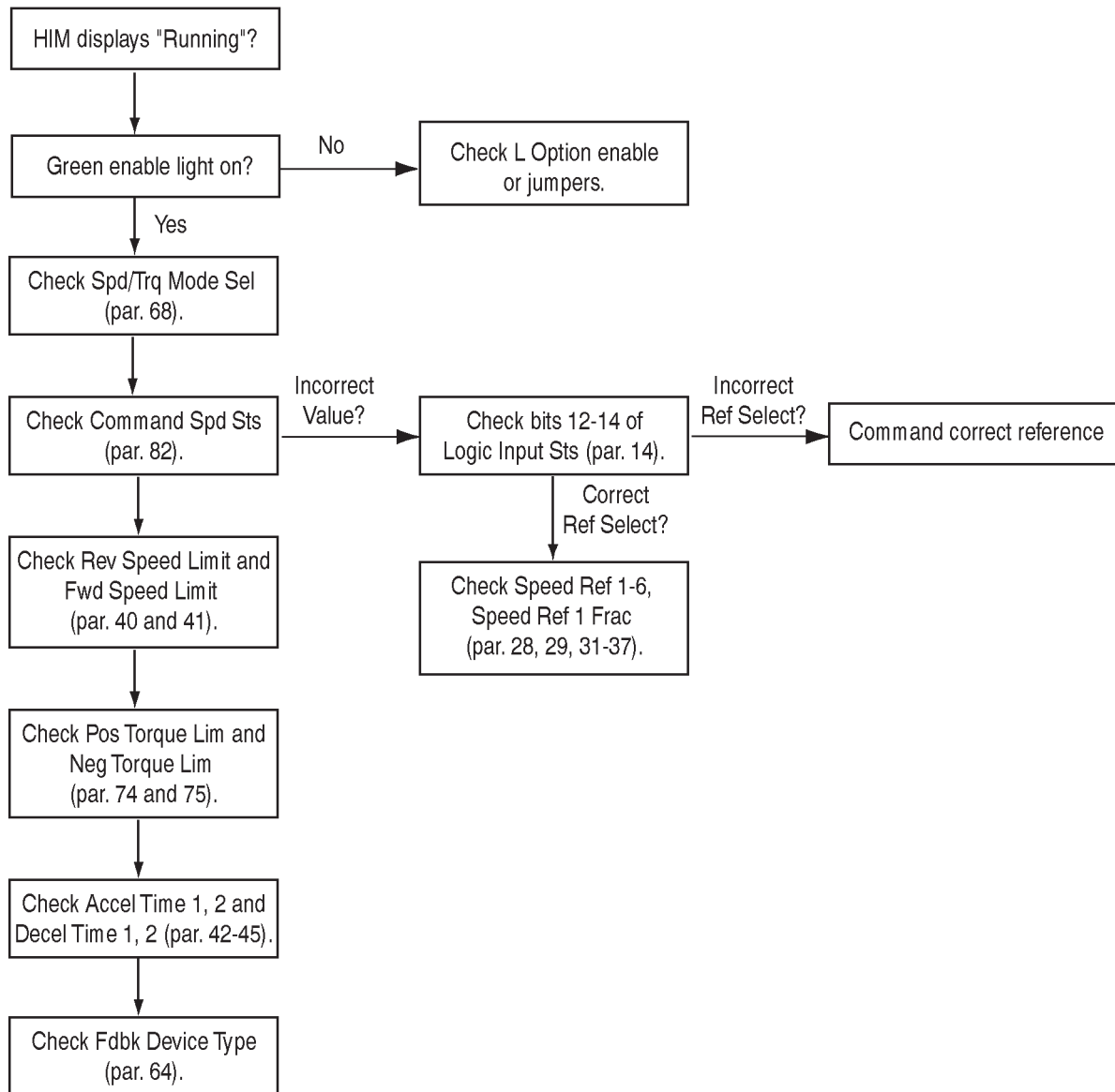
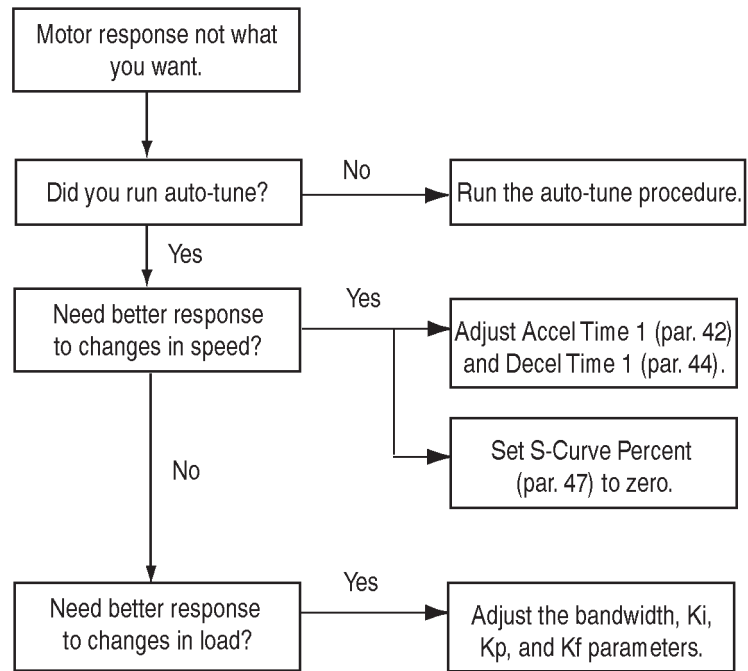


Figure 2.7
Motor Response Not Where You Want It



Start Up Troubleshooting Procedures

If you are having problems with the start up procedure, refer to this table for possible solutions before calling for help.

Table 2.E

If:	Then:
You powered up your drive and cannot access the start up routine.	The start up procedure is not supported on a Series A Human Interface Module (HIM). To verify that you have a Series A HIM, check the series letter located on the back side of the HIM or check the HIM version when you first power up your drive.
You got a <i>Feedback Loss Fault</i> .	You have specified that an encoder is on the system but it has been disconnected.
The motor does not turn during the phase rotation test.	Remove the load from the motor and try running the autotune tests again. Afterwards, you will need to attach the load again and run the inertia test manually.
During the phase rotation test you were asked to swap the encoder leads. You changed the leads and ran start up again. You were asked to swap the leads again.	The drive is not getting any speed feedback information. You need to: <ul style="list-style-type: none"> • Check the connection between the encoder and the motor. • Run the phase rotation test again and escape out to the status display at the first question. Check the motor speed. It should ramp to 3 Hz (90 rpm) for a 60 Hz 4 pole motor. If the motor speed is 0 rpm, you should: <ul style="list-style-type: none"> • Check the encoder wiring. • Check the encoder itself.

Miscellaneous Troubleshooting Procedures

If you are having problems with how your 1336 IMPACT drive is operating, refer to this table for possible solutions before calling for help.

Table 2.F

If:	Then you should:
The drive starts and then stops.	<ul style="list-style-type: none"> • Check if the mode specified in <i>L Option Mode</i> (parameter 116) is 2 or 3 wire. • Check <i>SP 2 Wire Enable</i> (parameter 181). • Check to see if the HIM displays a fault message. • Check the L Option Board wiring. • Check the settings on your gateway (communications module).
There is a delay before the stop command takes effect.	<ul style="list-style-type: none"> • Check the value of <i>Stop Dwell Time</i> (parameter 18).
The motor waits before starting.	<ul style="list-style-type: none"> • Check <i>Start Dwell Time</i> (parameter 194). • Check <i>Pos Torque Lim</i> (parameter 74) and <i>Neg Torque Lim</i> (parameter 75). • Check <i>Fast Flux Level</i> (parameter 78) and bit 8 of <i>Bus/Brake Opts</i> (parameter 13). • Check <i>S-Curve Percent</i> (parameter 47).
The drive coasts on stop.	<ul style="list-style-type: none"> • Check the stop type bits in <i>Logic Options</i> (parameter 17). • Check <i>Zero Speed Tol</i> (parameter 19).
You cannot clear faults.	<ul style="list-style-type: none"> • Check if the port is enabled in <i>SP Enable Mask</i> (parameter 124). • Check if clear faults is enabled in <i>Clr Flt/Res Mask</i> (parameter 127). • Check if clear fault owners in <i>Ramp/CIFlt Owner</i> (parameter 131) is set. If set, check stop owners in <i>Start/Stop Owner</i> (parameter 129) and remove stop conditions. • The fault is a hard fault which requires a power cycle or drive reset.
The motor does not turn or run at the correct speed.	<ul style="list-style-type: none"> • Check which speed reference the drive is following in <i>Drive/Inv Status</i> (parameter 15) bits 13 – 15. • Check if <i>Spd/Trq Mode Sel</i> (parameter 68) is set correctly. • Check if <i>Spd Desired BW</i> (parameter 161) is non-zero. • Set the drive defaults and run start up again to tune the drive.

If:	Then you should:
The HIM pot does not control motor speed.	<ul style="list-style-type: none"> • Check if <i>SP An In1 Select</i> (parameter 133) or <i>SP An In2 Select</i> (parameter 136) is set to the HIM port number. • Check if <i>SP An In1 Scale</i> (parameter 135) or <i>SP An In2 Scale</i> (parameter 138) is 0.125. • Check if a <i>Speed Ref 1 – 7</i> (parameters 29 through 36) is linked to <i>SP An In1 Value</i> (parameter 134) or <i>SP An In2 Value</i> (parameter 137). • Check which speed reference the drive is following in <i>Drive/Inv Status</i> (parameter 15) bits 13 – 15. The speed reference should be set to the speed reference that <i>SP An In1 Value</i> (parameter 134) or <i>SP An In2 Value</i> (parameter 137) is linked to.
The drive will not change direction.	<ul style="list-style-type: none"> • Check if the port is enabled in <i>SP Enable Mask</i> (parameter 124). • Check if Direction is enabled in <i>Dir/Ref Mask</i> (parameter 125). • Check if Direction owner in <i>Dir/Ref Owner</i> (parameter 128) has any bit set. If so, remove the command direction. • Check to make sure that bit 11 in <i>Logic Options</i> (parameter 17) is clear (0).
You cannot change the speed reference.	<ul style="list-style-type: none"> • Check if the port is enabled in <i>SP Enable Mask</i> (parameter 124). • Check if Reference is enabled in <i>Dir/Ref Mask</i> (parameter 125). • Check if Reference owner in <i>Dir/Ref Owner</i> (parameter 128) has any bit set. If so, remove the command reference. If bit 0 (for the L Option control) is set, you need to do one of the following to remove ownership: <ul style="list-style-type: none"> • Clear bit 0 in <i>Dir/Ref Mask</i> (parameter 125). • If <i>L Option Mode</i> (parameter 116) is 2, 3, 8, 9, 23, 24, or 26, close the L Option inputs for speed references 1, 2, and 3.
The drive does not run correct torque.	<ul style="list-style-type: none"> • Set the drive defaults and run start up again to tune the drive. • Check <i>Spd/Trq Mode Sel</i> (parameter 68) and <i>Slave Torque %</i> (parameter 70).
The drive cannot control current and trips on an overcurrent fault.	<ul style="list-style-type: none"> • If you are using an encoder, check that you have entered the correct PPR into <i>Encoder PPR</i> (parameter 8).
The MOP does not work.	<ul style="list-style-type: none"> • Check <i>L Option Mode</i> (parameter 116). • Make sure that <i>Mop Value</i> (parameter 119) is linked to a speed reference.
The pulse input does not work.	<ul style="list-style-type: none"> • Make sure that the pulse input jumper is set correctly. • Make sure that the input is differential and not single ended. • Check the values of <i>Pulse In PPR</i> (parameter 120), <i>Pulse In Scale</i> (parameter 121), and <i>Pulse In Offset</i> (parameter 122). • Check the link on <i>Pulse In Value</i> (parameter 123).
The external fault does not work.	<ul style="list-style-type: none"> • Check the mode in <i>L Option Mode</i> (parameter 116). • Check bit 6 in <i>Fault Select 2</i> (parameter 22) and <i>Warning Select 2</i> (parameter 23).
You keep getting motor overload trips.	<ul style="list-style-type: none"> • Reduce the load. • Check bits 3 and 4 in <i>Fault Select 2</i> (parameter 22) and <i>Warning Select 2</i> (parameter 23). • Check <i>Motor Overload %</i> (parameter 26).
The motor reduced the speed range.	<ul style="list-style-type: none"> • Check <i>SP An In1 Scale</i> (parameter 135) or <i>SP An In2Scale</i> (parameter 138) if your speed input is coming from the HIM pot. • Check <i>An In 1 Offset</i> (parameter 97), <i>An In 1 Scale</i> (parameter 98), <i>An In 2 Offset</i> (parameter 100), <i>An In 2 Scale</i> (parameter 101), <i>mA Input Offset</i> (parameter 103), and <i>mA Input Scale</i> (parameter 104) if your speed input is coming from the analog inputs. • Check <i>Speed Scale 1</i> (parameter 30) or <i>Speed Scale 7</i> (parameter 37). • Check <i>Absolute Overspd</i> (parameter 24). • Check <i>Min Speed Limit</i> (parameter 215).

Encoderless Troubleshooting Procedures

If you are having problems with encoderless mode, refer to this table for possible solutions before calling for help.

Table 2.G

If:	Then you should:
The motor will not accelerate or does not start smoothly	<ul style="list-style-type: none"> • Increase the bandwidth in <i>Spd Desired BW</i> (parameter 161). If the bandwidth is too low, the motor may not accelerate, although the current increases to current limit. • If the regen power limit is 0, increase it to at least -5%. • Increase the torque and current limits to the maximum. • Increase the value of <i>Kp Freq Reg</i> (parameter 178).
The motor oscillates after it is up to speed	<ul style="list-style-type: none"> • Decrease the bandwidth in <i>Spd Desired BW</i> (parameter 161) if the process will allow. If this does not help, depending on your application, you need to either increase or decrease the value of <i>Error Filter BW</i> (parameter 162).
The inverter trips on absolute overspeed during starting	<ul style="list-style-type: none"> • Increase the acceleration time. • If the overspeed occurs during a fast acceleration, increase the value of <i>Kp Freq Reg</i> (parameter 178) until the trip stops occurring. • Increase the bandwidth in <i>Spd Desired BW</i> (parameter 161). • If the overspeed occurs during a reversal, increase the deceleration time (slower deceleration).shippshippy

Disassembly and Access Procedures

Chapter Objectives

This chapter describes general disassembly procedures required to access internal drive components.

Disassembly and Access Overview



ATTENTION: Some printed circuit boards and drive components may contain hazardous voltage levels. Remove and lock out power before you disconnect or reconnect wires and before you remove or replace fuses and circuit boards. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Servicing energized industrial control equipment can be hazardous. Electrical shock, burns, or unintentional actuation of controlled industrial equipment may cause death or serious injury. Follow the safety-related practices of NFPA 70E, Electrical Safety for Employee Workplaces, when working on or near energized equipment. Do not work alone on energized equipment.

Electrostatic Discharge Precautions



ATTENTION: This assembly contains parts and sub-assemblies that are sensitive to electrostatic discharge. Static control precautions are required when servicing this assembly. Component damage may result if you ignore electrostatic discharge control procedures. If you are not familiar with static control procedures, reference Rockwell Automation Publication 8000-4.5.2, Guarding Against Electrostatic Discharge, or any other applicable ESD protection handbook.

Electrostatic discharge generated by static electricity can damage the complementary metallic oxide semiconductor devices on various drive boards. It is recommended that you perform these procedures to guard against this type of damage when circuit boards are removed or installed:

- Wear a wrist type grounding strap that is grounded to the chassis.
- Attach the wrist strap before removing the new circuit board from the conductive packet.
- Remove boards from the drive and immediately insert them into their conductive packets.

Tools

You need the following tools to disassemble and assemble the drive:

- Pliers
- Phillips screwdriver
- Standard screwdriver
- 5/16-inch or 8 mm socket
- 11/16-inch or 17 mm socket
- 5/16-inch or 8 mm open-end wrench
- Torque wrench, metered in lb-in. or N-m

Fastener Torque Specifications

Torque Sequence

When mounting components to a drive's heat sink, component-fastener torque sequences and tolerances are crucial to component-to-heat sink heat dissipation.

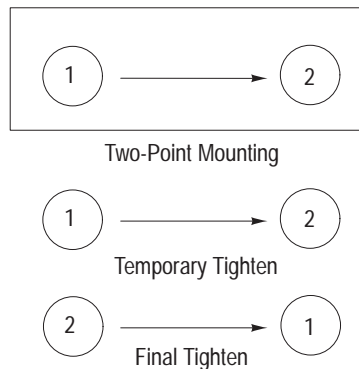


ATTENTION: Component can be damaged if temporary tightening procedure is not performed to specification.

Two-Point Mounting

The following illustrates temporary and final tightening sequences for components fastened to a heat sink using two screws. Temporary torque is 1/3 (33%) of final torque. The numeric illustration labels are for your assistance. Drive components do not carry these labels.

Figure 3.1
Two-Point Mounting

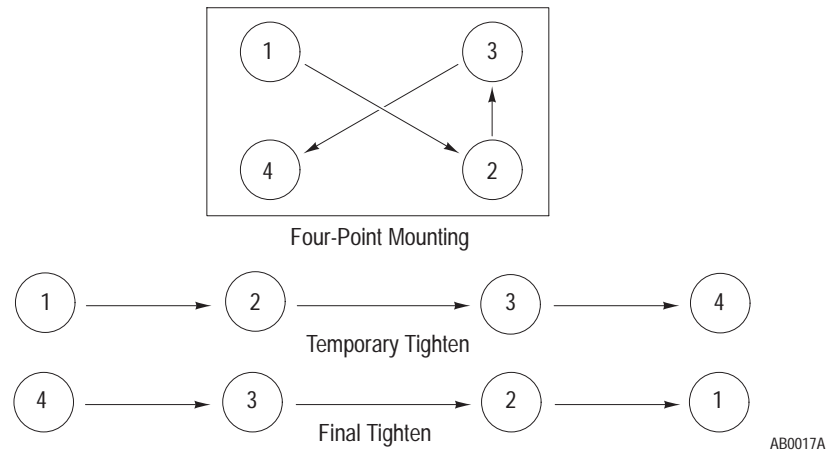


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Four-Point Mounting

The following illustrates temporary and final tightening sequences for components fastened to a heat sink using four screws. Temporary torque is 1/3 (33%) of final torque. The numeric illustration labels are for your assistance. Drive components do not carry these labels.

Figure 3.2
Four-Point Mounting



Torque Specifications

The following table lists fastener locations by component, how the fasteners are used, and torque specifications. Refer to Torque Sequence in this chapter for fastening two-point and four-point components to the heat sink.

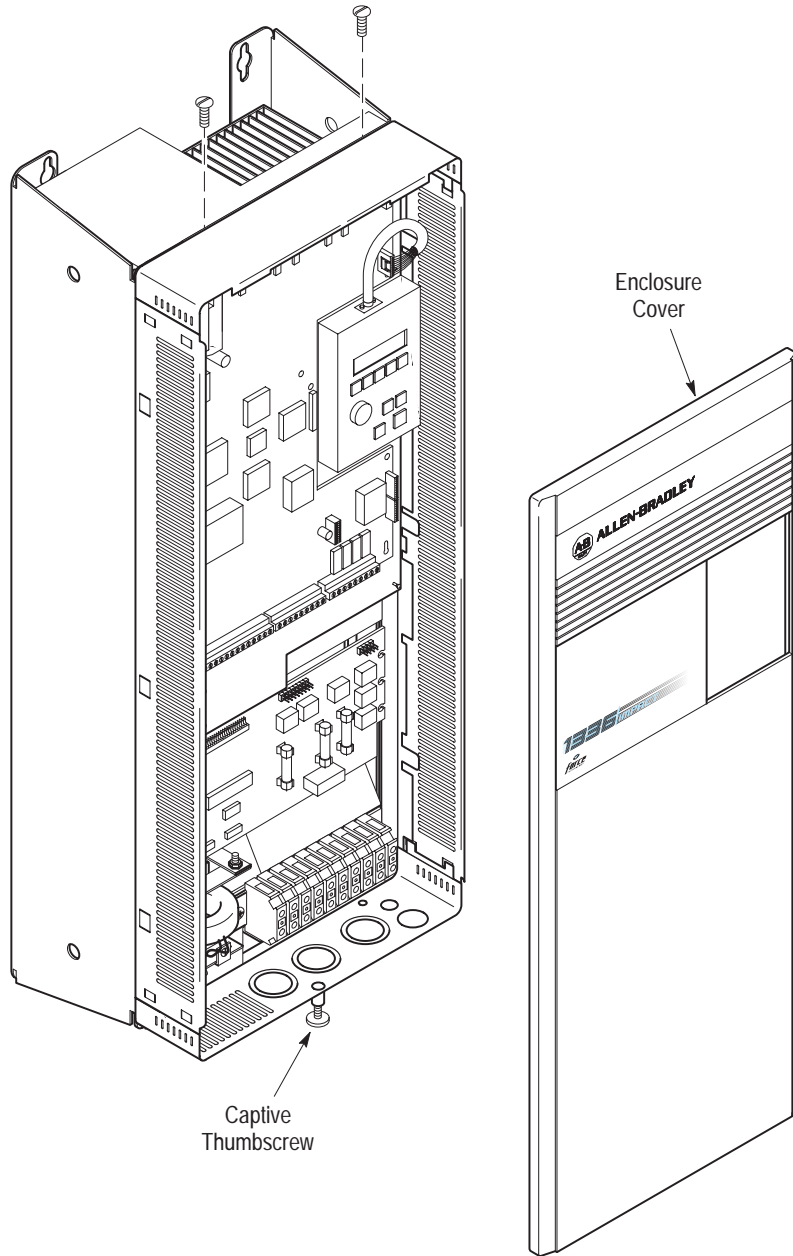
Table 3.A
Fastener Torque Specifications

Component	Fastener Application	Torque lb-in.	Torque N-m
Bus Capacitor Bank	Bank to chassis	25 – 31	2.8 – 3.5
DC Bus Inductor	Wires to bus bars	25 – 31	2.8 – 3.5
DC Bus Inductor	TB1 mounting plate to chassis	25 – 31	2.8 – 3.5
Snubber Board	Bus bars to capacitor bank	25 – 31	2.8 – 3.5
Snubber Board	Board to SCR1	25 – 31	2.8 – 3.5
Snubber Board	Board to PM1 – PM3	30 – 39	3.4 – 4.4
Power Modules PM1 – PM3	Module to heat sink	25 – 31	2.8 – 3.5
Input Rectifier	Rectifier to heat sink	25 – 31	2.8 – 3.5
Bus Fuse F1	Fuse to chassis	200 – 220	22.6 – 24.8
Thermistor	Thermistor to heat sink	Hand tighten only	
TB1	Wires to terminals	25 – 31	2.8 – 3.5
TB2	Wires to terminals	8	0.9
TB3	Wires to terminals	8	0.9
Ground Sense CT	Bracket to chassis	25 – 31	2.8 – 3.5
Ground Sense CT	Positive bus bar junction	25 – 31	2.8 – 3.5
Ground Sense CT	Bus bars to capacitor bank	25 – 31	2.8 – 3.5
Main Control Board	Board to Mounting Plate	12 – 16	1.4 – 1.8

Disassembly and Access Procedures

Opening the Drive Enclosure

Figure 3.3
Drive Enclosure



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Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

1. Remove power from the drive.
2. Loosen the captive thumb screw fastening the Enclosure cover to the bottom of the Enclosure frame.
3. Pull the bottom of the Enclosure cover outward to clear the frame and then lift the cover upward to remove the cover.
4. Check for zero volts at TB1 terminals +DC and –DC.
5. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
6. Remove the customer-supplied wiring from the drive.
7. Remove the screws from the Enclosure top panel. Note the tab slots in the top panel holding the side panels into place.
8. Lift the Enclosure side panels out of the Enclosure bottom-panel tab slots to remove the side panels.

Installation

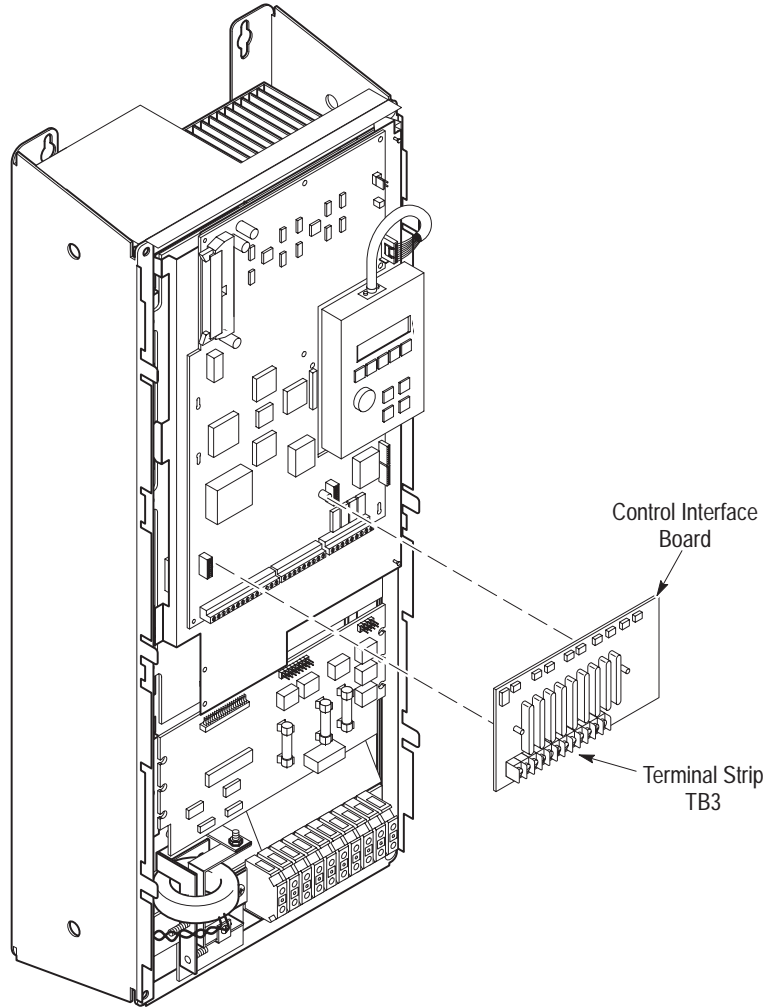
Install the Enclosure in reverse order of removal.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Removing L Option Board

Figure 3.4
L Option Board



AB0853A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Open the Enclosure cover. Refer to Opening the Drive Enclosure in this chapter.
3. Check for zero volts at TB1 terminals +DC and –DC.
4. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
5. Remove all wires from the terminals on TB3.
6. Loosen the two captive screws fastening the L Option Board to the Main Control Board.
7. Grip the right and left sides of the L Option Board and pull the board straight outward from the Main Control Board.

Installation

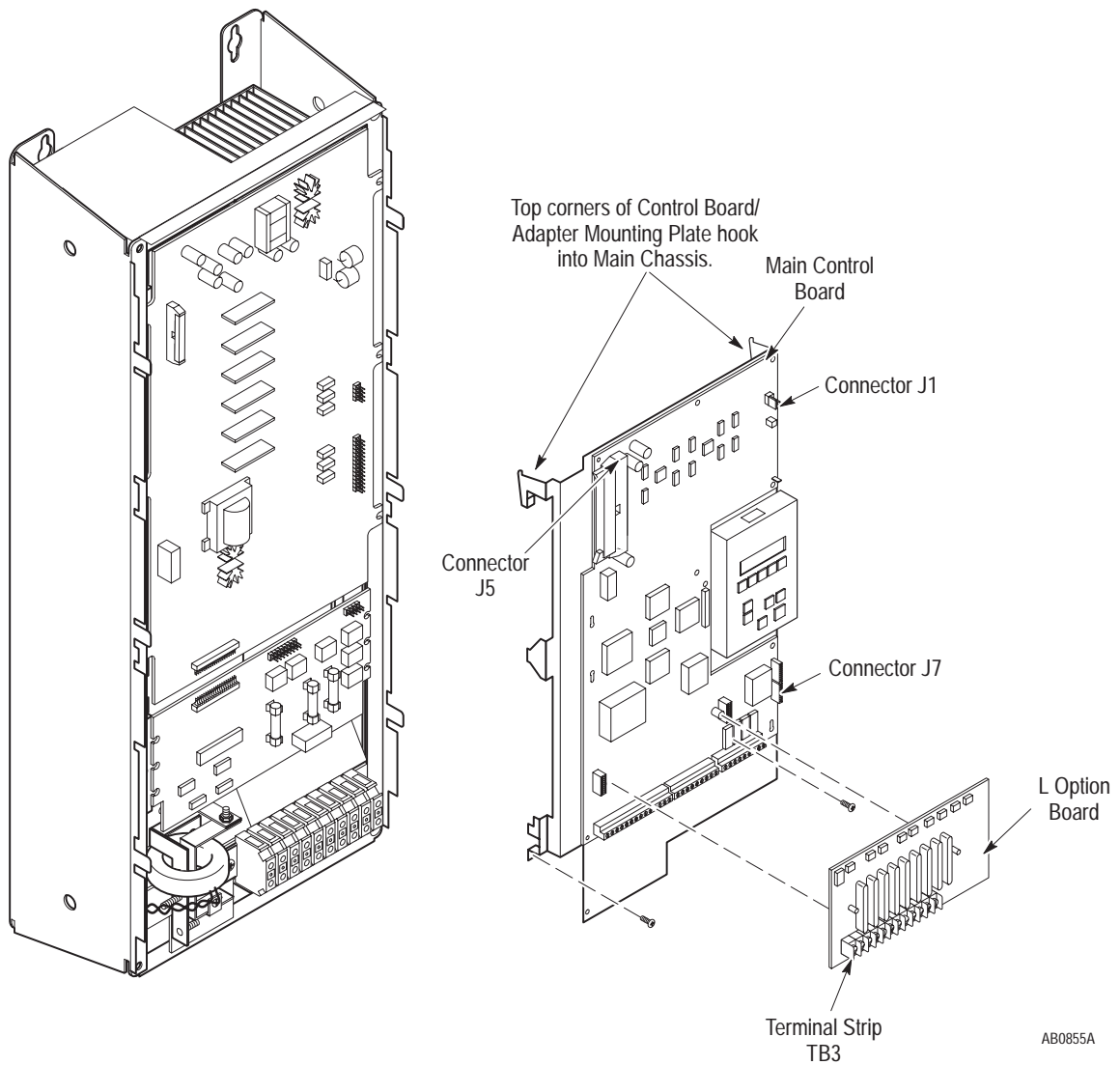
Install the L Option Board in reverse order of removal.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Removing the Main Control Board Mounting Plate

Figure 3.5
Main Control Board Mounting Plate



Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Open the Enclosure Cover. Refer to Opening the Drive Enclosure in this chapter.
3. Check for zero volts at TB1 terminals +DC and -DC.
4. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
5. Disconnect the following from the Main Control Board:
 - J1 connector
 - J5 ribbon cable connector
 - J7 connector
 - Ground wires from terminal strip TE
 - Chassis ground wire at the top-right corner of the Main Control Board Mounting Plate
6. Loosen the two captive screws near the bottom of the Main Control Board.
7. Pull the Main Control Board Mounting Plate out about two inches, then slide it downward.

Installation

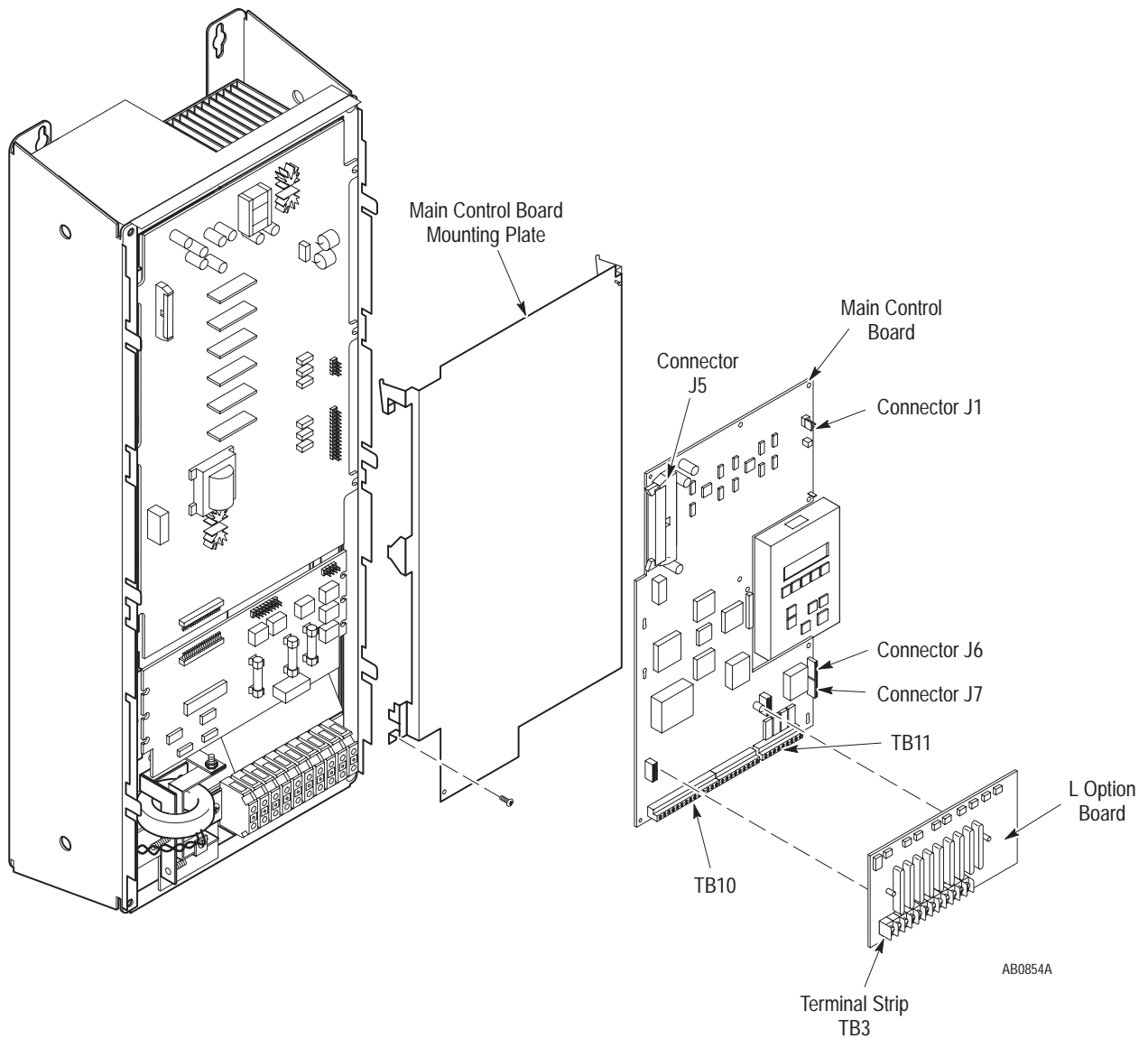
Install the Main Control Board Mounting Plate in reverse order of removal.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Removing the Main Control Board

Figure 3.6
Main Control Board



Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the Drive.
2. Open the Enclosure Cover. Refer to Opening the Drive Enclosure in this chapter.
3. Check for zero volts at TB1 Terminals +DC and -DC.
4. Check for absence of control voltage at:
 - TB10 and TB11
 - L Option Board (if used)
5. Remove all wires from Terminal Strip TB3 if an L Option Board is used.
6. Disconnect the following from the Main Control Board:
 - J1 connector
 - J5 ribbon cable connector
 - J6 connector
 - J7 connector
 - Ground wire at stake-on connector
 - All wires from the terminals on TB10 and TB11
7. Remove the screws fastening the Main Control Board to the mounting plate.
8. Lift the Main Control Board upward to release it from the slide-mount stand-offs.
9. Pull the Main Control Board away from the mounting plate.

Installation

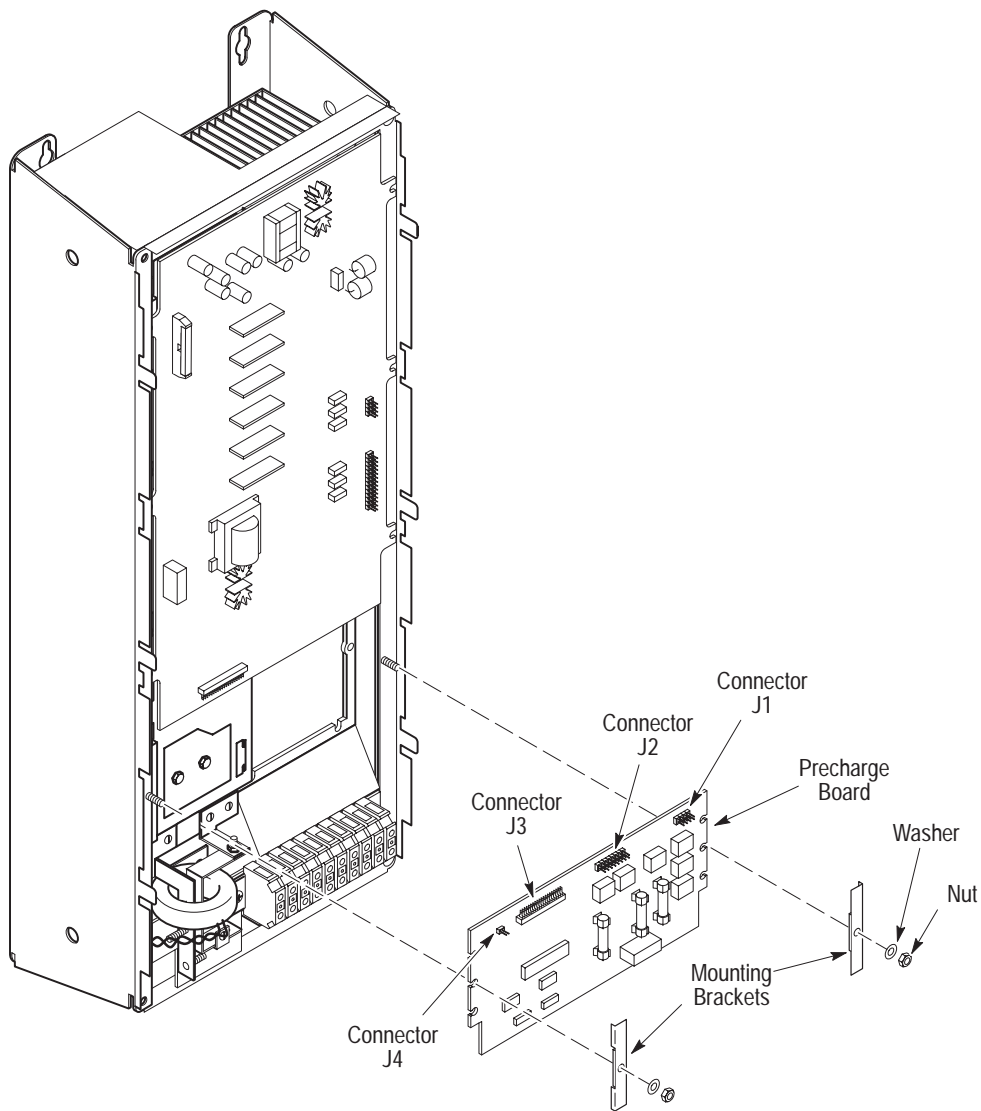
Install the Main Control Board in reverse order of removal.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Removing the Precharge Board

Figure 3.7
Precharge Board



AB0327A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Open the Enclosure. Refer to Opening the Drive Enclosure in this chapter.
3. Check for zero volts at TB1 terminals +DC and -DC.
4. Check for absence of control voltage at:
 - TB10 and TB11
 - L Option Board (if used)
5. Disconnect the following from the Precharge Board:
 - J1 connector
 - J2 connector
 - J3 connector
 - J4 connector
6. Remove the nuts and brackets fastening the sides of the Precharge Board to the drive.

Installation

Install the Precharge Board in reverse order of removal.



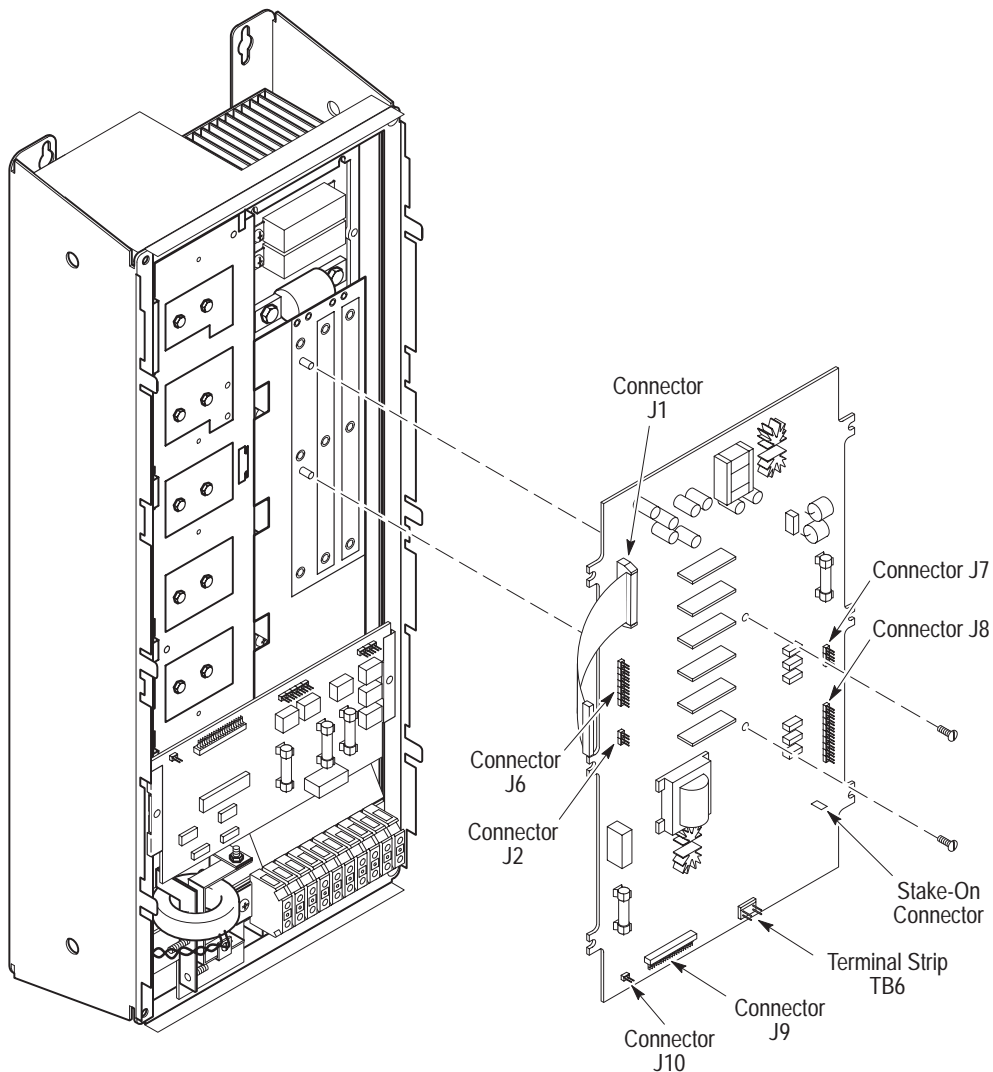
ATTENTION: When removing the entire wire harness connecting Gate Driver Board connector J9 to Precharge Board connector J3, align the wires on the harness terminals with the pins on the board connectors. Incorrect harness connection may result in faulty drive operation and may damage the equipment.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Removing the Gate Driver Board

Figure 3.8
Gate Driver Board



AB0341A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Open the Enclosure. Refer to Opening the Drive Enclosure in this chapter.
3. Check for zero volts at TB1 terminals +DC and –DC.
4. Check for absence of control voltage at:
 - TB10 and TB11
 - L Option Board (if used)
5. Remove the Main Control Board Mounting Plate. Refer to Removing the Main Control Board Mounting Plate in this chapter.
6. Disconnect the following from the Gate Driver Board:
 - J9 Precharge Board connector
 - J10 Bus Capacitor Bank connector
 - J2 Ground Sense CT connector
 - J7 Transistor Module connector
 - J8 Transistor Module connector
 - J6 Snubber Board connector
 - TB6 Fan connector
7. Remove the screws, fastening the Gate Driver Board to the drive to remove the board from the drive.

Installation

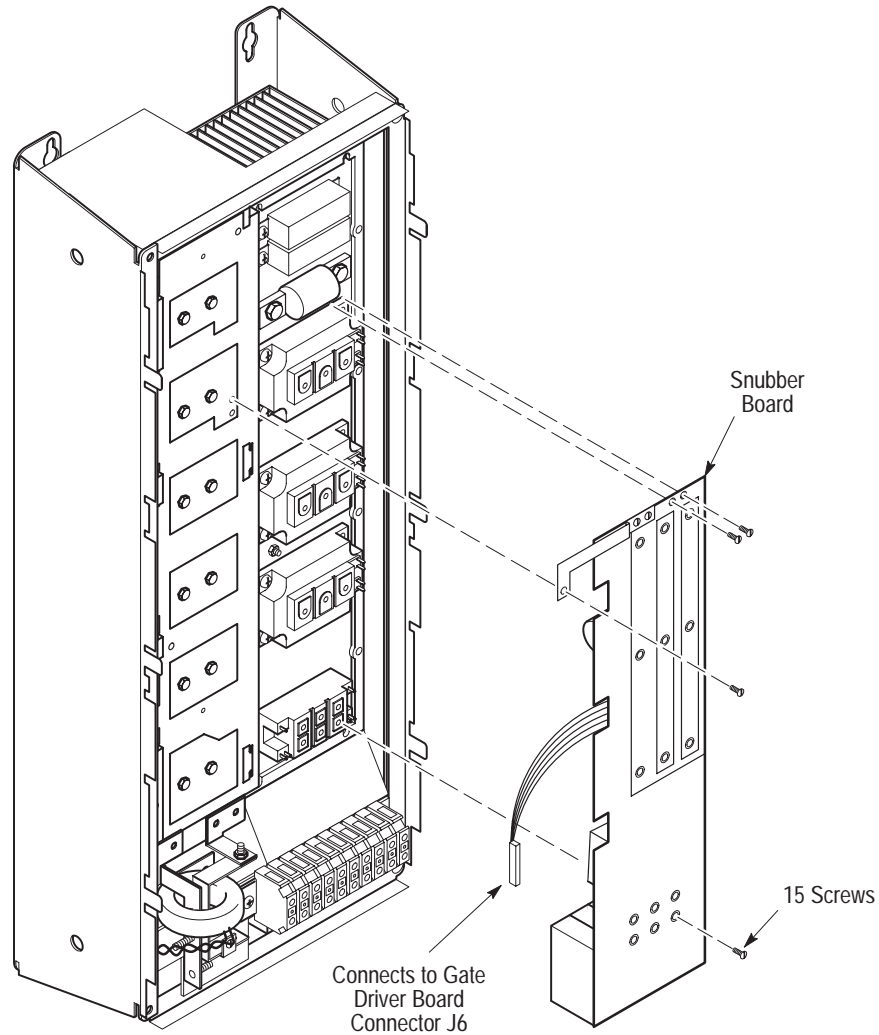
Install the Gate Driver Board in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Removing the Snubber Board

Figure 3.9
Snubber Board



AB0343A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Open the Enclosure. Refer to Opening the Drive Enclosure in this chapter.
3. Check for zero volts at TB1 terminals +DC and -DC.
4. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
5. Remove the Main Control Board Mounting Plate. Refer to Removing the Main Control Board Mounting Plate.
6. Remove the Gate Driver Board. Refer to Removing the Gate Driver Board in this chapter.
7. Remove the Precharge Board. Refer to Removing the Precharge Board in this chapter.
8. Remove the screws fastening the Snubber Board bus bar to the Bus Capacitor Bank.
9. Remove the wires from the Snubber Board stake-on connectors.
10. Remove the 15 screws fastening the Snubber Board to the Transistor Modules and Input Rectifier.



ATTENTION: The wire from TB1 terminal T3 (W) passes through the lower LEM located on the back of the Snubber Board. The wire from TB1 terminal T1 (U) passes through the upper LEM located on the back of the Snubber Board. During assembly, pass these wires through their respective LEMs to prevent damage to the equipment.

Installation

1. Remove the screws and nuts fastening the negative (-) bus bar to the old Snubber Board.
2. Fasten the bus bar to the new Snubber Board.
3. Pass the wires from TB1 terminals T3 (W) and T1 (U) through their respective LEMs.



ATTENTION: The wire from TB1 terminal T3 (W) passes through the lower LEM located on the back of the Snubber Board. The wire from TB1 terminal T1 (U) passes through the upper LEM located on the back of the Snubber Board. During assembly, pass these wires through their respective LEMs to prevent damage to the equipment.

4. Align the screw holes in the Snubber Board with the holes on the Transistor Modules and Input Rectifier.
5. Install the Snubber Board in reverse order of removal.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Accessing Chassis Power Components

To access the power components located on the chassis, refer to Removing the Gate Driver Board in this chapter.

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Component Test Procedures

Chapter Objectives

The following tests help you troubleshoot A020 – A030, B040, B050, BX040, BX060, and C025 – C060 drives.

Component Test Overview

In some cases, different tests troubleshoot components of the same name. These similar tests vary according to the rating of the drive being tested. Verify that the rating on the drive matches the rating for the test you are performing.

The procedures in this chapter assume that the drive you are servicing either has no enclosure or that the enclosure is open. For more information on opening the Drive Enclosure, refer to Chapter 3 – Disassembly and Access Procedures, Opening the Drive Enclosure.



ATTENTION: Some printed circuit boards and drive components may contain hazardous voltage levels. Remove and lock out power before you disconnect or reconnect wires and before you remove or replace fuses and circuit boards. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Servicing energized industrial control equipment can be hazardous. Electrical shock, burns, or unintentional actuation of controlled industrial equipment may cause death or serious injury. Follow the safety-related practices of NFPA 70E, Electrical Safety for Employee Workplaces, when working on or near energized equipment. Do not work alone on energized equipment.

Electrostatic Discharge Precautions



ATTENTION: This assembly contains parts and sub-assemblies that are sensitive to electrostatic discharge. Static control precautions are required when servicing this assembly. Component damage may result if you ignore electrostatic discharge control procedures. If you are not familiar with static control procedures, reference Rockwell Automation Publication 8000-4.5.2, Guarding Against Electrostatic Discharge, or any other applicable ESD protection handbook.

Electrostatic discharge generated by static electricity can damage the complementary metallic oxide semiconductor devices on various drive boards. It is recommended that you perform these procedures to guard against this type of damage when circuit boards are removed or installed:

- Wear a wrist-type grounding strap that is grounded to the chassis.
- Attach the wrist strap before removing the new circuit board from the conductive packet.
- Remove boards from the drive and immediately insert them into their conductive packets.

Tools

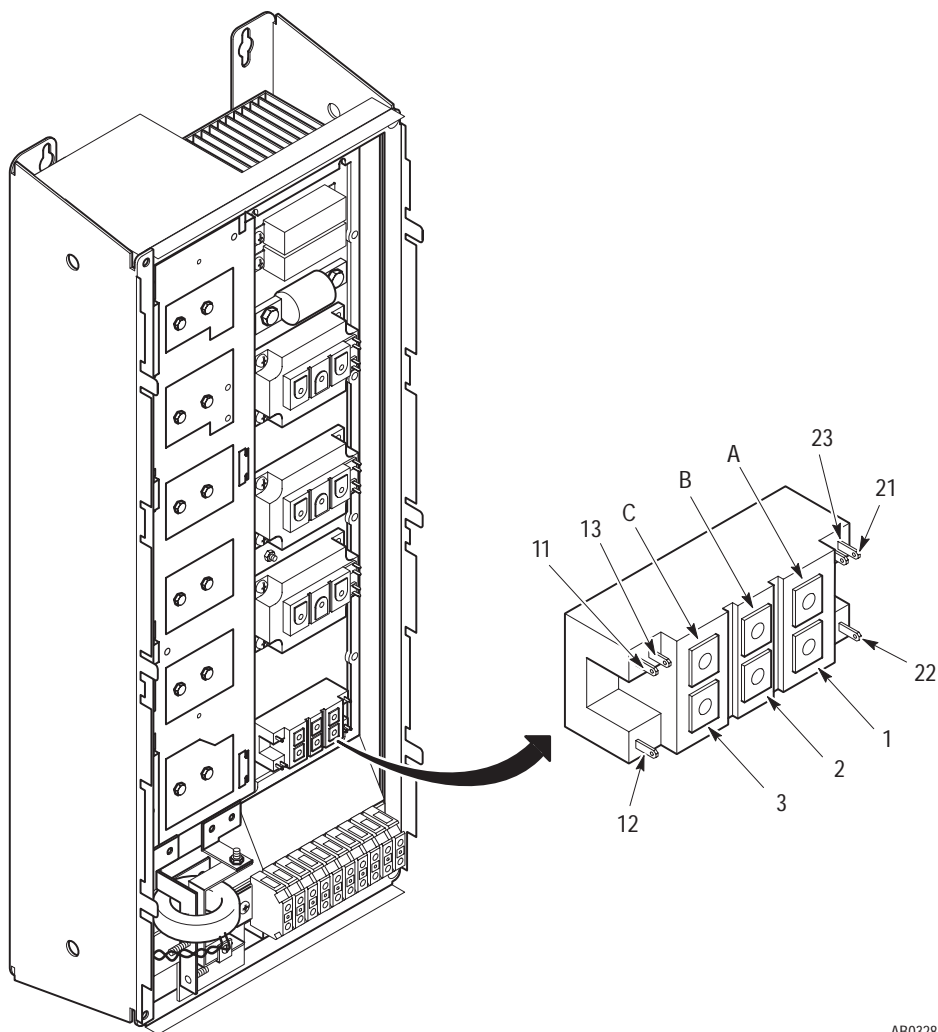
You need the following tools to disassemble and assemble the drive:

- Pliers
- Phillips screwdriver
- Standard screwdriver
- 5/16-inch or 8 mm socket
- 11/16-inch or 17 mm socket
- 5/16-inch or 8 mm open-end wrench
- Torque wrench, metered in lb-in. or N-m

Test 1 – Testing Input Rectifier SCR1

Input Rectifier SCR1 is located on the bottom of the heat sink.

Figure 4.1
Input Rectifier Test



AB0328B



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Snubber Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Snubber Board.
5. Set your meter to test diodes.
6. The following table shows meter connections and ideal meter readings for those connections. Refer to the former illustration for meter connection locations.

Table 4.A
Input Rectifier SCR1 Test

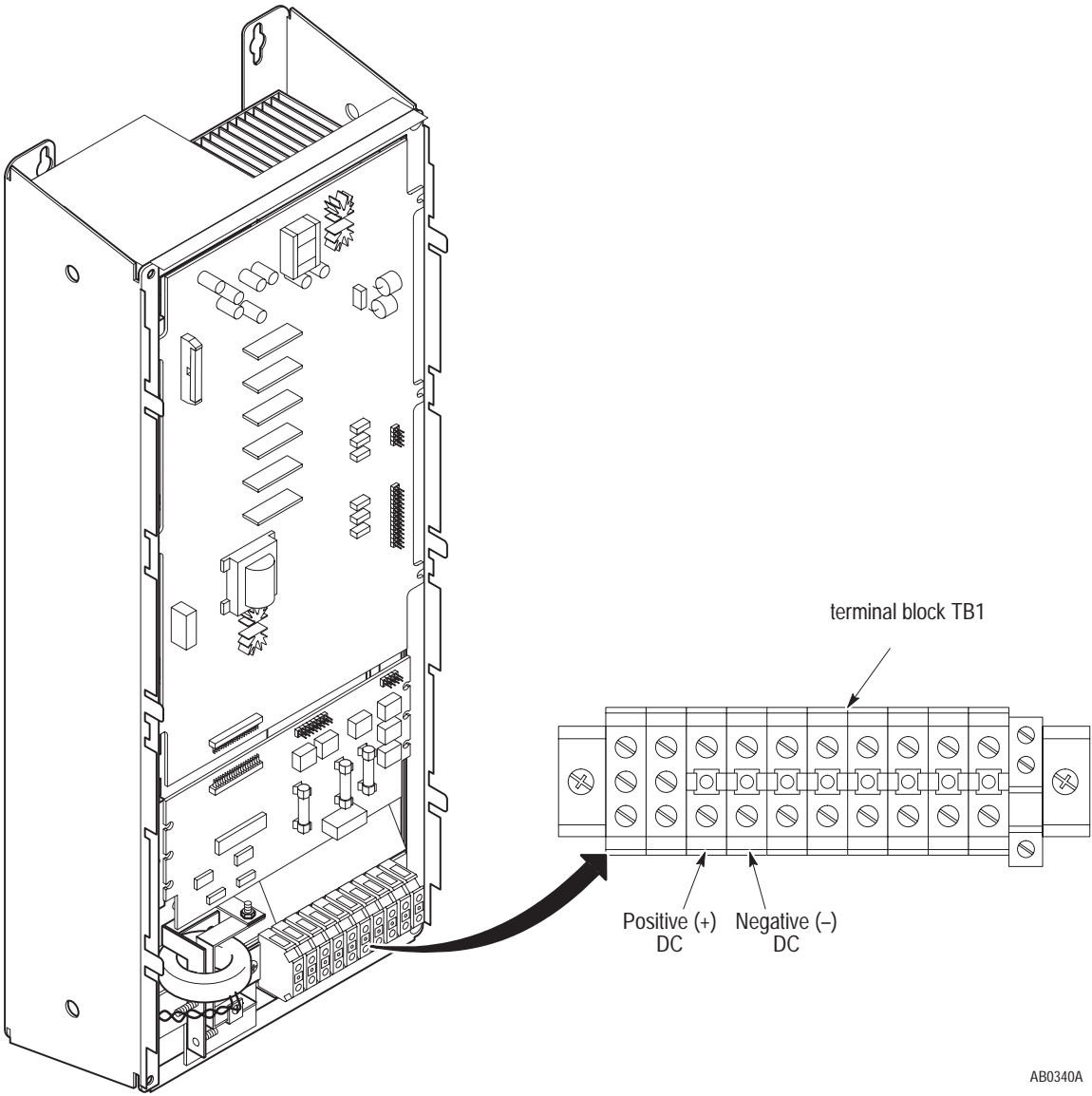
Meter (+) Lead	Meter (-) Lead	Nominal Diode Reading	Nominal Ohm Reading
1	A	Infinite	8 Meg
1	B	Infinite	8 Meg
1	C	Infinite	8 Meg
2	A	Infinite	8.5 Meg
2	B	Infinite	8.5 Meg
2	C	Infinite	8.5 Meg
3	A	Infinite	7 Meg
3	B	Infinite	7 Meg
3	C	Infinite	7 Meg
21	22	0.035	30
21	23	0.035	30
22	21	0.035	30
23	21	0.035	30
11	1	0.035	15
12	2	0.035	15
13	3	0.035	15

7. Replace the Input Rectifier if any meter readings are not as shown. Refer to Chapter 5 – Part Replacement Procedures, Input Rectifier SCR1.
8. If the Input Rectifier requires replacement, check the Power Modules for damage. Refer to Testing the Power Modules in this chapter.
9. Assemble the drive in reverse order of disassembly.

Test 2 – Testing the Bus Capacitor Bank

The Bus Capacitor Bank is located on the left side of the Main Chassis.

Figure 4.2
Bus Capacitor Bank Test



AB0340A



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Set your meter to test voltage.
5. Connect the negative (–) lead of your meter to the (–) DC Bus terminal on TB1 and the positive lead to the (+) DC Bus terminal. Refer to the following tables and former illustration for meter readings and terminal locations.



ATTENTION: Servicing energized industrial control equipment can be hazardous. Electrical shock, burns, or unintentional actuation of controlled industrial equipment may cause death or serious injury. Follow the safety-related practices of NFPA 70E, Electrical Safety for Employee Workplaces, when working on or near energized equipment. Do not work alone on energized equipment.

6. Apply power **AFTER** the meter is connected; otherwise, your meter will read zero volts. Expand readings for all input voltage ratings.

Table 4.B
Bus Capacitor Bank Test

Drive Rating	Input Volts	Meter Reading
A	200	280V DC +/-5%
	230	322V DC +/-5%
	240	336V DC +/-5%
B	380	535V DC +/-5%
	415	580V DC +/-5%
	480	675V DC +/-5%
C	500	700V DC +/-5%
	575	810V DC +/-5%
	600	850V DC +/-5%

7. If the voltage is out of tolerance, check the following:
 - An open condition at Input Rectifier SCR1
 - A voltage drop due to Bus Inductor L1 resistance
 - A voltage drop between Input Rectifier SCR1 and the bus capacitors due to loose or resistive wires or connections
 - Precharge circuit problems
8. If the above check does not reveal a problem, replace the Bus Capacitor Bank and Load-Sharing Resistors. Refer to Chapter 5 – Part Replacement Procedures, Bus Capacitor Bank.

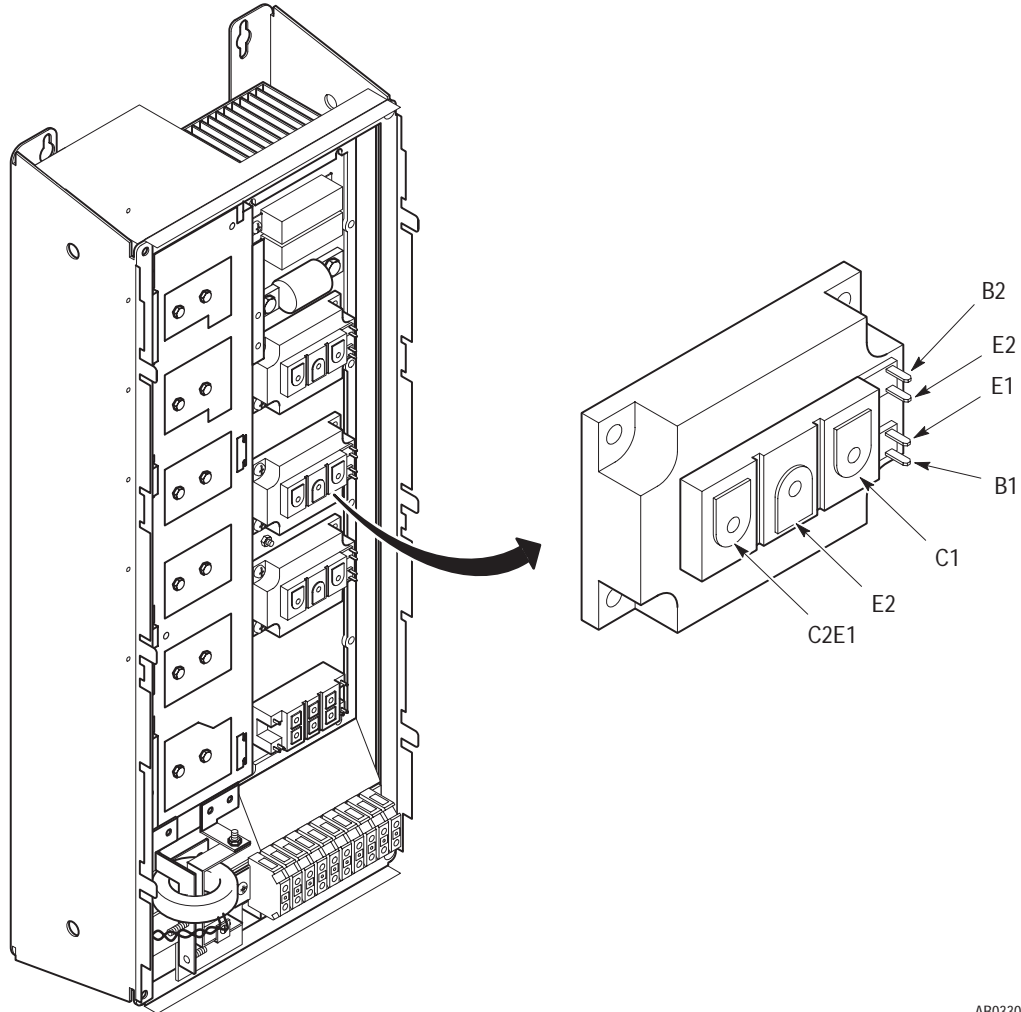


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Test 3 – Testing Power Modules PM1 – PM3

Power Modules PM1 – PM3 are located near the center of the heat sink.

Figure 4.3
Power Module Test



AB0330A



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Snubber Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Snubber Board.
5. Set your meter to test diodes.
6. Test Power Modules PM1, PM2, and PM3. The following table shows meter connections and ideal meter readings for those connections. Refer to the former illustration for meter connection locations.

Table 4.C
Power Modules PM1 – PM3

Motor (+) Lead	Meter (-) Lead	Nominal Meter Reading
C2E1	E2	Infinite
E2	C2E1	0.36
C1	C2E1	Infinite
C2E1	C1	0.36
B1	E1	Infinite
B2	E2	Infinite

7. Replace Power Module PM1, PM2, or PM3 if meter readings are not as shown. Refer to Chapter 5 – Part Replacement Procedures, Power Modules PM1 – PM3.
8. If one or more Power Modules is replaced, test the Gate Driver Board. Refer to Testing the Gate Driver Board in this chapter.
9. Assemble the drive in reverse order of disassembly.

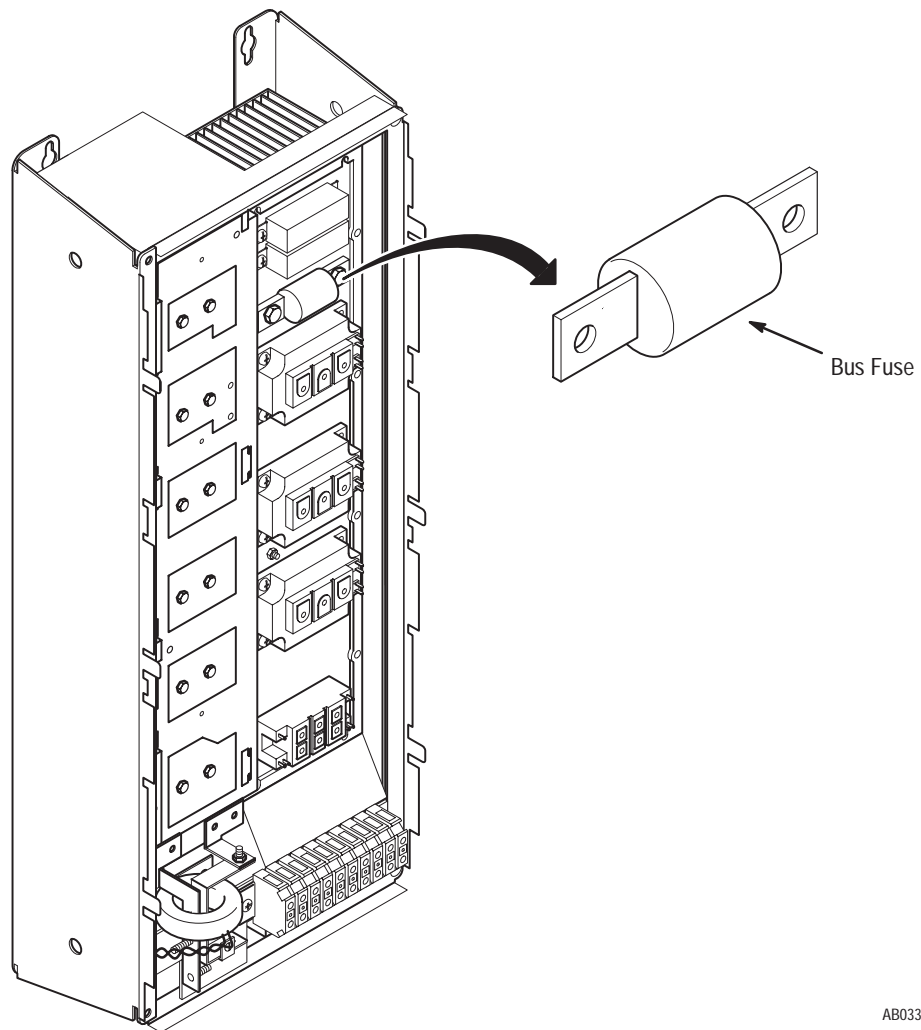


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Test 4 – Testing Bus Fuse F1

Bus Fuse F1 is located at the top of the heat sink.

Figure 4.4
Bus Fuse F1 Test



AB0331A



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Gate Driver Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Gate Driver Board.
5. Set your meter to test resistance.
6. Check for an open condition across Bus Fuse F1.
7. If the fuse shows an open condition, replace the fuse. Refer to Chapter 5 – Part Replacement Procedures, Bus Fuse F1.
8. Assemble the drive in reverse order of disassembly.

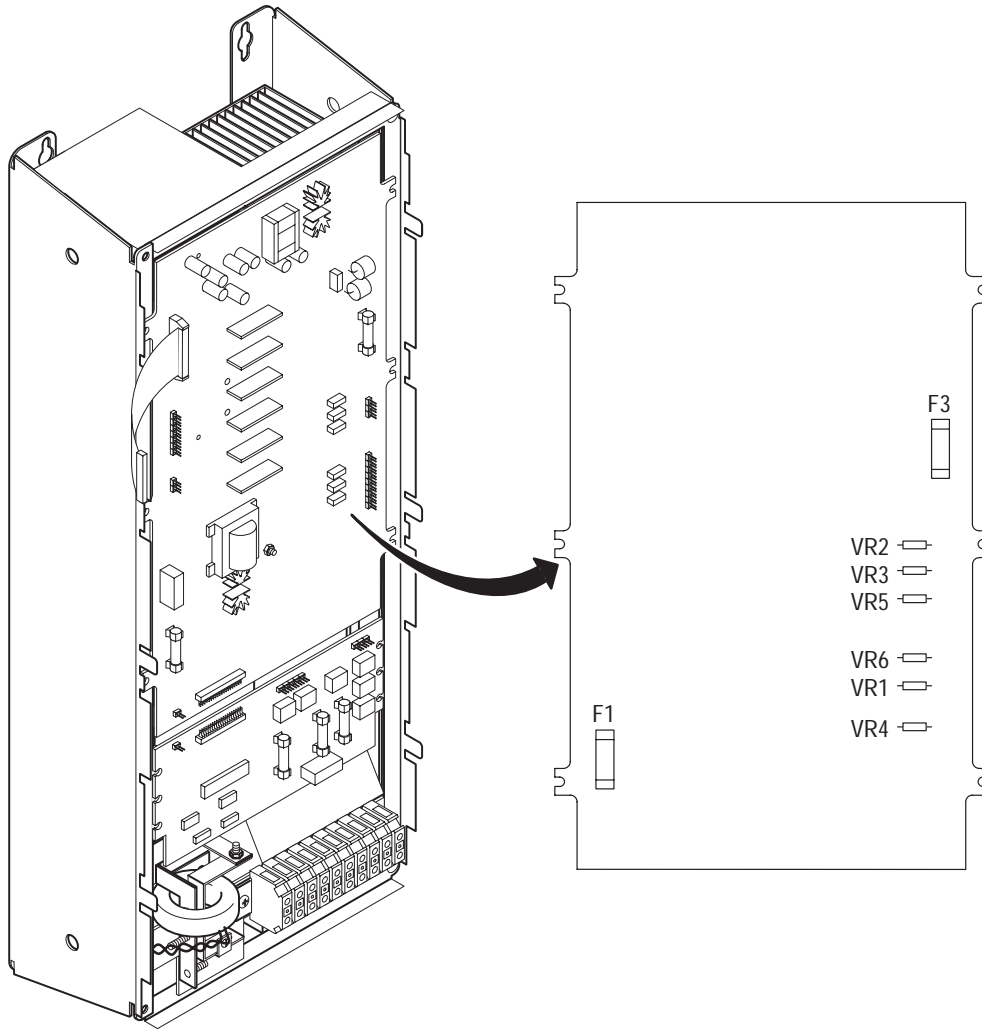


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Test 5 – Testing the Gate Driver Board

The Gate Driver Board is located between the Main Control Board and the Main Chassis. If one or more Power Modules has been replaced, you must test the Gate Driver Board.

Figure 4.5
Gate Driver Board Test



AB0339A



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Main Control Board Mounting Plate. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Main Control Board Mounting Plate.
5. Unplug the connectors from the Gate Driver Board.
6. Set your meter to test resistance.
7. Test Fuses F1 and F3 for an open condition. Replace the Gate Driver Board if either fuse shows an open condition.
8. Set your meter to test diodes.
9. Test VR1 – VR6. The following table shows meter connections at the components and ideal meter readings for those connections. Refer to the former illustration for meter connection locations.

Table 4.D
Gate Driver Board Test

Component	Meter (+) Lead	Meter (-) Lead	Nominal Meter Reading
VR1 – VR6	+	–	1.06
	–	+	1.8

Important: Typical malfunction is shorted in both directions.

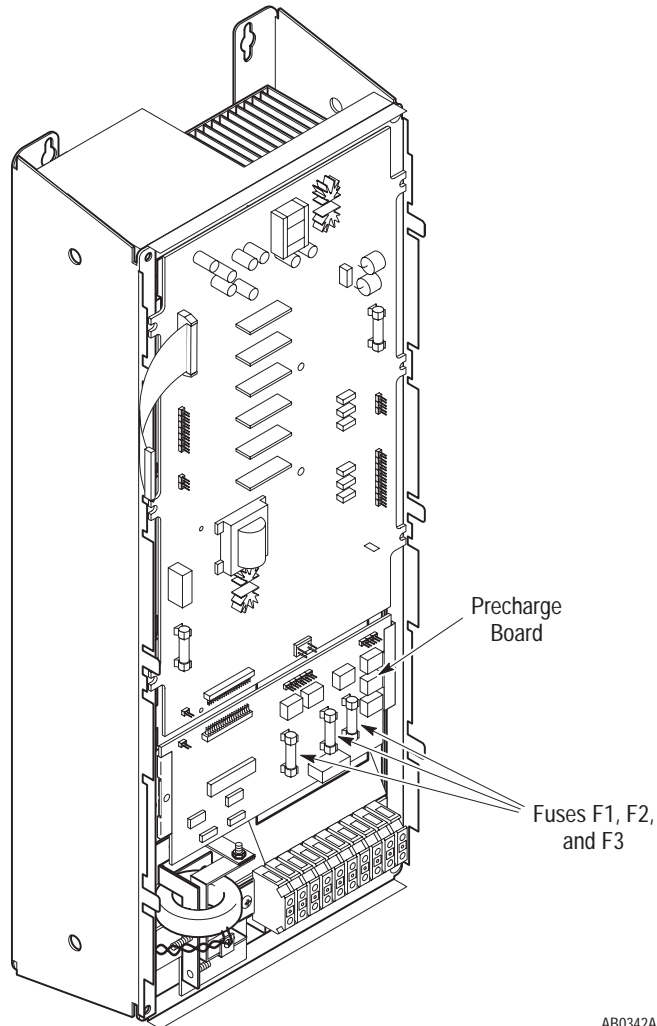
10. Replace the Gate Driver Board if your readings do not match the table readings. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Gate Driver Board.
11. Assemble the drive in reverse order of disassembly.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Test 6 – Testing the Precharge Board

Figure 4.6
Precharge Board Test



AB0342A



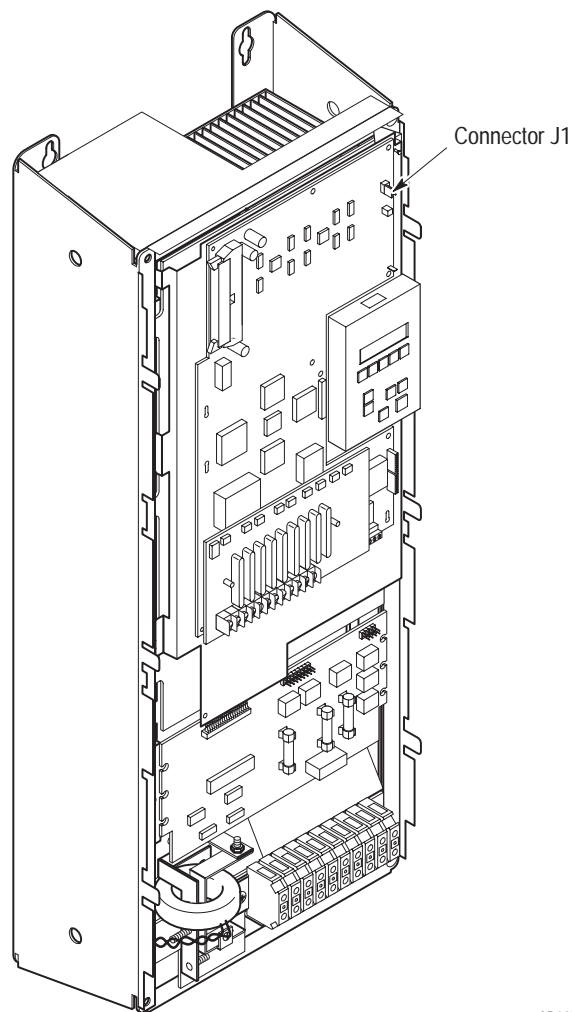
ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and -DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Set your meter to measure resistance.
5. Test fuses F1, F2, and F3 for open conditions.
6. Replace the Precharge Board if any fuse shows an open condition.

Test 7 – Testing the Thermistor

Figure 4.7
Thermistor Test



AB0856A



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Disconnect the Thermistor from Connector J1 on the Main Control Board.
5. Allow the drive to cool down to room temperature.
6. Set your meter to test resistance.
7. Measure the resistance across the Thermistor wires. Nominal meter reading should be 100K ohms at room temperature.
8. If the Thermistor reading measures other than the nominal value, replace the Thermistor. Refer to Chapter 5 – Part Replacement Procedures, Thermistor.

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Part Replacement Procedures

Chapter Objective

This chapter describes procedures required to replace drive components. This chapter references Chapter 3 – Disassembly and Access Procedures for basic drive component access.

Part Replacement Overview

The part replacement procedures in this chapter assume that the drive you are servicing either has no enclosure or that the enclosure is open. For more information on opening the Drive Enclosure, refer to Chapter 3 – Disassembly and Access Procedures, Opening the Drive Enclosure.

Safety Precautions



ATTENTION: Some printed circuit boards and drive components may contain hazardous voltage levels. Remove power before you disconnect or reconnect wires and before you remove or replace fuses and circuit boards. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.

Electrostatic Discharge Precautions



ATTENTION: This assembly contains parts and sub-assemblies that are sensitive to electrostatic discharge. Static control precautions are required when servicing this assembly. Component damage may result if you ignore electrostatic discharge control procedures. If you are not familiar with static control procedures, reference Rockwell Automation Publication 8000-4.5.2, Guarding Against Electrostatic Discharge, or any other applicable ESD protection handbook.

Electrostatic discharge generated by static electricity can damage the complementary metallic oxide semiconductor devices on various drive boards. It is recommended that you perform these procedures to guard against this type of damage when circuit boards are removed or installed:

- Wear a wrist-type grounding strap that is grounded to the chassis.
- Attach the wrist strap before removing the new circuit board from the conductive packet.
- Remove boards from the drive and immediately insert them into their conductive packets.

Tools

You need the following tools to disassemble and assemble the drive:

- Pliers
- Phillips screwdriver
- Standard screwdriver
- 5/16-inch or 8 mm socket
- 11/16-inch or 17 mm socket
- 5/16-inch or 8 mm open-end wrench
- Torque wrench, metered in lb-in. or N-m

Major Component Replacement

This section explains in detail how to replace the following drive components:

- Ground Sense CT
- Bus Fuse F1
- Thermistor
- Power Modules PM1 – PM3
- Input Rectifier SCR1
- Fan
- DC Bus Inductor L1
- Bus Capacitors

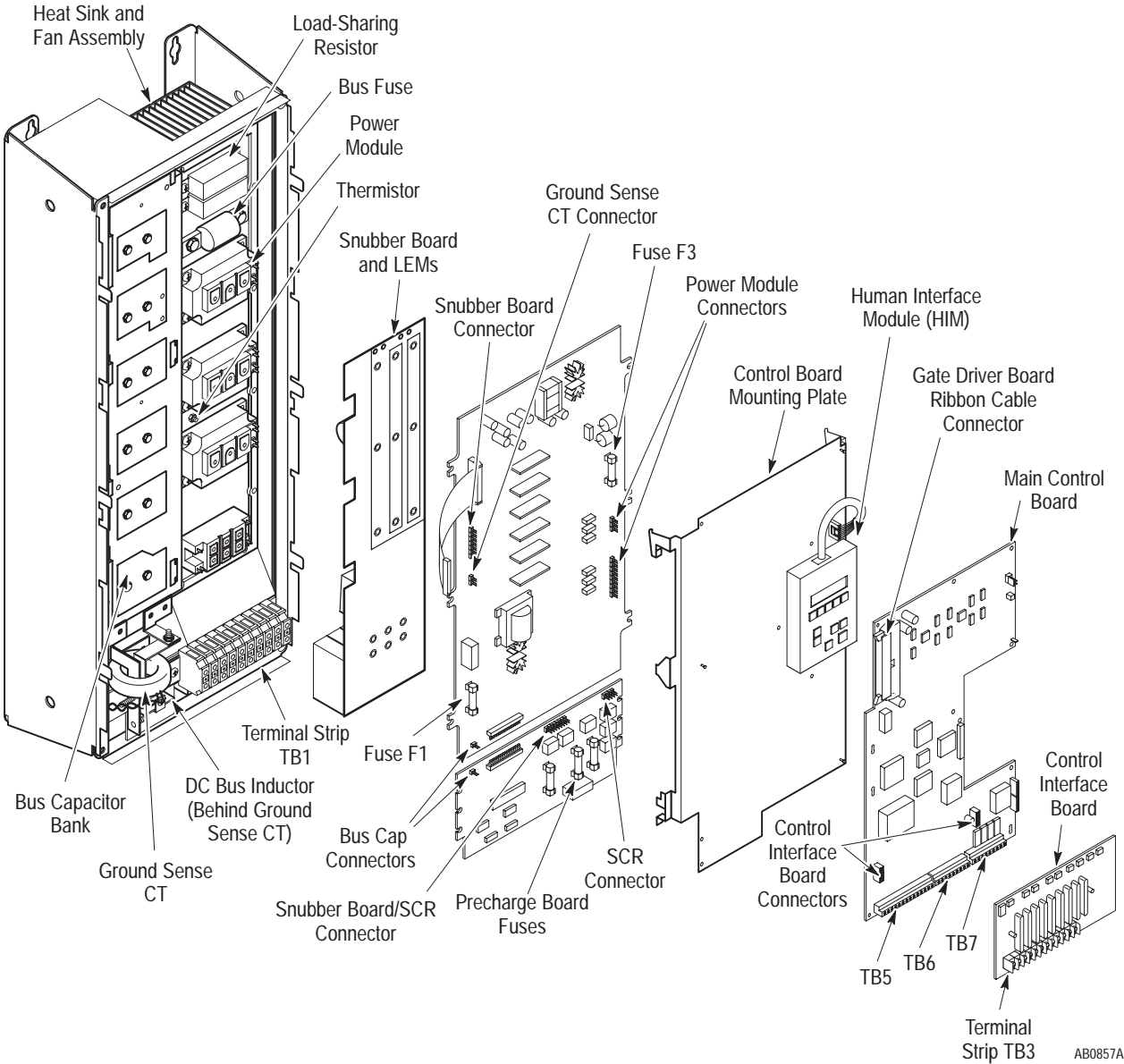
For Gate Driver Board, Main Control Board, Precharge Board, and L Option Board installation and removal procedures, refer to Chapter 3.

Detailed Product Identification

Rockwell Automation Adjustable Frequency AC Drives are modular by design to enhance troubleshooting and spare parts replacement, thereby helping reduce production down-time.

The following illustration calls out the main components of a typical drive. Component designs vary slightly among the different drive ratings, but component locations are identical.

Figure 5.1
Main Drive Components

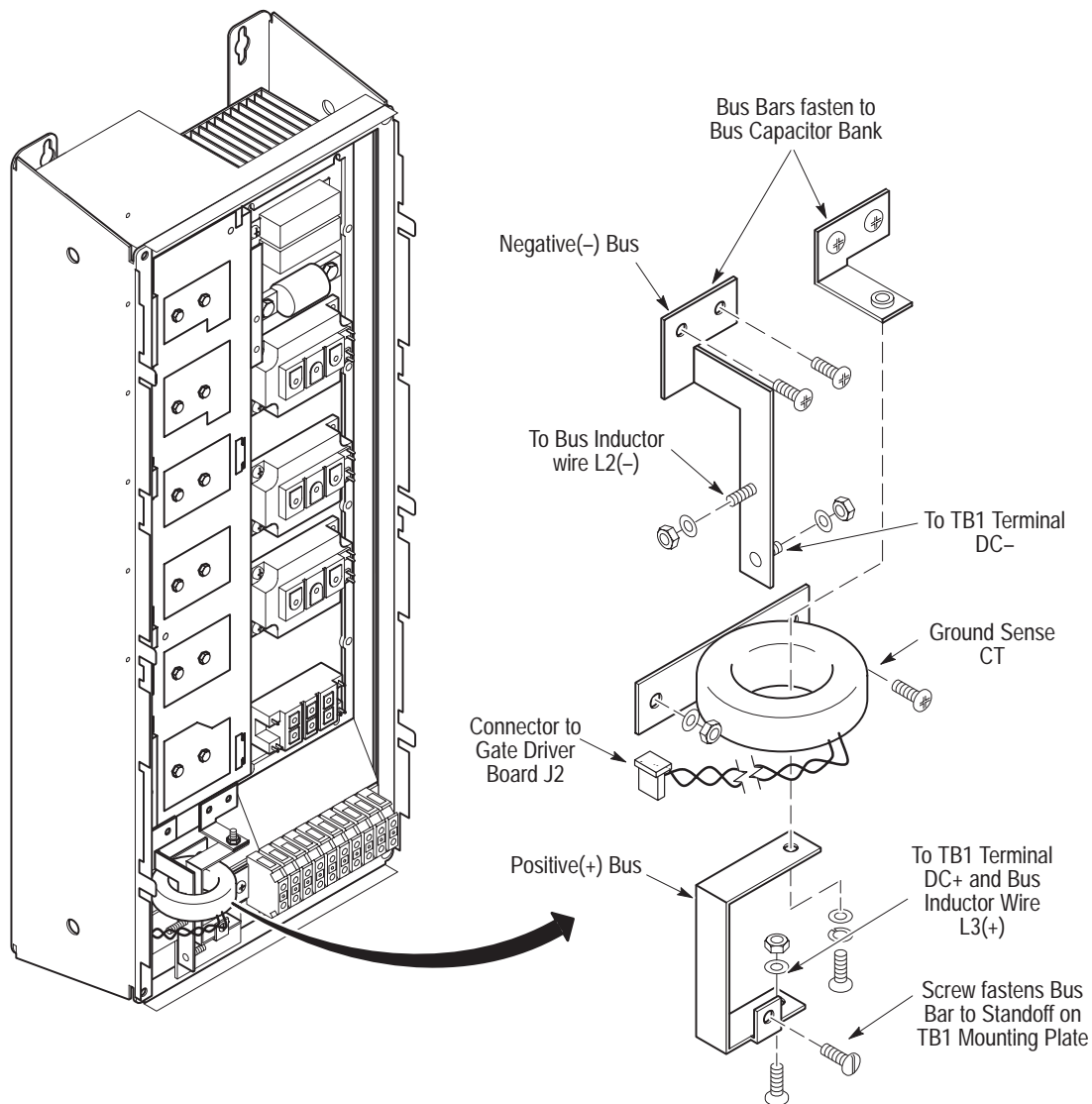


AB0857A

Ground Sense CT

The Ground Sense CT is located in the lower left corner of the drive.

Figure 5.2
Ground Sense CT



AB0348A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and -DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Main Control Board Mounting Plate. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Main Control Board Mounting Plate.
5. Remove the Precharge Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Precharge Board.
6. Disconnect the Ground Sense CT from Gate Driver Board connector J2.
7. Remove the following from the Ground Sense CT Bus Bars:
 - DC Bus Inductor wire L3
 - DC Bus Inductor wire L2. Note that the positive (+) and negative (-) DC wires from TB1 do not need to be removed from the bus bars.
 - The screw fastening the positive (+) bus bar to the standoff
 - The screw and nut assembly fastening the positive (+) bus bar to the bus bar extension from Bus Capacitor Bank terminal E1
 - The two screws fastening the negative (-) bus bar to the Bus Capacitor Bank terminal E2
8. Remove the nut fastening the Ground Sense CT to the Main Chassis.
9. Remove the screw fastening the Ground Sense CT to the TB1 Mounting Plate.

Installation

1. Place the bus bars through the center of the Ground Sense CT. Refer to Figure 5.2.
2. Install the Ground Sense CT in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.

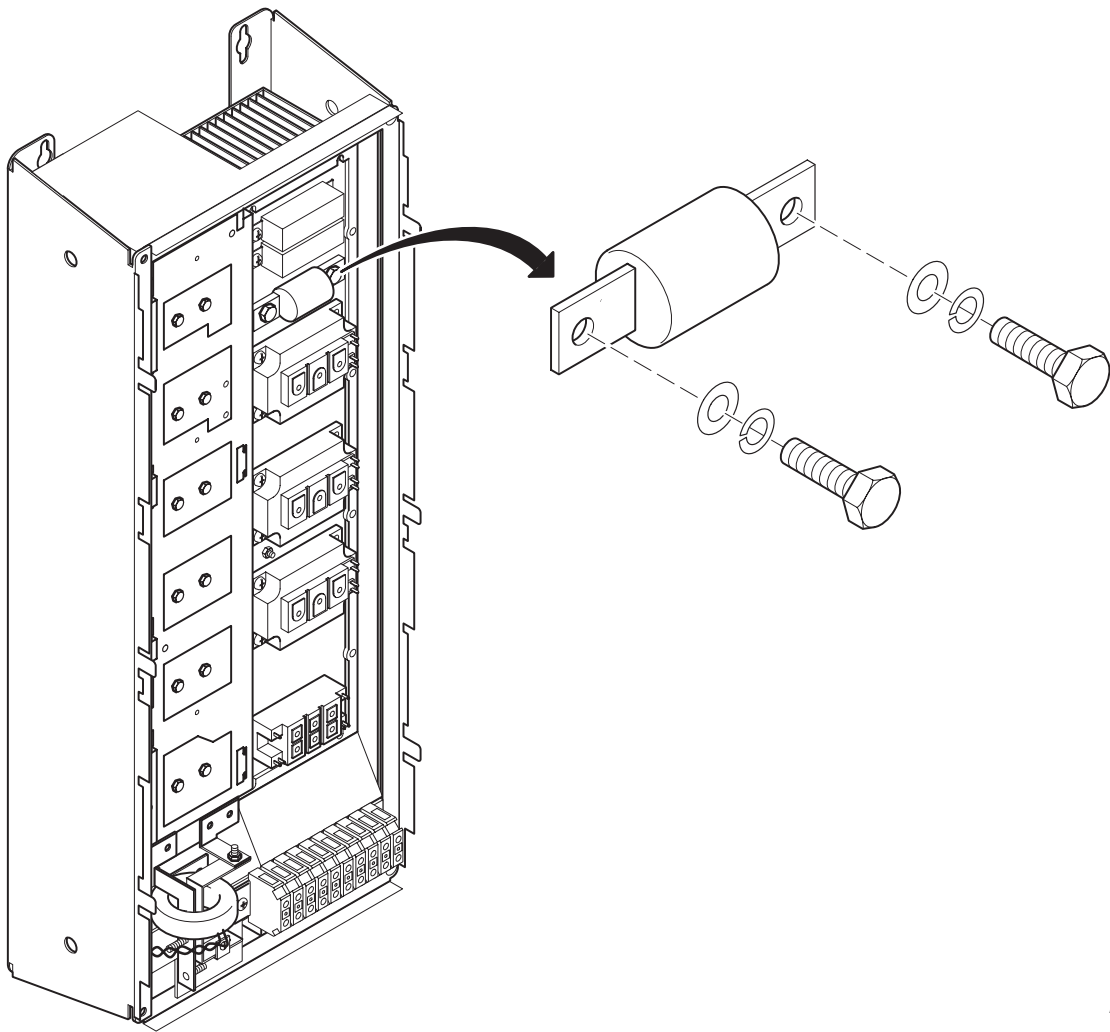


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Bus Fuse F1

Bus Fuse F1 is located at the top of the heat sink.

Figure 5.3
Bus Fuse F1



AB0332A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Gate Driver Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Gate Driver Board.
5. Remove the two bolts fastening the fuse to the drive.

Installation

Install Fuse F1 in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.

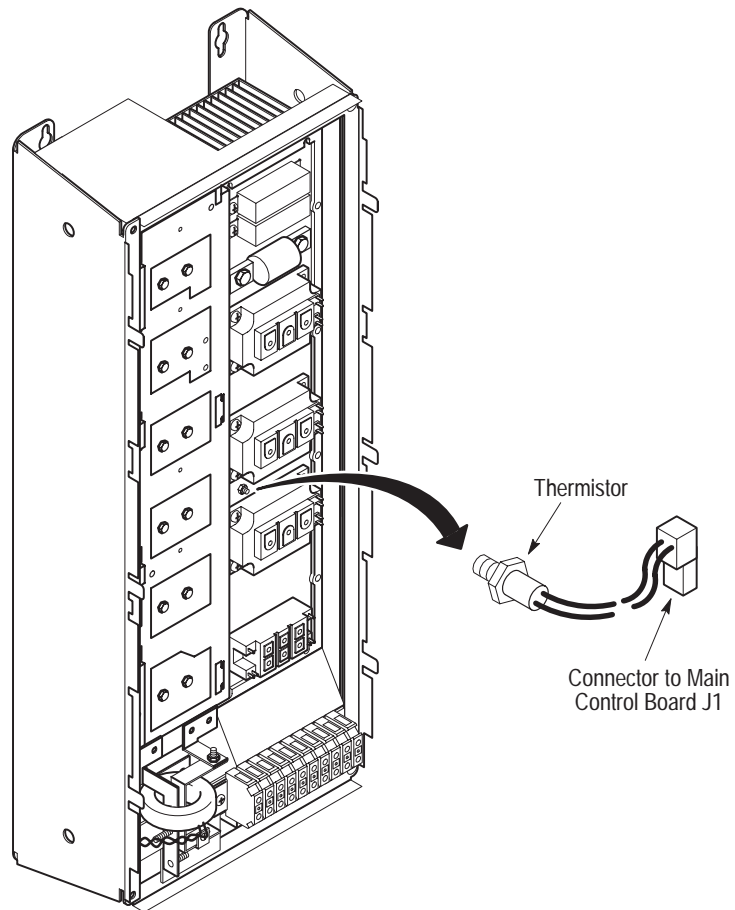


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Thermistor

The Thermistor is located on the heat sink, between the Power Modules and the Input Rectifier.

Figure 5.4
Thermistor



Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and -DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Snubber Board from the drive. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Snubber Board.
5. Unscrew the Thermistor from the heat sink.

Installation

Install the Thermistor in reverse order of removal.

Important: When fastening the Thermistor to the heat sink, hand-tighten the Thermistor to avoid damaging the porcelain Thermistor body.

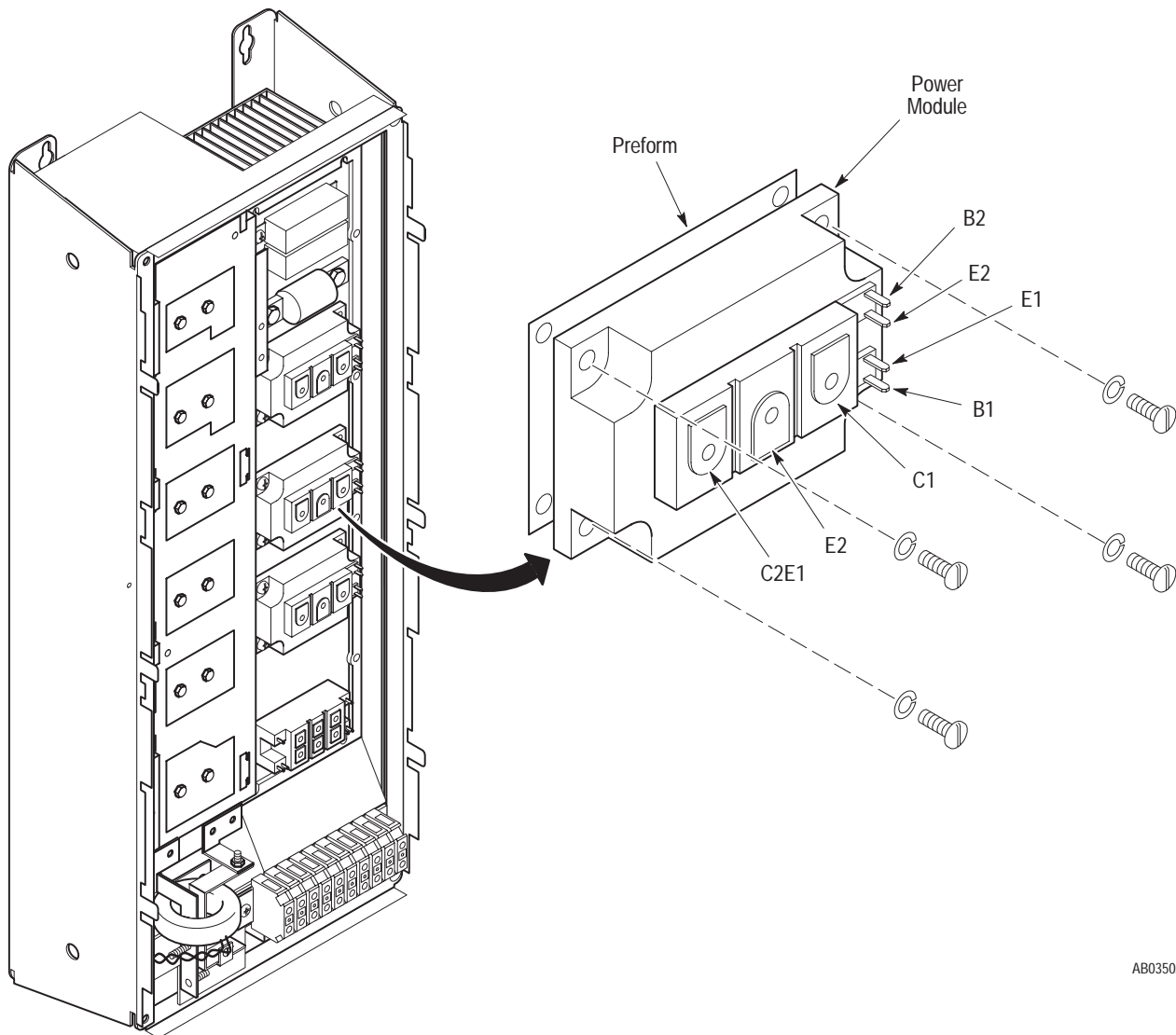


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Power Modules PM1 – PM3

Power Modules PM1 – PM3 are located on the heat sink, behind the Snubber Board.

Figure 5.5
Power Modules



AB0350A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and -DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Snubber Board from the drive. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Snubber Board.
5. Remove all wires connected to the Power Module terminals.
6. Remove the screws fastening the Power Module to the heat sink.

Installation

1. Clean all surfaces between the Power Module and the heat sink using a soft, clean cloth.
2. Replace the Preform between the Power Module and the heat sink.
3. Install the Power Module in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.

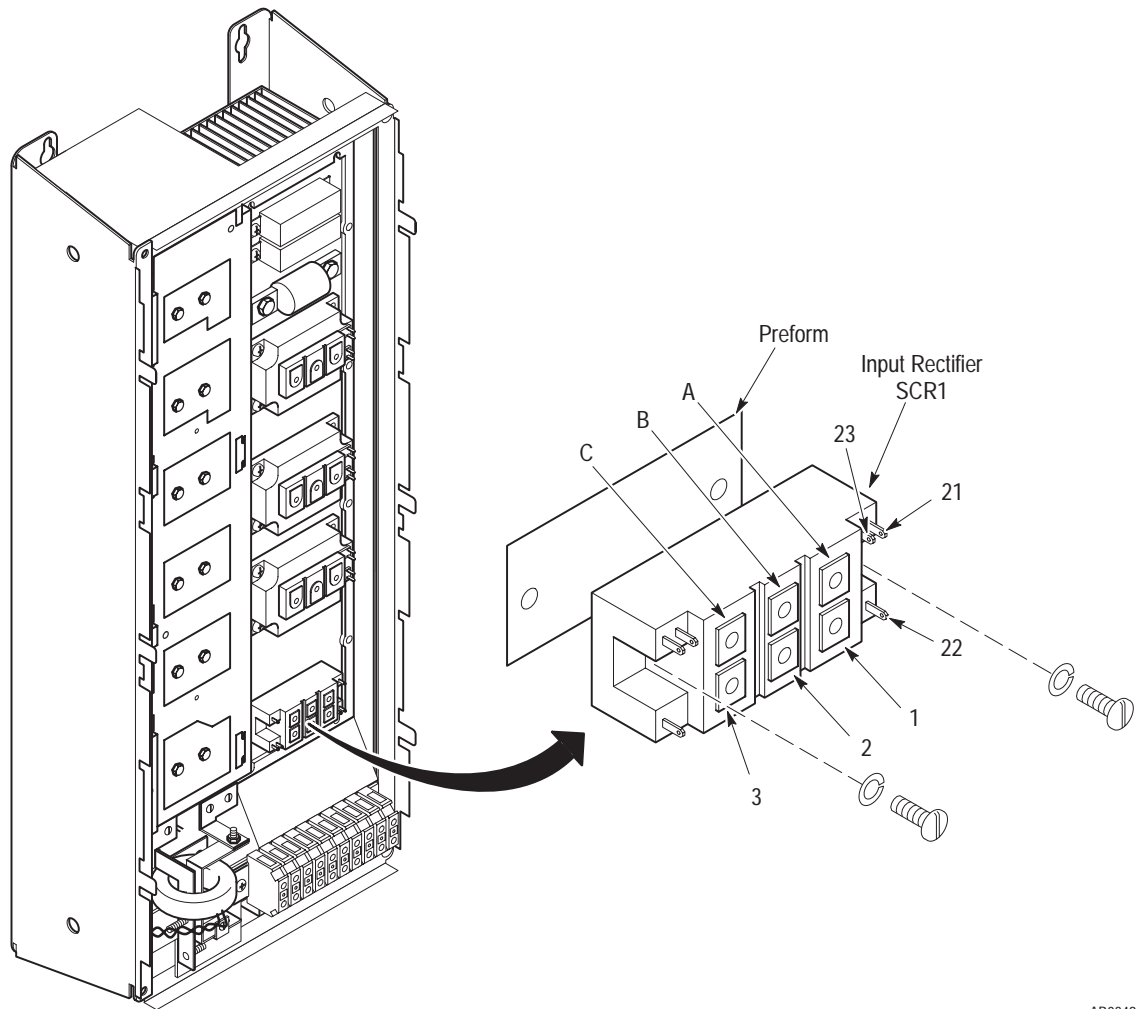


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Input Rectifier SCR1

The Input Rectifier SCR1 is located on the heat sink, behind the Snubber Board.

Figure 5.6
Input Rectifier SCR1



AB0349B

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and -DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and -DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Snubber Board from the drive. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Snubber Board.
5. Remove all wires from the Input Rectifier.
6. Remove the screws fastening the Input Rectifier to the heat sink.

Installation

1. Clean all surfaces between the Input Rectifier and the heat sink using a soft, clean cloth.
2. Replace the Preform between the Input Rectifier and the heat sink.
3. Install the Input Rectifier in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.

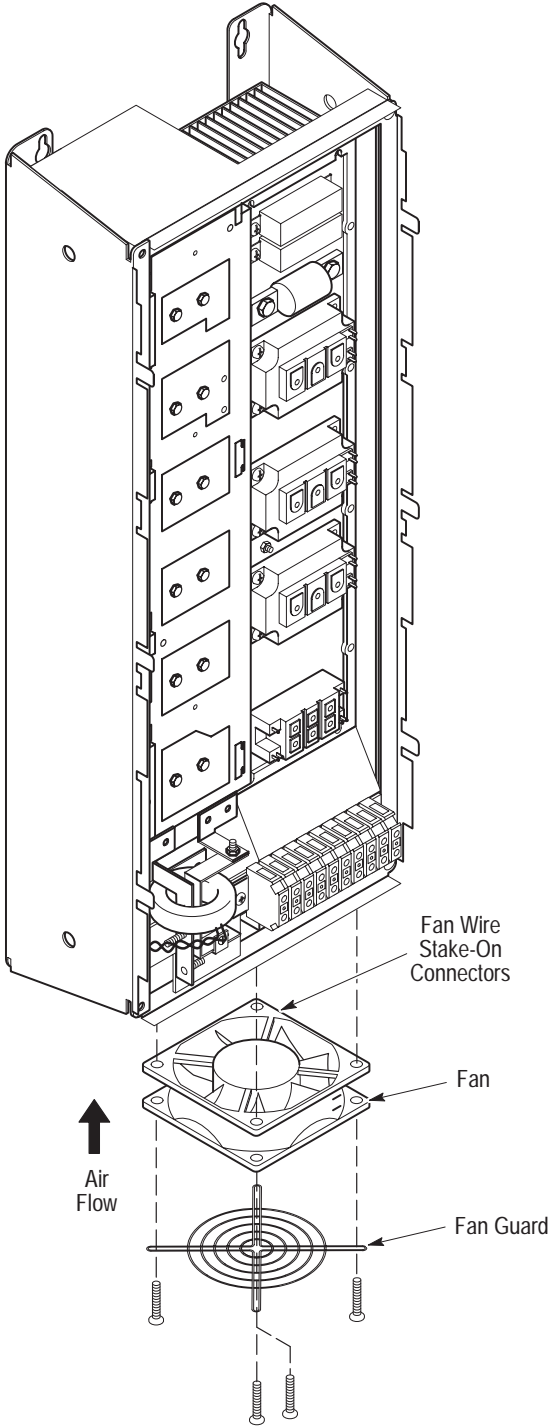


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

Fan

The Fan is located behind and on the bottom of the heat sink.

Figure 5.7
Fan



AB0323A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the four screws fastening the Fan assembly to the bottom of the Drive.
5. Remove the wires from the Fan stake-on connectors.

Installation

Install the fan in reverse order of removal.

Important: When fastening the Fan to the cover plate, position the air flow arrow, located on the top of the fan near the connectors, so it points to the top of the drive. Position the Fan connectors to the front, away from DC Bus Inductor L1. Connect the red wire to the positive fan terminal and the black wire to the negative terminal.

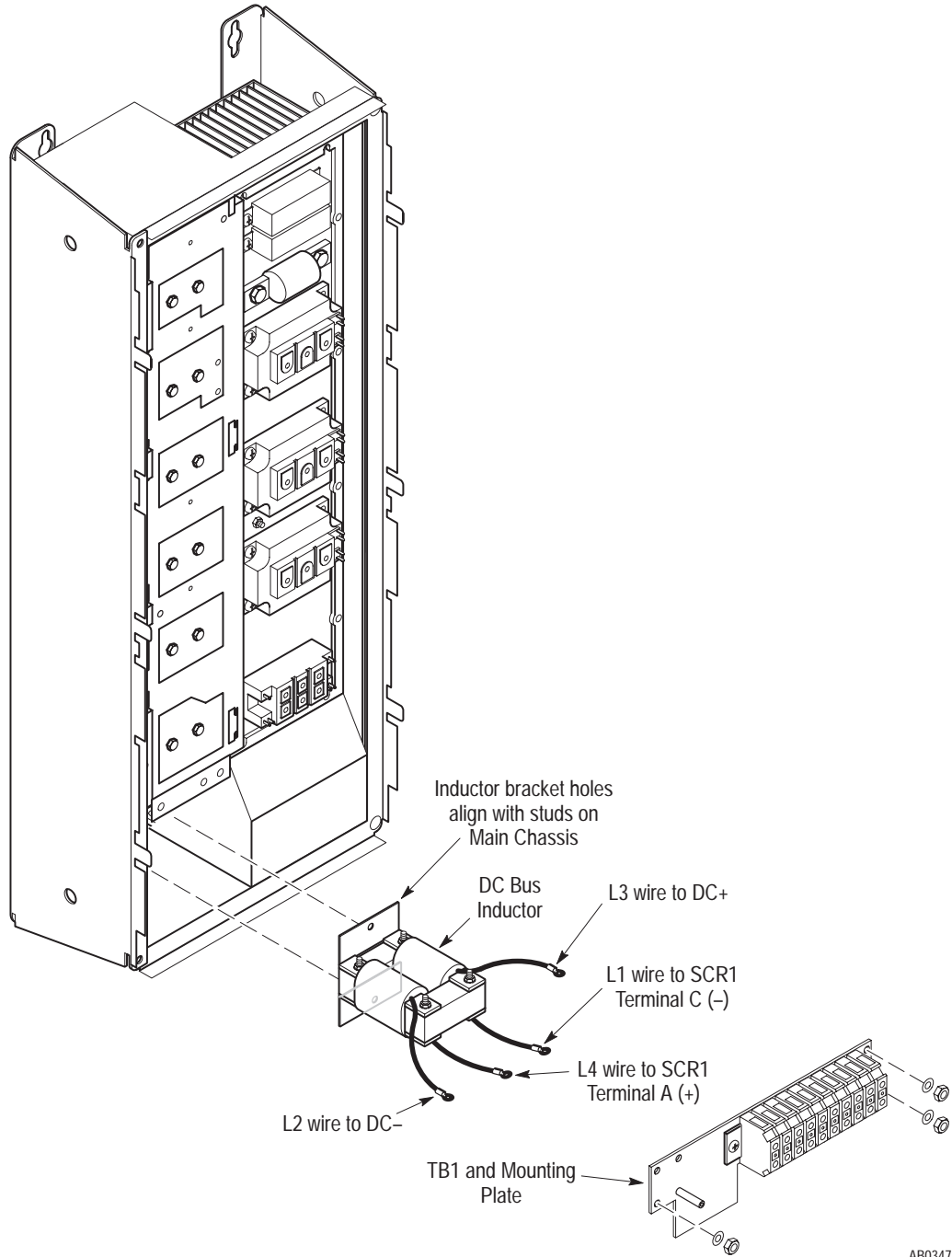


ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.

DC Bus Inductor L1

The DC Bus Inductor L1 is located on the lower left corner of the drive, behind the Ground Sense CT.

Figure 5.8
DC Bus Inductor L1



AB0347A

Removal



ATTENTION: Disconnect and lock out power from the drive before disassembling the drive. Failure to disconnect power may result in death or serious injury. Verify bus voltage by measuring the voltage between +DC and –DC on terminal block TB1. Do not attempt to service the drive until the bus voltage has discharged to zero volts.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

Access the Main Chassis:

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and –DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Precharge Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Precharge Board.
5. Remove the Gate Driver Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Gate Driver Board.
6. Remove the Bus Capacitor Bank. Refer to Bus Capacitor Bank in this chapter.

Remove the TB1 Mounting Plate and DC Bus Inductor L1:

1. Remove the following from the drive-connection side of TB1:
 - Ground wires
 - Wires at terminals U, V, and W (T1, T2, and T3)

2. Remove the following from the Ground Sense CT Bus Bars:
 - L3 wire from DC Bus Inductor L1.
 - L2 wire from DC Bus Inductor L1. Note that the positive (+) and negative (-) DC wires from TB1 may remain connected to the bus bars.
3. Remove the following from the Snubber Board:
 - DC Bus Inductor wire L1 from SCR1 terminal C (-).
 - DC Bus Inductor wire L4 from SCR1 terminal A (+).
 - TB1 terminal wire R from SCR1 terminal 3.
 - TB1 terminal wire S from SCR1 terminal 2.
 - TB1 terminal wire T from SCR1 terminal 1.
4. Remove the nuts fastening the TB1 Mounting Plate to the drive to remove the plate from the drive.
5. Pull the Bus Inductor straight out of the drive to remove the inductor from the drive.



ATTENTION: Note the position of the bracket toward the lower end of the inductor. The tab on the bottom right of the inductor bracket fits into a hole on the TB1 mounting plate. Correctly position the replacement inductor brackets to prevent damage to the equipment.



ATTENTION: Holes in the inductor bracket align with pins located on the inside-back of the Main Chassis. Correctly align the holes on the replacement inductor bracket with the chassis pins to prevent damage to the equipment.

Installation

1. Lower the inductor into the Main Chassis, aligning the hole in the bottom inductor bracket with the peg on the chassis.
2. Install DC Bus Inductor L1 in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.



ATTENTION: Replace all guards and insulators before applying power to the drive. Failure to replace guards may result in death or serious injury.



ATTENTION: Wear a wrist-type grounding strap when servicing 1336 IMPACT drives. Failure to protect drive components against ESD may damage drive components. Refer to Electrostatic Discharge Precautions at the beginning of this chapter.

Important: Before you remove connections and wires from the drive components, mark the connections and wires to correspond with their component connections and terminals to prevent incorrect wiring during assembly.

Access the Main Chassis:

1. Remove power from the drive.
2. Check for zero volts at TB1 terminals +DC and -DC.
3. Check for absence of control voltage at:
 - TB10
 - TB11
 - L Option Board (if used)
4. Remove the Precharge Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Precharge Board.
5. Remove the Gate Driver Board. Refer to Chapter 3 – Disassembly and Access Procedures, Removing the Gate Driver Board.

Remove the Bus Capacitor Bank:

1. Remove the Load-Sharing Resistor wires from the Bus Capacitor Bank stake-on connectors.
2. Remove the four screws fastening the Snubber Board Bus Bars to the Bus Capacitor Bank terminals E10 (+) and E11 (-).
3. Loosen the screws fastening the Snubber Board negative Bus Bar to the Snubber Board.



ATTENTION: These screws are fastened with nuts located under the Snubber Board. Removing the screws requires removing the Snubber Board to fasten the bus bar to the Snubber Board.

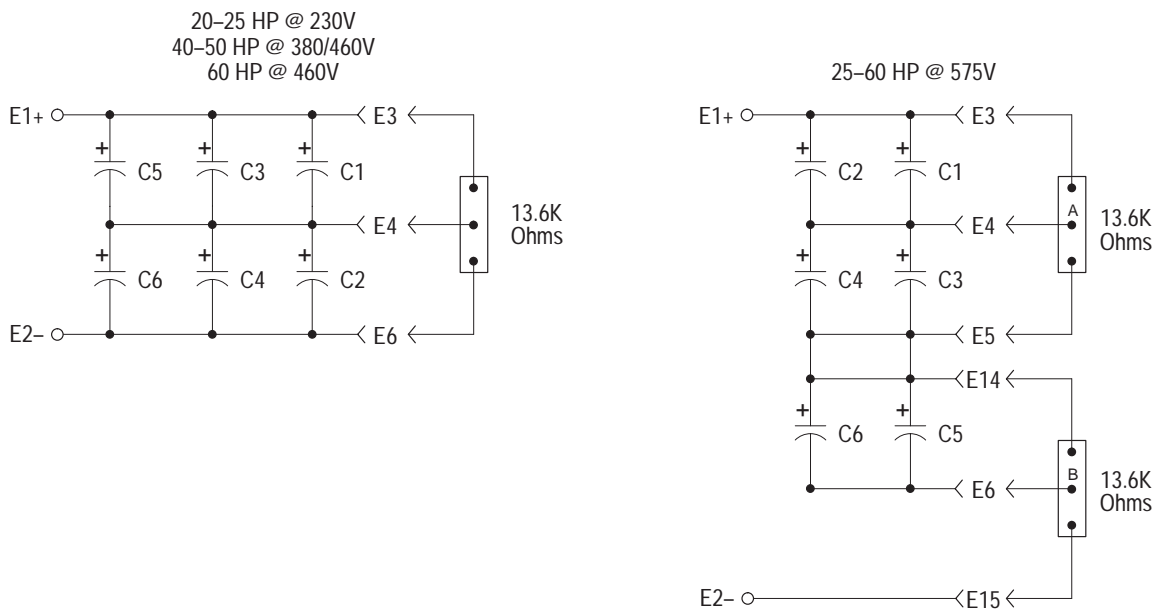
4. Remove the four screws fastening the Ground Sense CT Bus Bars to Bus Capacitor Bank terminals E1 (+) and E2 (-).
5. Remove the three nuts and washers fastening the left side of the Bus Capacitor Bank to the Main Chassis.

6. Slide the Bus Capacitor Bank to the right to unlock the right side of the capacitor frame from the tabs located on the Main Chassis.
7. Pull the Bus Capacitor Bank away from the drive to remove the capacitors from the drive.

Installation

1. Fasten the capacitor assembly in reverse order of removal. Refer to Table 3.A – Fastener Torque Specifications.
2. Connect the Load-Sharing Resistors to the Bus Capacitors according to the following diagram.

Figure 5.10
Load-Sharing Resistor Connections to Bus Capacitors



ATTENTION: The Capacitor Bus PCB must connect a positive (+) capacitor terminal to a negative (-) capacitor terminal. Capacitors not connected correctly will explode and cause death or serious injury.

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Replacement Parts List

Chapter Objectives

This chapter illustrates and lists replacement parts for the 1336 IMPACT Drives rated A020 – A030, B040, B050, BX040, BX060, and C025 – C060 and describes replacement parts ordering procedures.

The following illustration and table show you parts, part names, locations, and chapters for replacement procedures.

Ordering Replacement Parts

For your convenience, the Rockwell Automation Drives Division and the Rockwell Automation Support Division provide efficient and convenient repair and exchange for eligible equipment.

A product service report number is required to return any equipment for repair. Your local Rockwell Automation distributor or area sales and support office can provide you with a product service report number.

You should return equipment to be repaired to the area sales and support center nearest you. Reference the product service report number on the carton and packing slip. Include:

- Your company name
- Your company address
- The repair purchase order number
- A brief description of the problem

Contact your local Rockwell Automation distributor or sales office for a complete listing of area sales and support centers near you.

For parts catalog numbers, refer to the 1336 IMPACT Spare Parts Pricing publication included with your drive documentation set. See next page for more information.

Spare Parts Information

Current 1336 IMPACT drive spare parts information including recommended parts, catalog numbers and pricing can be obtained from the following sources:

Allen-Bradley home page on the World Wide Web at

<http://www.ab.com>

then select . . .

“Drives and Motors” *followed by . . .*

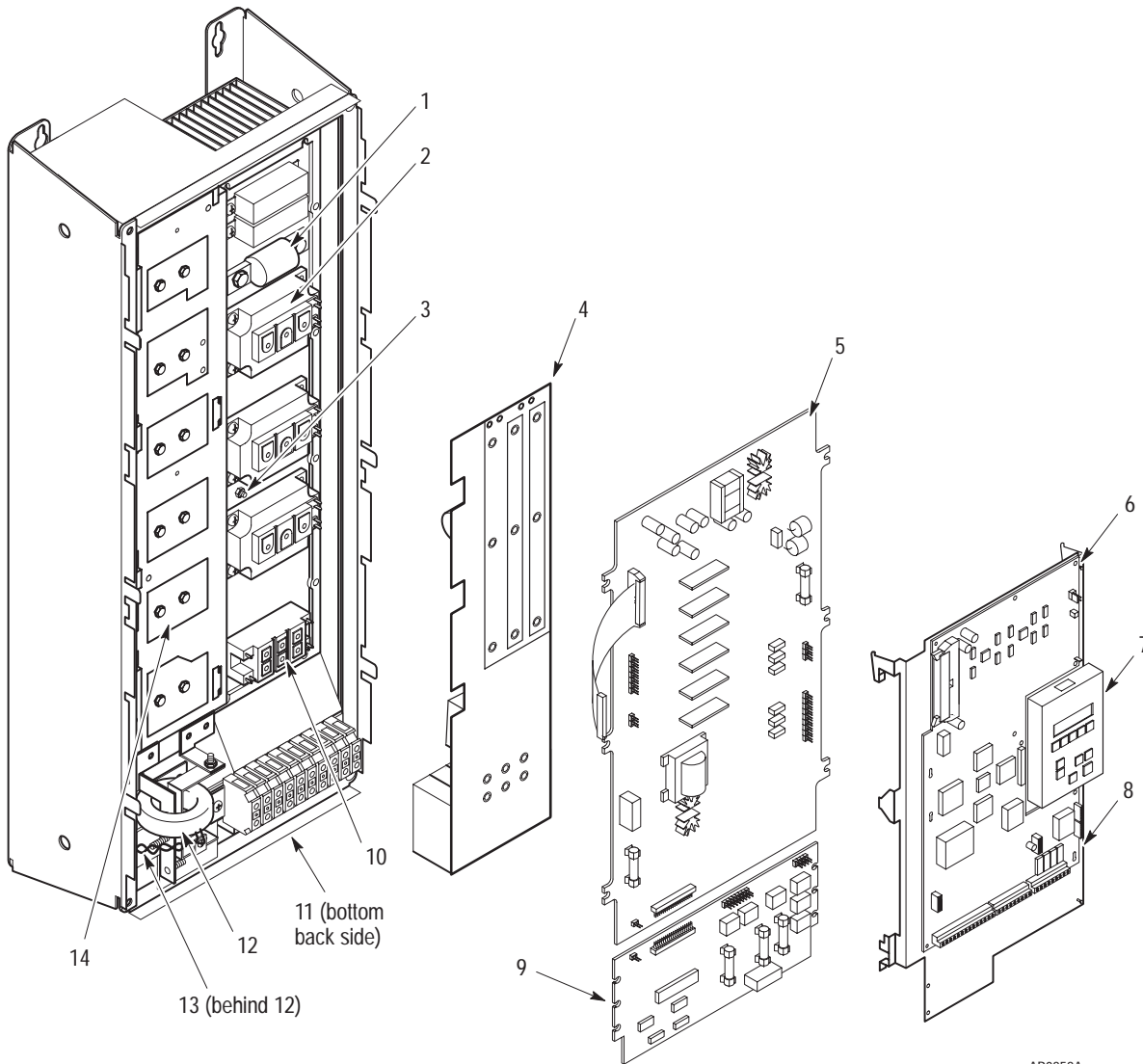
“1336 IMPACT” from the Product Directory *and . . .*

“Technical Support . . .”

Select "Parts List"

Replacement Parts Listing

Figure 6.1
Parts for A020 – A030, B040, B050, BX040, BX060, and
C025 – C060 Drives



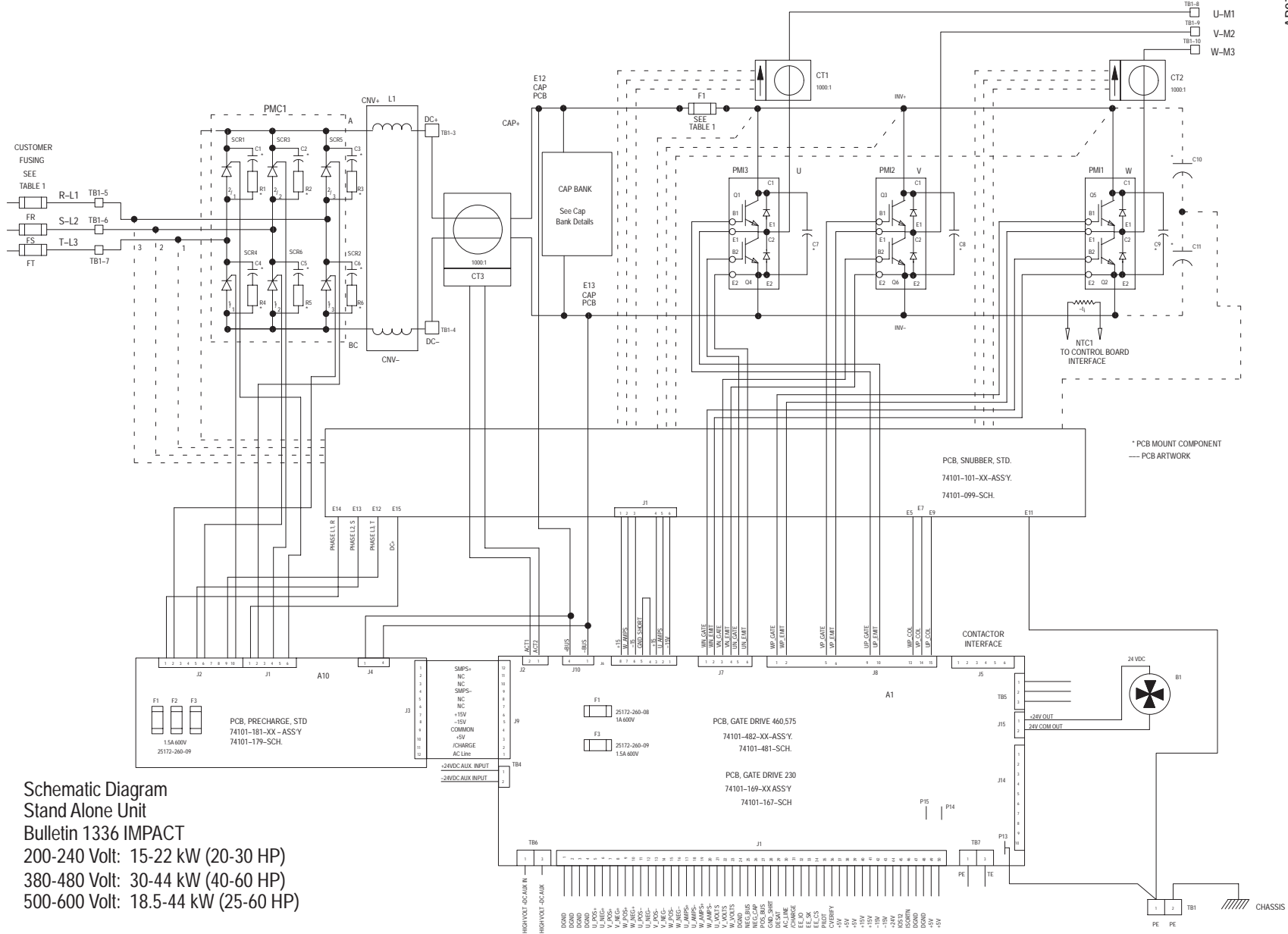
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Table 6.A
Replacement Parts for A020 – A030, B040, B050, BX040,
BX060, and C025 – C060 Drives

Callout	Symbol	Description	Location	Replacement Procedures
1	F1	Bus Fuse	Heat Sink	Chapter 5, Bus Fuse F1
2	Q1-3	Transistor	Heat Sink	Chapter 5, Transistor Modules
3	ST	Thermistor	Heat Sink	Chapter 5, Thermistor
4	SNUBBER BOARD	Snubber Board	—	Chapter 3, Removing the Snubber Board
5	BASEDR/PWRSPLY	Gate Driver/Power Supply PCB	—	Chapter 3, Removing the Gate Driver Board
6	LOCAL DIS	Human Interface Module	Main Control Board Mounting Plate	Chapter 1, Removing the HIM
7	MAIN CTL	Main Control PCB	Main Control Board	Chapter 3, Removing the Main Control Board from the Mounting Plate
8	PRECHARGE	Precharge Board	—	Chapter 3, Removing the Precharge Board
9	SCR1	Input Rectifier	Heat Sink	Chapter 5, Input Rectifier SCR1
10	FAN	Fan	Main Chassis	Chapter 5, Fan
11	GND SENSE	Ground Sense CT	—	Chapter 5, Ground Sense CT
12	L1	DC Bus Inductor	Main Chassis	Chapter 5, DC Bus Inductor L1
13	C1-C6	Bus Capacitors	Main Chassis	Chapter 5, Bus Capacitors

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**Schematics — 20 – 60 HP 1336 IMPACT
Drives**



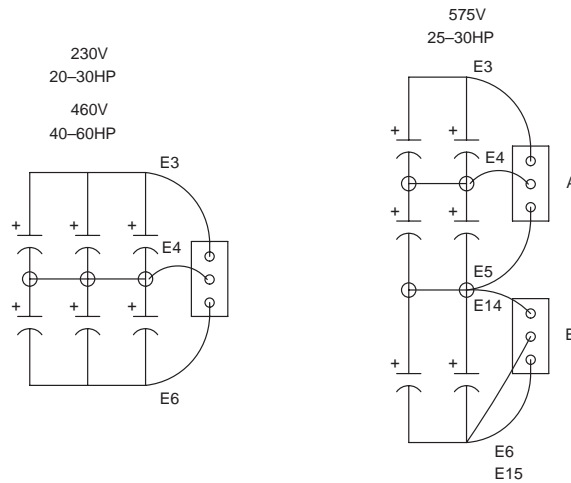
Schematic Diagram
 Stand Alone Unit
 Bulletin 1336 IMPACT
 200-240 Volt: 15-22 kW (20-30 HP)
 380-480 Volt: 30-44 kW (40-60 HP)
 500-600 Volt: 18.5-44 kW (25-60 HP)

AB0734A

TABLE 1 – FUSES

	DC FUSE	LINE FUSE
	INVERTER	(AC)
	F1	FR,FS,FT
HP RATING	A70Q TYPE	TYPE JJ
230VAC		
20	100A,700V	100A
25	125A,700V	100A
30	125A,700V	100A
380/460VAC		
40CT 50VT	100A,700V	90A
50CT 60VT	125A,700V	100A
60 460V ONLY	125A,700V	100A
575VAC		
25	50A,700V	40A
30	60A,700V	50A
40	70A,700V	60A
50	90A,700V	80A
60	100A,700V	90A

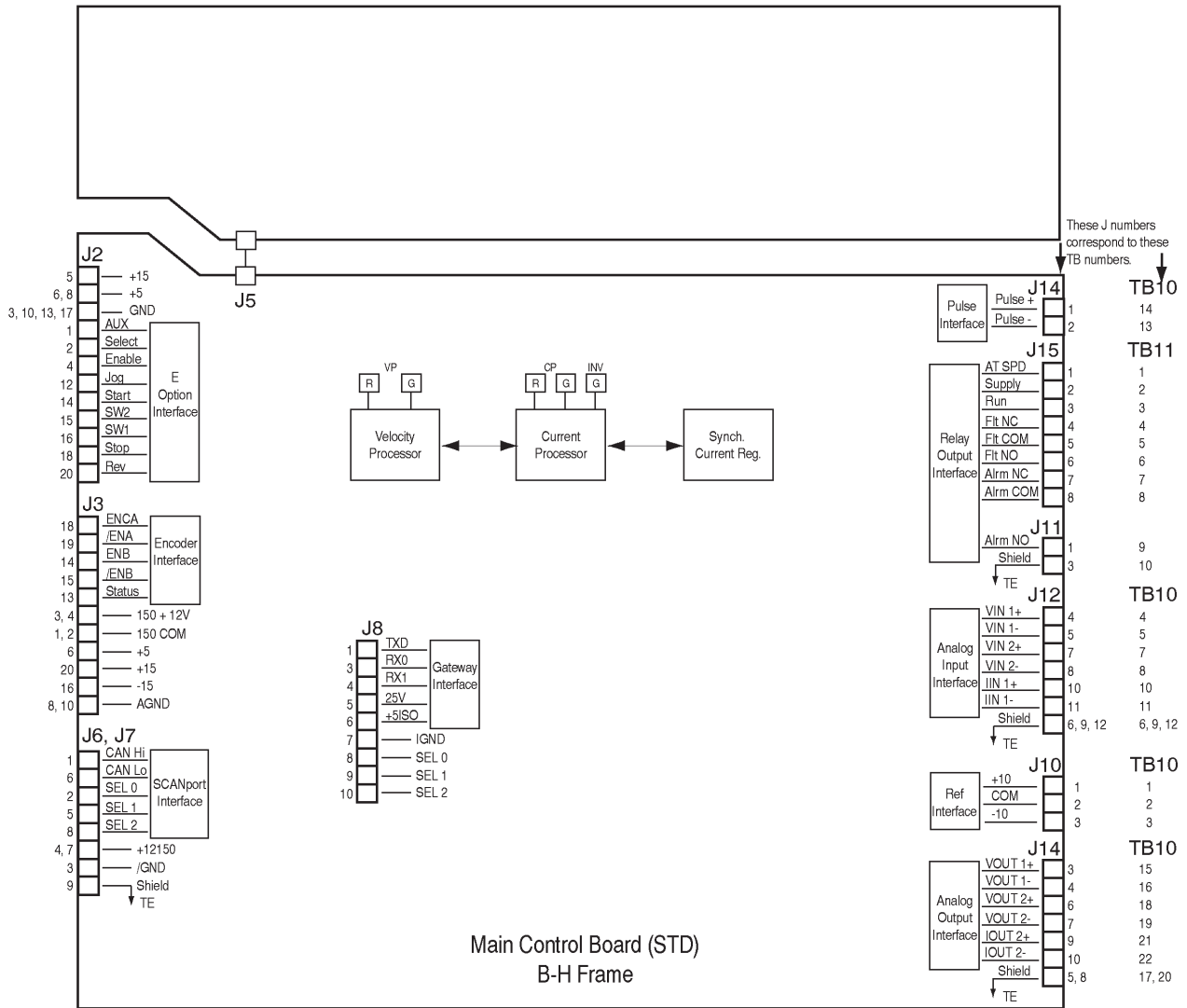
CAP BANK DETAILS



Schematic Diagram
 Stand Alone Unit
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Main Control Board



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